### **Components of Imaging at Low Frequencies: Status & Challenges**

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### **Telescope sensitivity**

Noise limit for imaging with interferometric radio telescopes

Noise 
$$\propto \frac{T_{sys}}{A_{eff}\sqrt{\Delta v \Delta T}}$$

• Sensitivity improvements achieved by

 $\Delta v$ : Wide band receivers: >60% fractional bandwidth

 $\Delta T$ : Long integration times: many hours -- months

A<sub>eff</sub>: More antennas: 30 -- many 100s

Long baselines: To beat confusion limit



## Sky at low frequencies: No. of sources





- PSF side-lobe at 1% level  $\rightarrow$  deconvolve sources >100µJy for 1µJy/beam RMS
- $10^{4-5}$  sources per deg<sup>2</sup> >10µJy @1.4GHz
  - Source size distribution important at resolution <  $\sim$ 2"
- Implications for imaging
  - 1. Wide-field imaging
  - HDR imaging: few X 100 mJy 1 Jy source ~few sq. deg.
  - Deconvolution of crowded fields (same problem as deconvolution of extended emission)

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## Sky at low frequencies: Confusion limit



- $\sigma_{\text{confusion}} \propto (\nu^{-2.7}/\text{B}_{\text{max}}^2)$ :  $B_{\text{max}} \sim 100 \text{ Km at 200MHz for } \sigma_{\text{confusion}} \sim 1\mu \text{Jy/beam}$
- Implications for imaging
  - 1. Long baselines:  $B_{max} > 2-3$  Km & DR >  $10^4$
  - 2. Wide-field effects: W-term, PB effects, ionospheric effects
  - Larger data volume



Wide-field, wide-band, high resolution, HDR imaging using large data volumes is a natural consequence of low frequency and high sensitivity





- EVLA @L-Band • BW=600 MHz
  - (1.2 1.8 GHz)
- Algorithmic Challenge:
  - Time-varying direction-dependent gains
  - Wide-band effects
  - Extended emission with superimposed compact emission
  - Full Stokes + Mosaicking

### Wide-band implies Wide-field imaging



## Imaging challenges

- Challenges in imaging at low frequencies
  - 1. Wide-field imaging
    - Account for Direction Dependent (DD) effects PB: Time, frequency and poln. dependence W-term
  - 2. Wide-band imaging
    - All of the above plus...
    - …frequency dependence of the sky brightness

1. HPC: Data volume proportional to  $N^2_{ant} \overline{N_{chan}}$ 

- 1. Sky brightness stronger and complex: Multi-Scale deconvolution
- 2. Ionospheric effects

Requires DD solvers: An algorithmic & computing challenge in itself



### **Direction Dependent (DD) Effects**

• DI Calibrated ME



- Fastest varying term on the RHS determines the averaging scale (time and frequency)
- Removing the effects of the DD terms cannot be separated from imaging
- Imaging equation:

$$I_{continuum}^{Dirty} = \int \int PSF(v, t) * \left[ PB(v, t) \times I^{True} \right] dv dt$$

## **Direction Dependent (DD) Effects**

• DI Calibrated ME



- Standard Imaging assumes:
  - PB is independent of time, frequency and polarization
  - Sky brightness is independent of frequency
  - Geometry is 2D
- Lets look at the DD-term one at a time (the terms marked in white in the equation above)



### Time dependent terms

- Antenna PB (*The*  $P_{ii}(s, v, t)$ )
  - Time dependence
  - Rotation of PB with PA leads to time-varying DD gains







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### **Polarization dependent terms**

- Antenna PB (*The*  $P_{ii}(s, v, t)$ )
  - Polarization dependence
  - Off-axis polarization due to antenna optics
  - Time variation due to PB rotation with PA



Contours: Stokes-I Colours: Stokes-V PB<sub>RR</sub> - PB<sub>LL</sub>



### Instrumental frequency dependence

- Continuum imaging  $I^{continuum} = \int P_{ij}(s, v, t) I(s, v) dv$
- Antenna PB (*The*  $P_{ii}(s, v, t)$ )
  - Frequency dependence
  - First order: scaling with frequency
     by 2x across the EVLA band





# All PB effects together: Time,





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### Sky frequency dependence





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### Non co-planar baselines: W-Term

• Imaging



- The geometric term (non co-planar baselines)
  - Transform is no more 2D Fourier Transform



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## **MT-MFS: Freq. dependence of the sky**

- Model the frequency dependence of the sky brightness as a polynomial in frequency
- Solve for the coefficients as a joint deconvolution problem



Rau et al., A&A, 2011



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### **DD Corrections: Projection Algorithms**

$$V_{ij}^{DI-Cal}(\nu) = W_{ij} \int P_{ij}(s, \nu, t) I^{True}(s, \nu) e^{\iota s.b_{ij}} ds$$
$$V_{ij}^{DI-Cal}(\nu) = A_{ij}(\nu, t) * V^{True}(\nu, t)$$

• Can we find an operator X which when applied to the above equation, projects-out the undesirable effects of A?

$$X_{ij} V_{ij}^{DI-Cal} = X_{ij} A_{ij} V^{True}$$

such that  $X_{ij} A_{ij} = \mathbf{1}$ 

• Then

$$F X_{ij} V_{ij}^{DI-Cal} = F V^{True} = I^{True}$$



Understand the Physics of the problem; use mathematical techniques to find a solution

### **PB Polarization Effects**

#### Stokes-V Images



• L-Band VLA imaging • DR ~  $10^4$ 

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### Wide-Band AW-Projection

- Correct for PB effects + W-term
  - Polarization: Squint + in-beam polarization
  - Time variability: Rotation with Parallactic Angle



### Wide-Band AW-Projection

$$A_{ij}(\nu_{*})$$
 where  $\nu_{*} = \sqrt{2 \nu_{ref}^{2} - \nu^{2}}$ 



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### Wide-Band AW-Projection + MT-MFS

- Intensity weight Spectral Index Map
- Wide-field Spectral Index maps comes out in the wash correctly



### **WB AW-Projection + MT-MFS**

- Simultaneously account for the PB effects and frequency dependence of the sky
  - PB effects corrected by WB A-Projection

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 PB-corrected image used in MT-MFS for model the frequency dependence of the sky brightness



### Status-1

- W-Term correction: Dominant DD term at low frequencies
  - Facted-imaging, W-Projection, W-Stacking
- Extended emission
  - MS-Clean, Asp-Clean, various variants
- Frequency dependence of the sky brightness
  - MS-MFS, MT-MFS
- PB corrections
  - A-Projection: Time and polarization dependence
  - WB A-Projection: Also frequency dependence
- W-Term + WB A-Projection + MT-MFS
  - Simultaneously account for instrumental and sky terms
- Wide-band Mosaic





## Wide-band Mosaic Imaging + SD



- Simultaneous corrections for instrumental effects+ Frequency Dependence of the Sky
- WB AW-Projection + MS-MFS + Mosaic
- Wide-band 100-pointing mosaic
- EVLA + GBT Feathering (existing algorithm)
- In progress:

   Mosaic spectral Index mapping
- Parallel execution / Optimization /
- Numerical tests

### **Status-2**

### Full-polarization imaging

- Extend PB correction to full polarization (student PhD project)
- RM Synthesis at the sensitivity and band-width now available

- Ionospheric phase corrections
  - Corrections: Can be included as a term in A-Projection for correction during imaging (Tasse et al., A&A)
  - Ionospheric phase screen solvers
    - » SPAM
    - » Other similar "peeling" based solvers
    - » More generic solvers

### • Deployment on HPC platforms

- Cluster computing
- Multi-threaded CPUs, GP-GPUs



### **Computing Cost**

- Imaging + deconvolution accounts for ~70% of the computing cost in an "typical" end-to-end processing
- Computing Scaling
  - <u>– Computing costs:  $N_{support}^2 + N_{vis}$ </u>: Dominated by Projection
  - Memory footprint:  $N^2_{Scales} + N^2_{Terms}$  :  $\Box$
- : Dominated by Projection : Dominated by MT-MFS
- Imaging : Embarrassingly parallel
  - Scatter-Gather Paradigm on the Cluster scale
- Optimal utilization of the computing multi-core CPUs is harder
  - Multiple process per node: Limited by total memory footprint
  - Single multi-threaded process: Algorithmically challenging



### Algorithm Design: 3D Parameter space



### **Algorithm design**

- Move towards algorithms with higher compute-to-I/O ratio
- Reduce memory foot print
  - remain inside the Green Box



### Challenges

#### Aperture Array PB (LOFAR, MWA, LWA) vs Antenna PB

#### Antenna-to-antenna variations



Simulations for LWA @50MHz (Masaya Kuniyoshi (LWA/NRAO))



Model for EVLA PB at L-Band



### Challenges

- Algorithms
  - Scientific commissioning (in progress)
    - » WB-AWP + MT-MFS + Mosaic
  - All of the above + full Polarization (starting Jan. 2014)
  - Wide-band RM Synthesis
  - DD Solvers: Ionospheric screen, Pointing Errors, ...

- Computing
  - Use of (massively) parallel hardware
    - » Multi-core CPUs, GP-GPUs
  - Memory footprint
  - Data I/O
    - » Algorithms are fundamentally iterative



## Challenges

- Current algorithms
  - Performance
  - Efficiency
  - PB variations, Pointing errors, Shape
- Full-polarization treatment
  - 1 vs 2 vs 4x4 Mueller Matrix treatment
- Rate of convergence: Crucial for SKA-scale problems
  - Optimal algorithms, Optimal utilization
- SKA sensitivity  $\rightarrow$  wider-field imaging, expose more error terms
  - Instrumental terms: Measure vs Model vs Solve
- We collect enormous amounts of data  $\rightarrow$  more information
  - Are we utilizing the available information optimally?
    - » In terms of algorithm design
    - » In terms of extracting astrophysical information



### Imaging with the EVLA @ L-Band



Wide-band mosaic+Single Dish (GBT) Working on Stokes-I + Sp.Ndx. Mapping -(Bhatnagar et al.)

Intensity-weighted Sp. Ndx. Map

Single pointing, narrow field, wide-band image (Owen, Rau)



### Challenges: Human resources

- Algorithm R&D is not yet main-stream astronomy

   Algorithm R&D is a service mind-set needs to break
- Data taken under many proposals, but science not achievable without algorithm commissioning work
- Many telescopes in construction, with ambitious scientific and time-line goals around the Globe
- Appeal to the young-guns
  - Think of ambitious scientific goals, do not be shy of technical work (telescope debugging, algorithms R&D, commissioning)
  - It's great fun. Mind-liberating, scientific-horizon widening
  - "...it does not work" kind of gripes are insufficient
- Appeal to the seniors
  - Policy changes: Encourage & support multidisciplinary research at least at the observatories!

