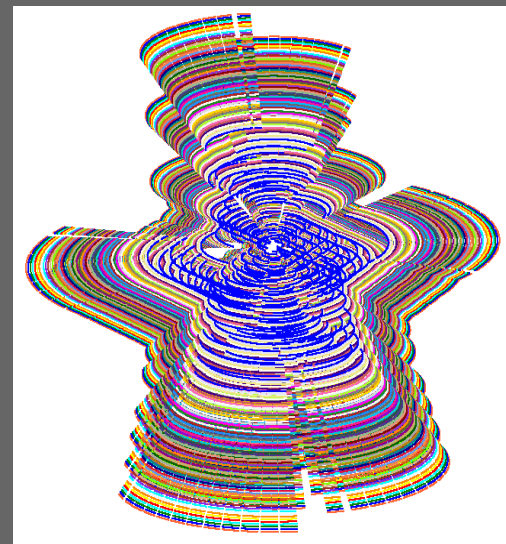
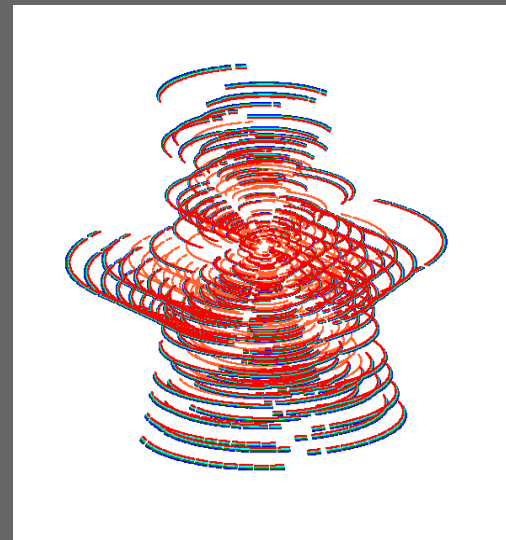


Wide-band wide-field imaging with the EVLA – II

Goal : Make images at the wide-band sensitivity level

Outline :

- Bandwidth and bandwidth-ratio
- Frequency-dependent sky and instrument
- Methods to reconstruct intensity and spectra
- Dynamic-range and accuracy
- Wide-field effects of wide bandwidths
- Wide-band self-calibration
- RFI identification and flagging



Bandwidth and bandwidth-ratio

Broad-band receivers => higher 'instantaneous' continuum sensitivity

$$\sigma_{\text{continuum}} = \frac{\sigma_{\delta\nu}}{\sqrt{(\nu_{\text{max}} - \nu_{\text{min}}) / \delta\nu}} = \frac{\sigma_{\text{chan}}}{\sqrt{N_{\text{chan}}}}$$

Instantaneous bandwidth $\nu_{\text{max}} - \nu_{\text{min}}$

VLA = 50 MHz

EVLA = 1 GHz at L-Band, 4 GHz at C-band, upto 8 GHz at higher bands.
(x 4) (x 9) (x 12)

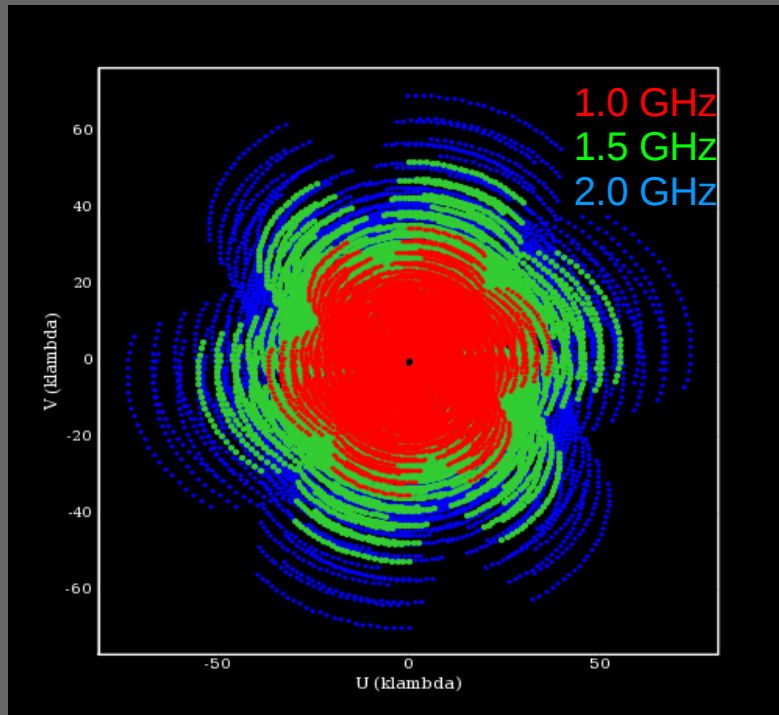
Currently, maximum bandwidth is 2 GHz => (x 6)

Bandwidth Ratio ($\nu_{\text{max}} : \nu_{\text{min}}$) or Fractional Bandwidth $\frac{\nu_{\text{max}} - \nu_{\text{min}}}{\nu_{\text{mid}}}$

Higher BWR (2:1 at L,S, C bands) => Stronger frequency-dependent effects within the band (sky and instrument)

Frequency-dependence of the instrument and sky

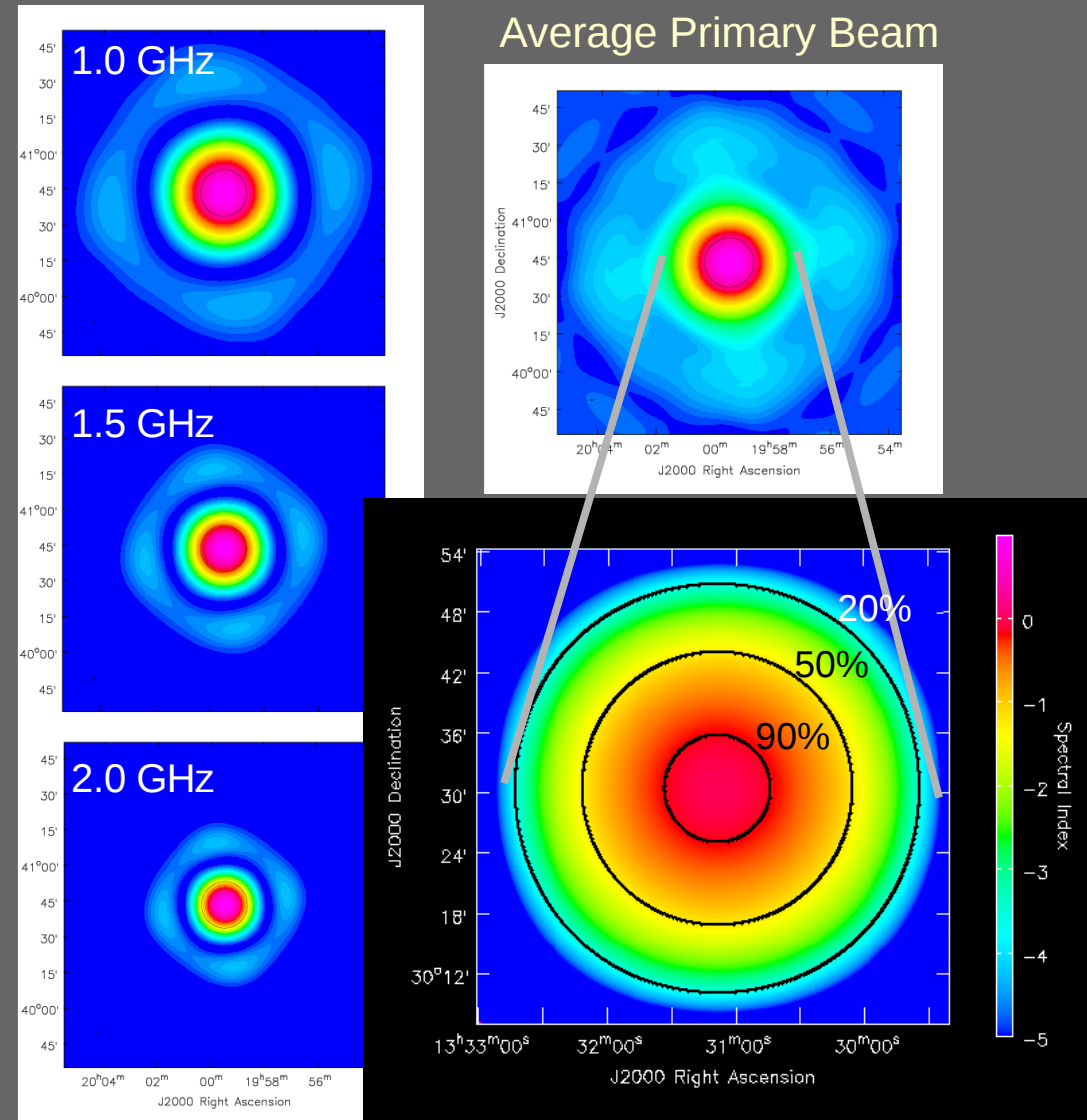
Multi-Frequency UV-coverage



- UV-coverage (angular resolution)
- Primary-beam (field-of-view)
- Sky-brightness distribution

..... all change with frequency

Multi-Frequency Primary Beams



'Spectral Index' of PB

Wideband Imaging Options

(1) Make images for each channel / SPW separately.

- Signal-to-noise ratio : one SPW
- Angular resolution varies with SPW (smooth to lowest)
- Imaging fidelity may change across SPWs

When will this suffice ?

- Sources have sufficient SNR in a single channel / SPW
- UV-coverage per SPW gives un-ambiguous reconstructions
- You don't need the highest-possible angular resolution for spectra

(2) Combine all frequencies during imaging
(MFS : multi-frequency synthesis)

- Signal-to-noise ratio : all SPWs
- Angular resolution is given by the highest frequency
- Imaging fidelity is given by the combined uv-coverage

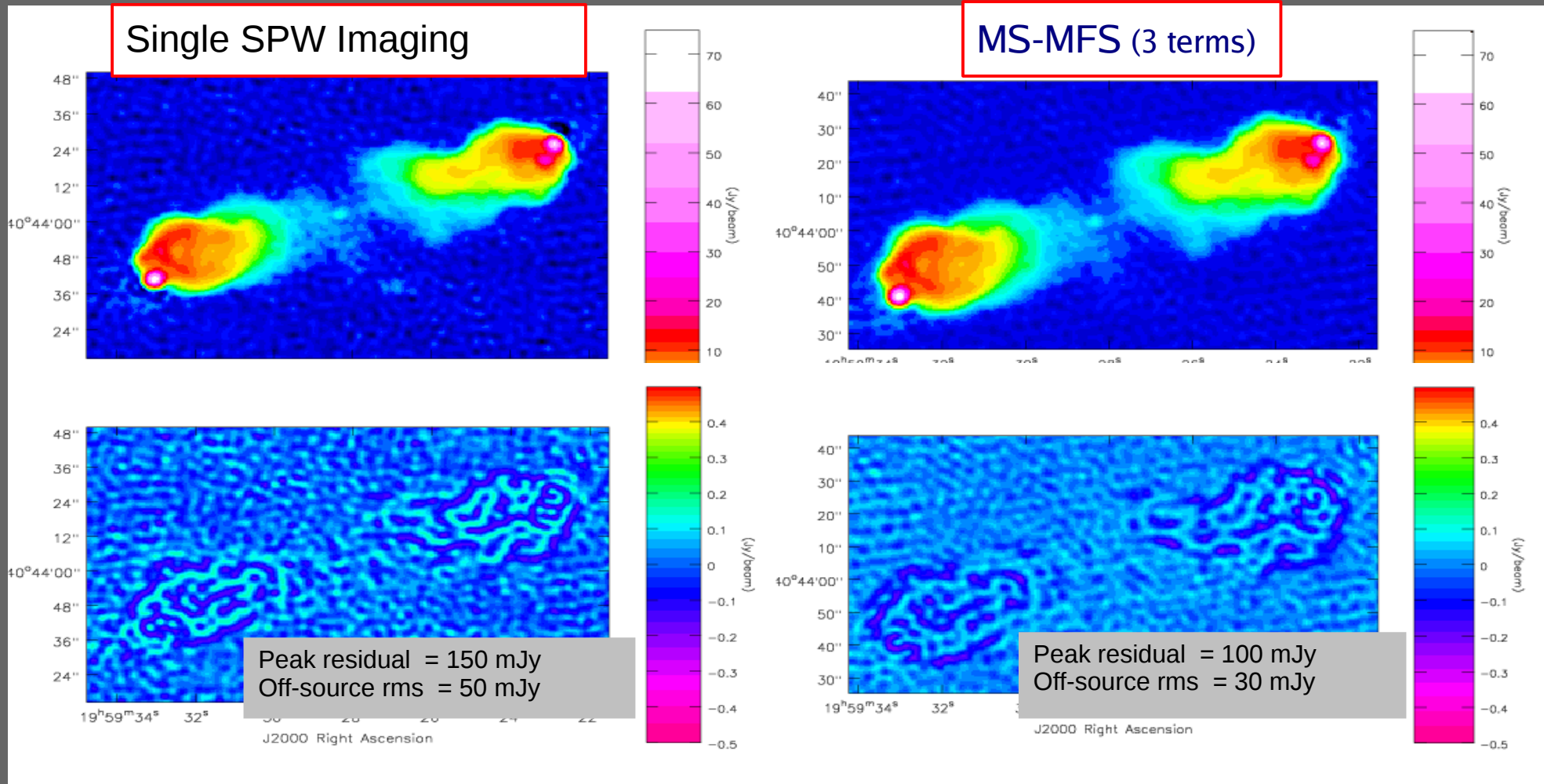
When do you need MFS ?

- Single channel / SPW sensitivity is too low
- Complicated fields where single-SPW uv-coverage gives non-unique solutions
- Need high angular-resolution images (intensity and spectral index)

(But, need to model / reconstruct spectra too...)

Comparison of single-SPW imaging with MFS - Intensity

Data : 20 VLA snapshots at 9 frequencies across L-band + wide-band self-calibration



=> Similar results

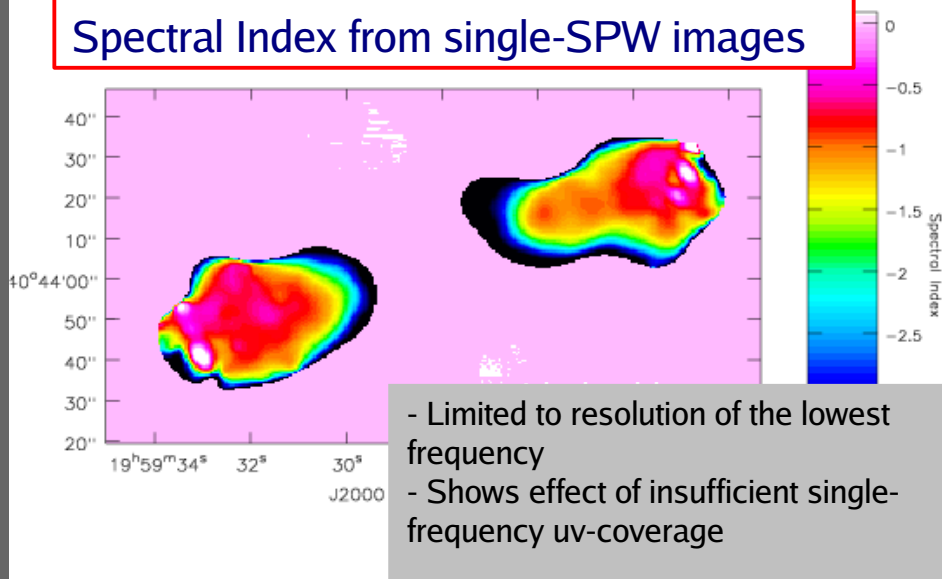
- both methods reconstruct plausible intensity images.
- both have similar residual errors due to deconvolution.

(MS-MFS : Multi-Scale Multi-Frequency Synthesis : models intensity and spectrum (Taylor polynomial))

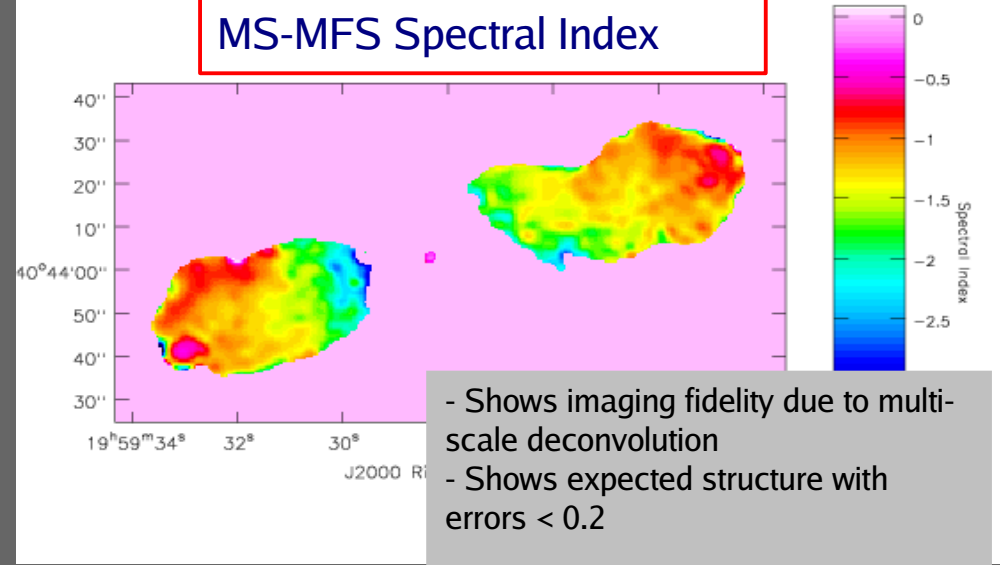
Comparison of single-SPW imaging with MFS – Spectral Index

Data : 20 VLA snapshots at 9 frequencies across L-band + wide-band self-calibration

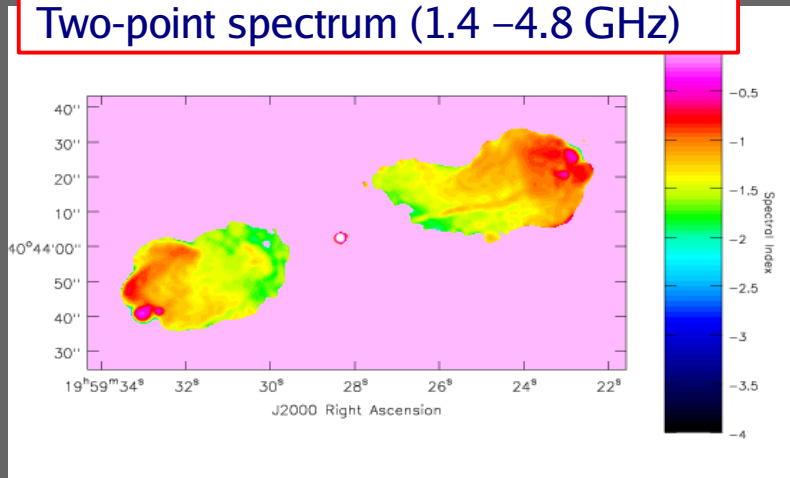
Spectral Index from single-SPW images



MS-MFS Spectral Index



Two-point spectrum (1.4 – 4.8 GHz)



C.Carilli et al, Ap.J. 1991.
(VLA A,B,C,D Array at L and C band)

=> It helps to use the combined uv-coverage and solve for sky spectra.

Can often extract more information from your data, compared to traditional methods.

“Multi-Scale Multi-Frequency Synthesis”

Multi-Scale MFS : as implemented in CASA

Sky Model : Collection of multi-scale flux components whose amplitudes follow a polynomial in frequency

$$I_{\nu}^{sky} = \sum_t I_t \left(\frac{\nu - \nu_0}{\nu_0} \right)^t \quad I_t = \sum_s [I_s^{shp} * I_{s,t}]$$

Image Reconstruction : Linear least squares + Deconvolution (2011A&A...532A..71R , arXiv:1106.2745)

User Parameters :

Imaging mode	: mode='mfs'
Number of Taylor-polynomial coeffs.	: nterms=2
Reference frequency	: reffreq = '1.5GHz'
Set of spatial scales (in units of pixels)	: multiscale=[0,6,10]

Data Products : Taylor-Coefficient images I_0, I_1, I_2, \dots

- Interpret in terms of a power-law : spectral index and curvature

$$I_0 = I_{\nu_0} \quad I_1 = I_{\nu_0} \alpha \quad I_2 = I_{\nu_0} \left(\frac{\alpha(\alpha-1)}{2} + \beta \right)$$

(Or, evaluate the spectral cube (for non power-law spectra))

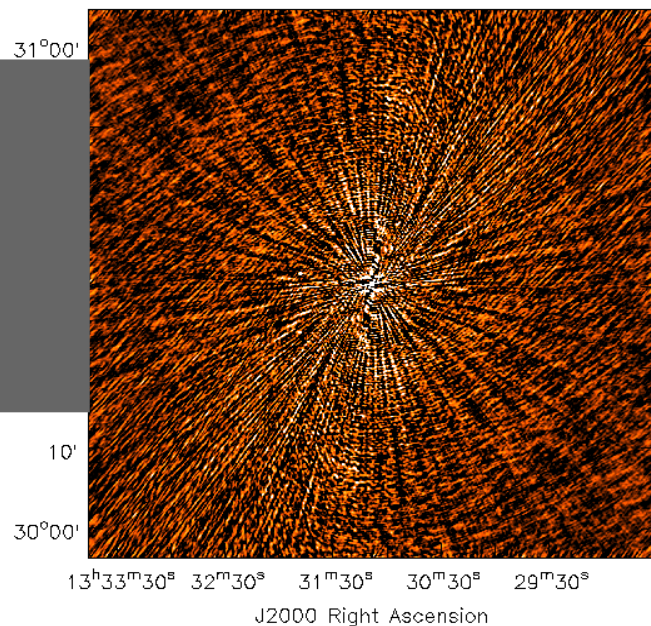
Dynamic Range (vs) NTERMS – 3C286 field (point sources)

($I=14.4$ Jy/bm, $\alpha = -0.47$, BW=1.1GHz at Lband)

NTERMS = 1

Rms :
9 mJy -- 1 mJy

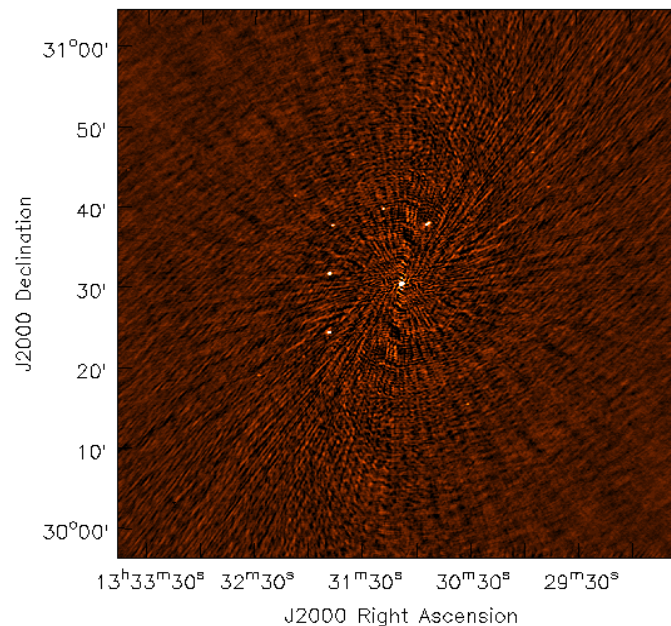
DR :
1600 -- 13000



NTERMS = 2

Rms :
1 mJy -- 0.2 mJy

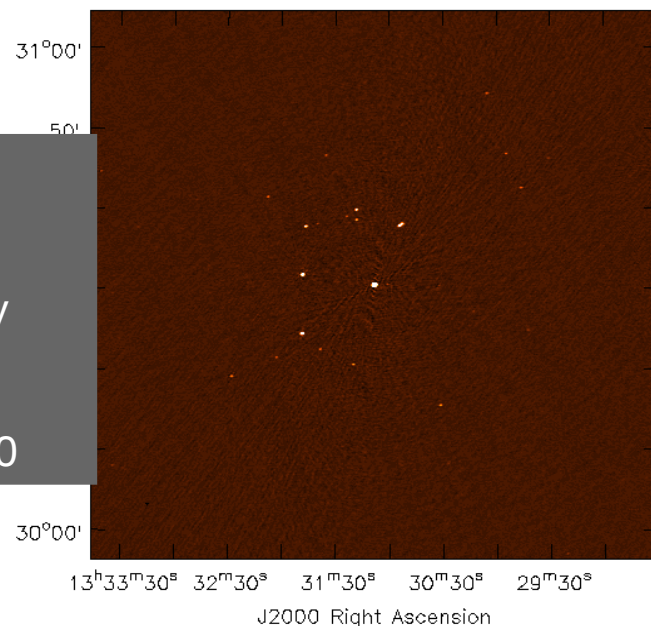
DR :
10,000 -- 17,000



NTERMS = 3

Rms :
0.2 mJy -- 85 uJy

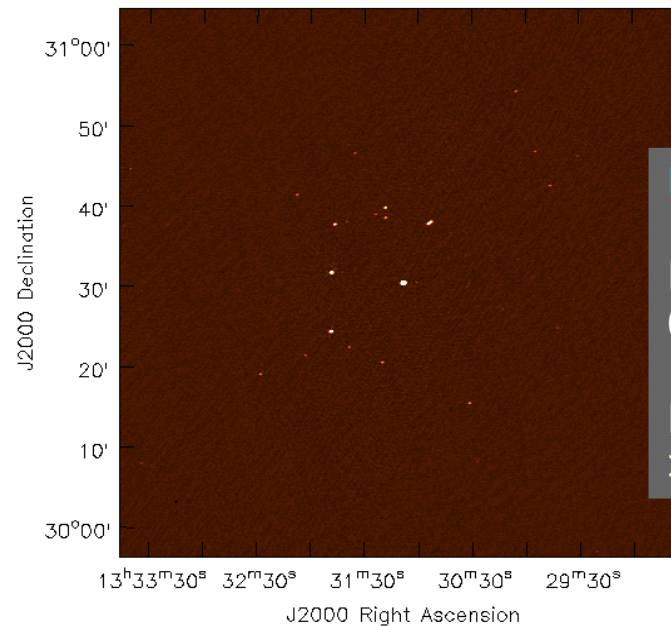
DR :
65,000 -- 170,000



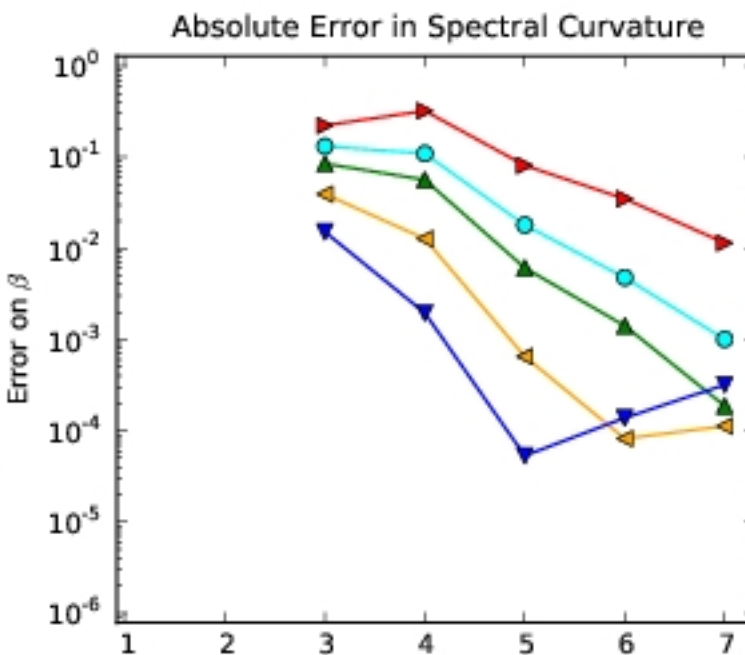
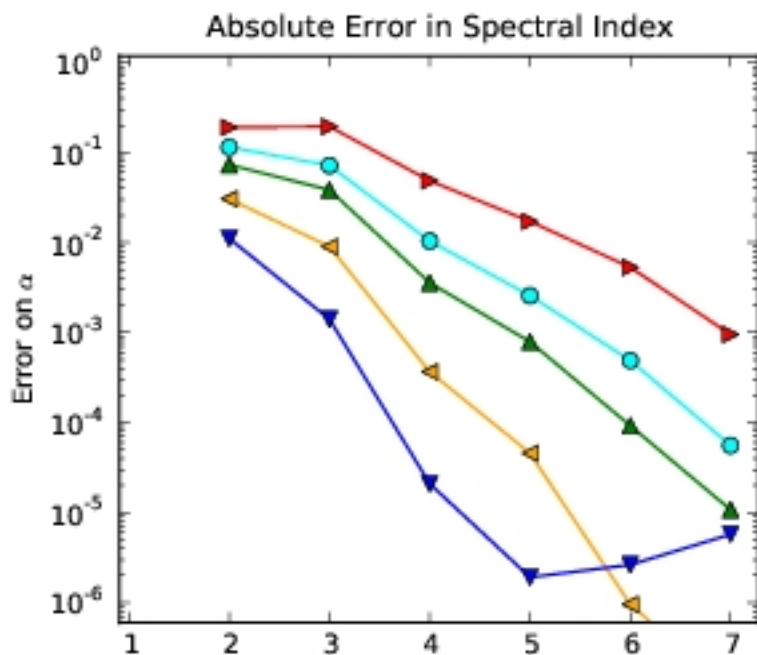
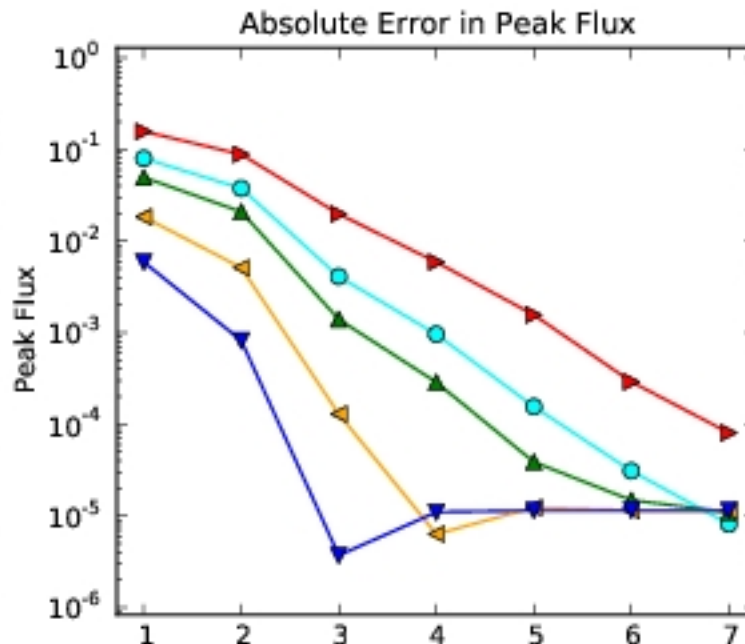
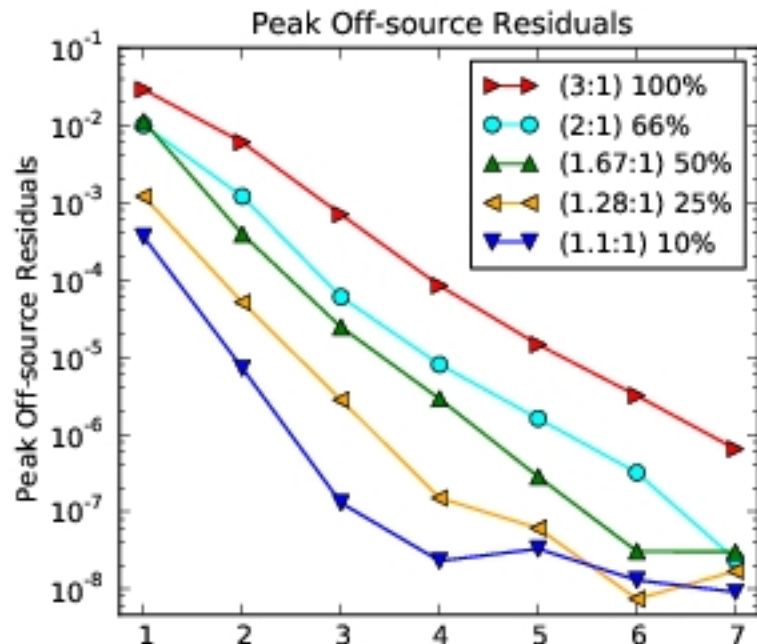
NTERMS = 4

Rms
0.14 mJy -- 80 uJy

DR :
>110,000 -- 180,000



Error estimates : Bandwidth-ratio vs 'nterms' (high SNR)



If spectra are ignored

=> larger BWR gives larger errors

If there is high SNR,

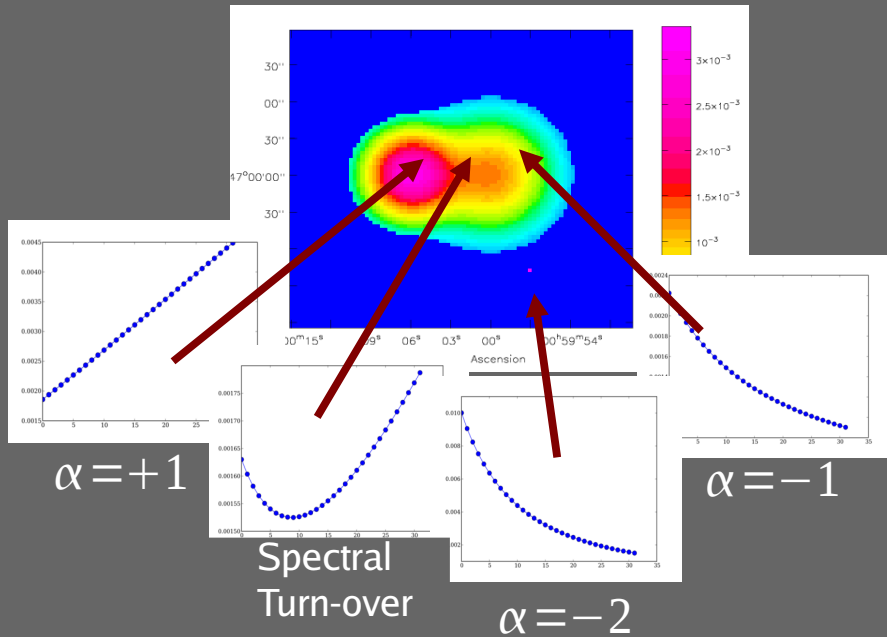
=> more terms gives smaller errors

Note : These plots are for one point-source at the phase center, with very high signal-to-noise levels.

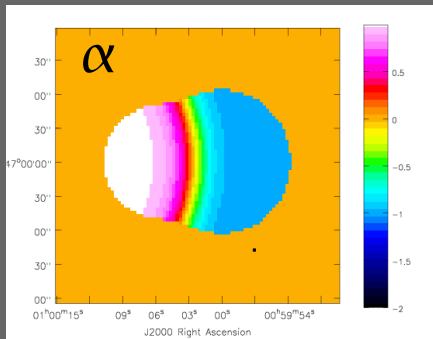
In practice, use $n_{\text{terms}} > 2$ only if there is high SNR (> 100), and if you can see spectral artifacts in the image with $n_{\text{terms}} = 2$

Multi-Scale vs Point-Source model for wideband imaging

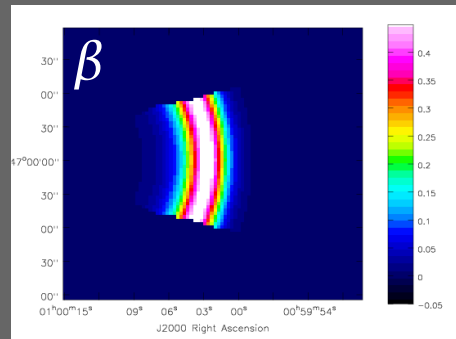
Intensity Image



Average Spectral Index

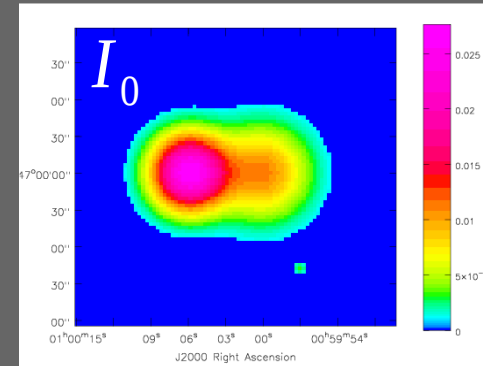


Gradient in Spectral Index

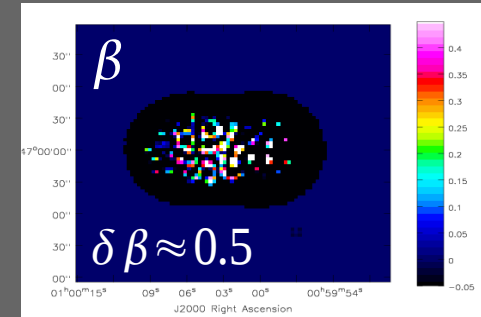
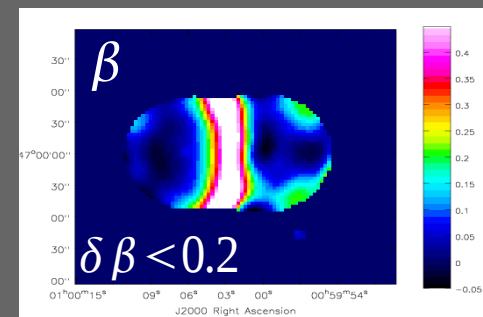
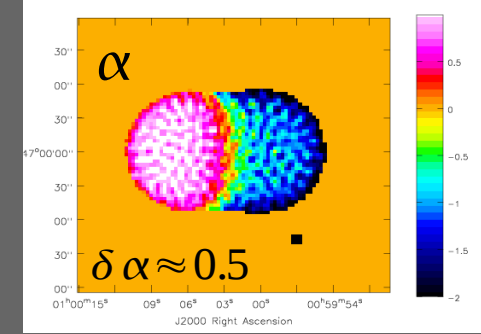
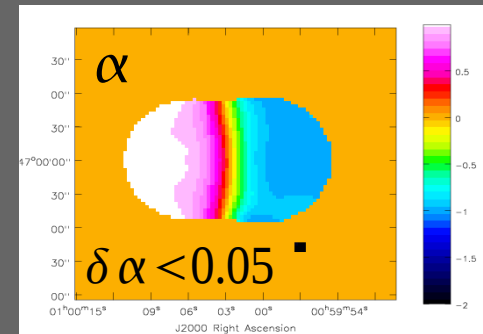
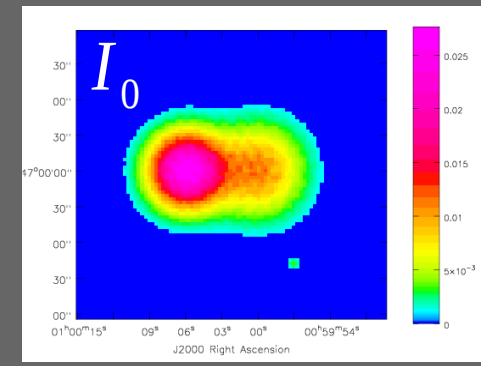


MFS
(4 terms)

multi-scale



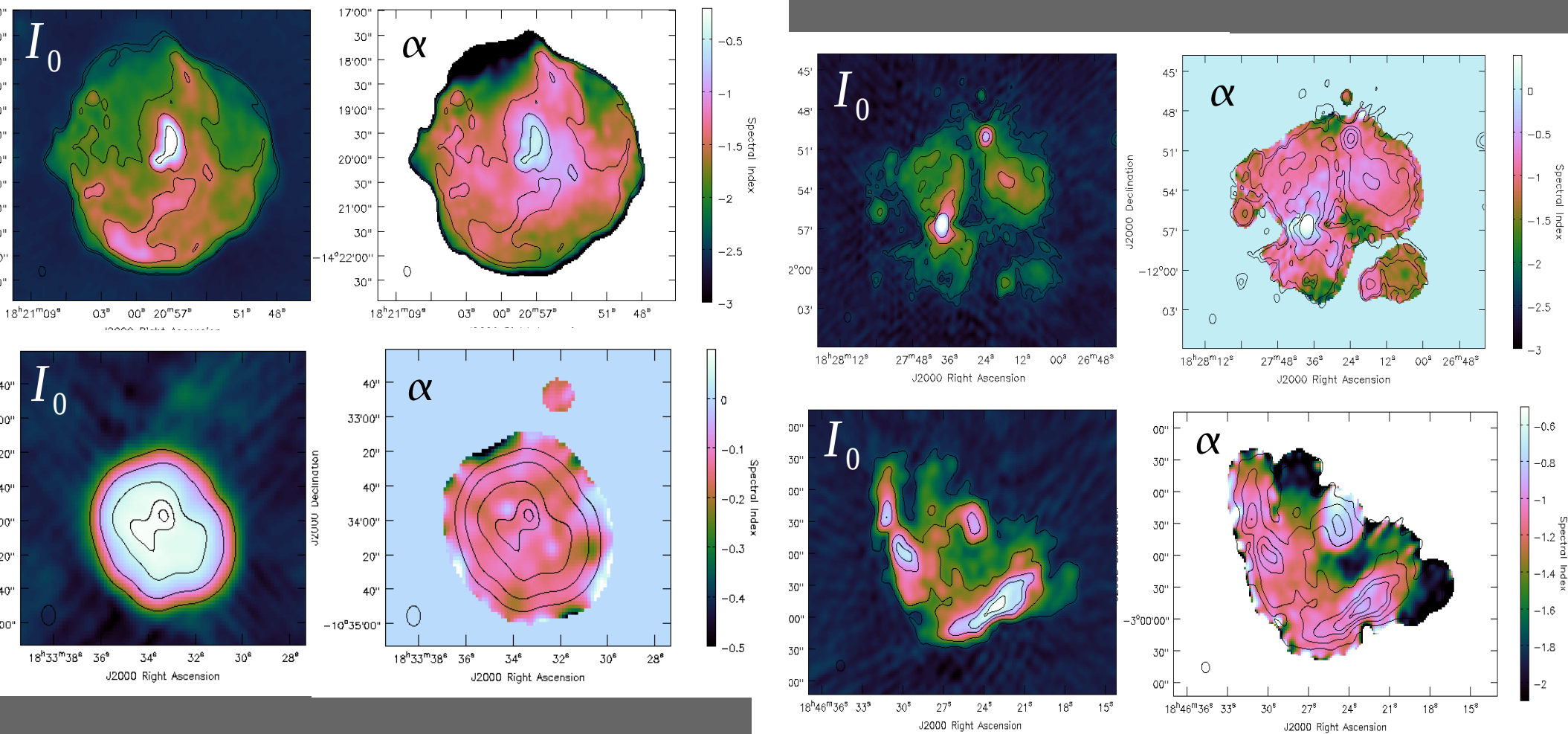
point-source



=> For extended emission,
 -> a multi-scale model gives better spectral index and curvature maps

Separating regions/sources based on spectral index structure

(2011ApJ...739L..20B , arXiv:1106.2796)



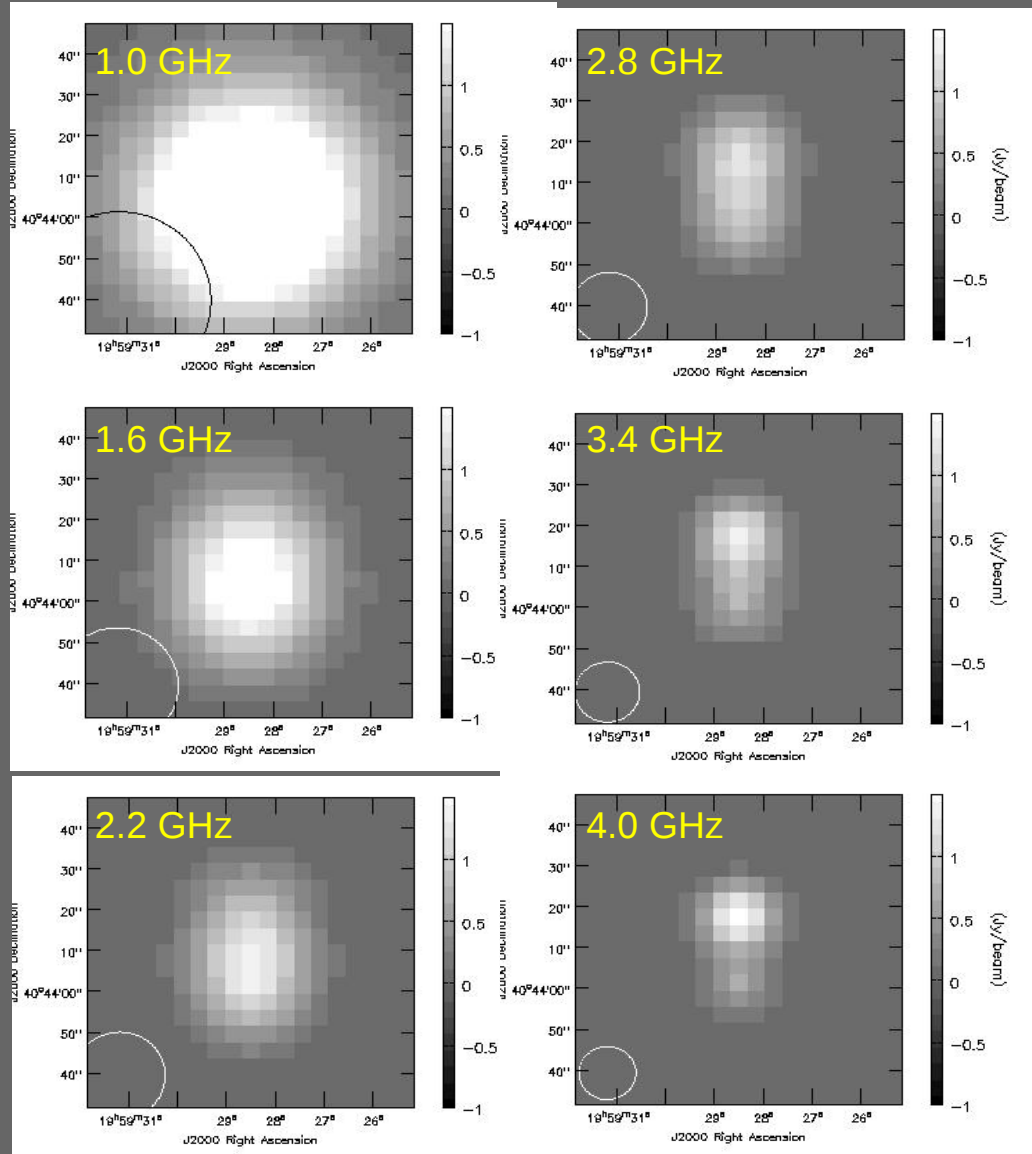
Initial results of a pilot survey (EVLA RSRO AB1345). These examples used $n_{\text{terms}}=2$, and about 5 scales.

=> Within L-band and C-band, can tell-apart regions by their spectral-index (± 0.2) if $\text{SNR} > 100$.

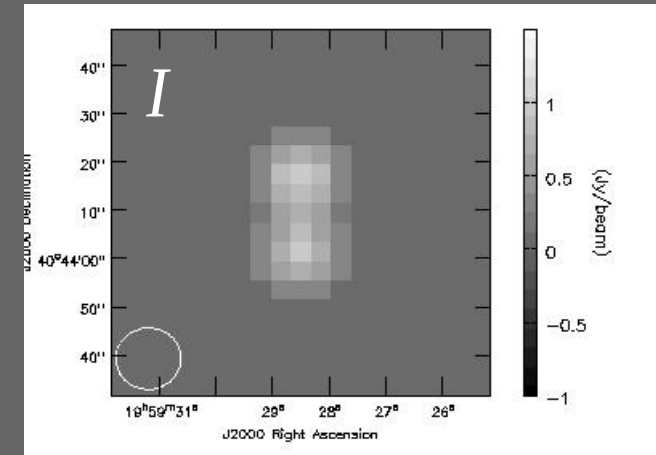
=> These images have a dynamic-range limit of few $\times 1000$

Small spatial-scales - moderately-resolved sources

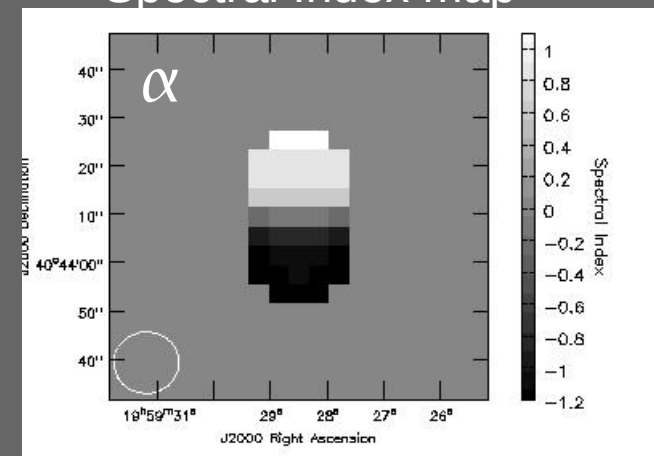
Can reconstruct the spectrum at the angular resolution of the highest frequency



Restored Intensity image

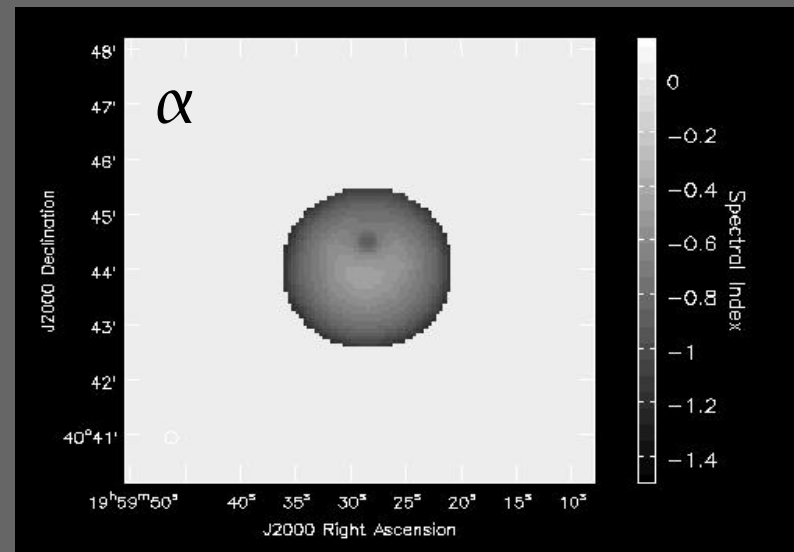
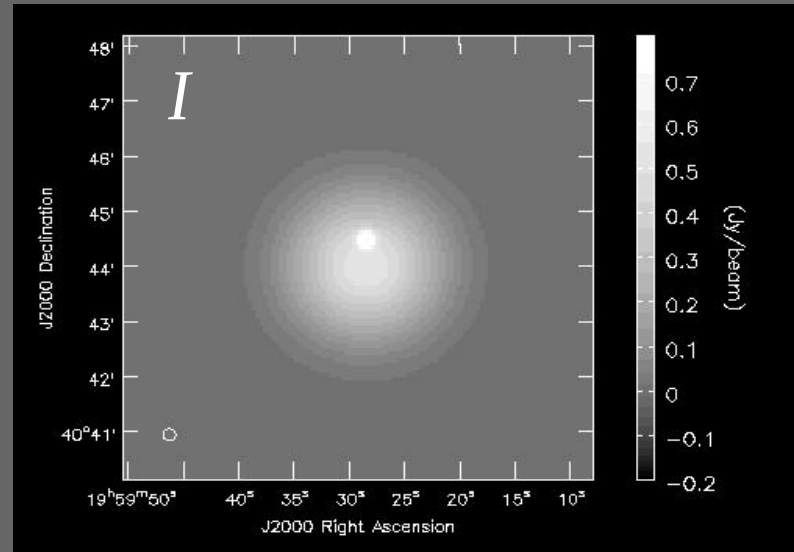
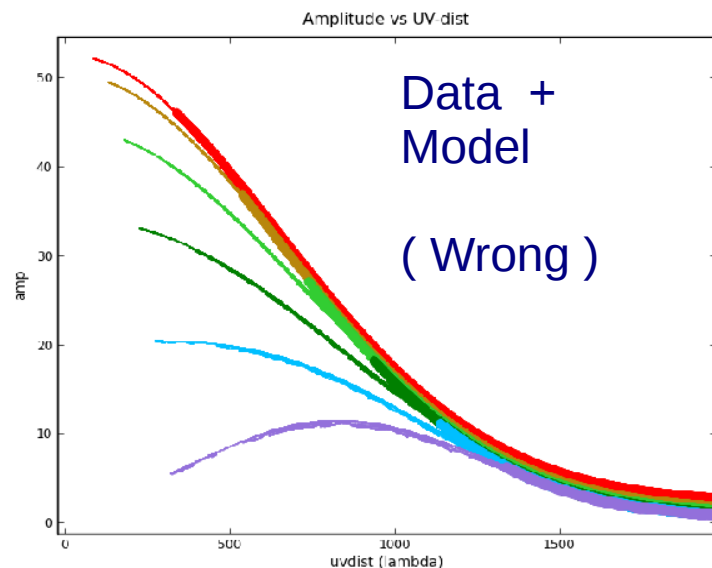
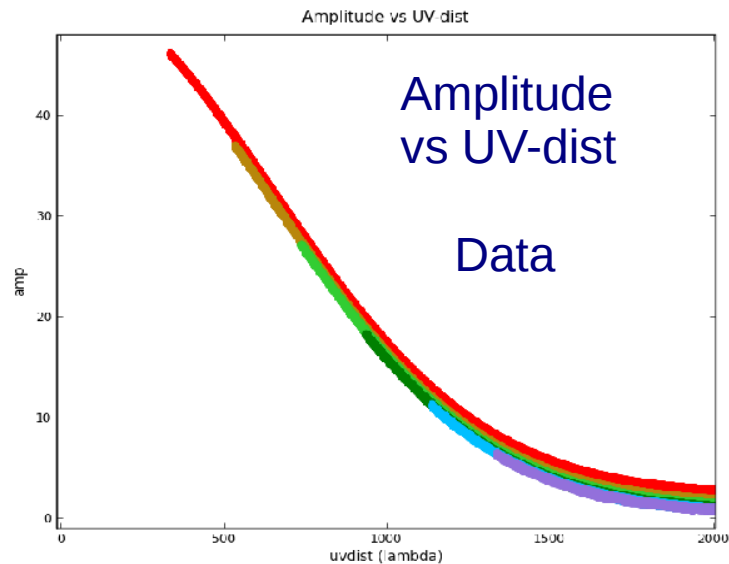


Spectral Index map



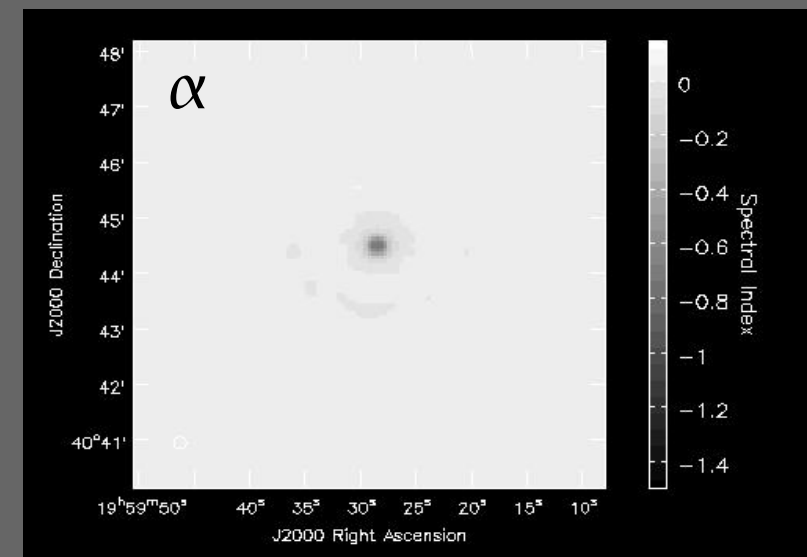
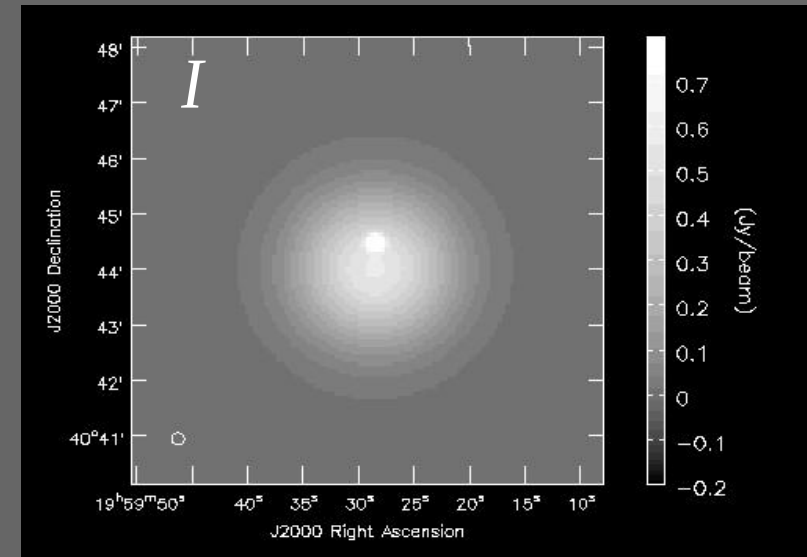
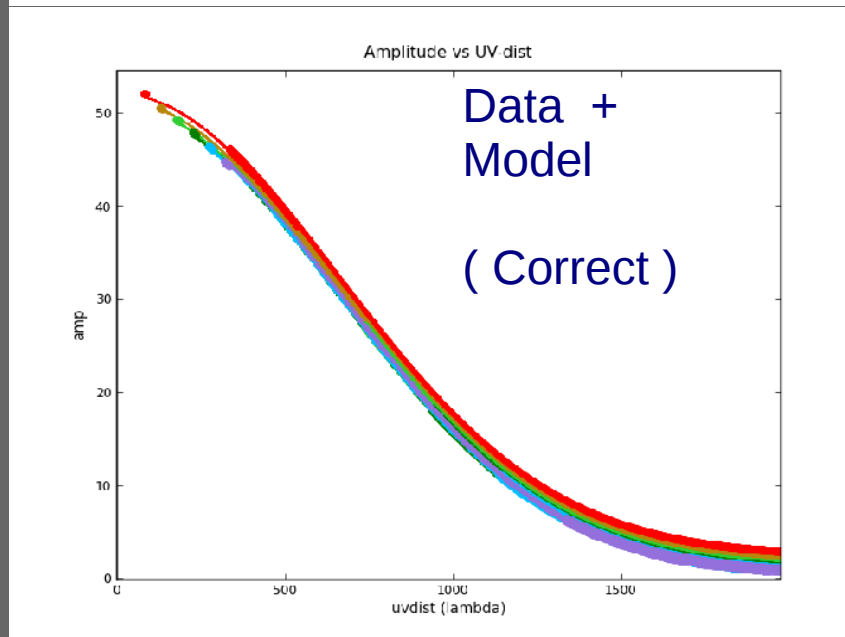
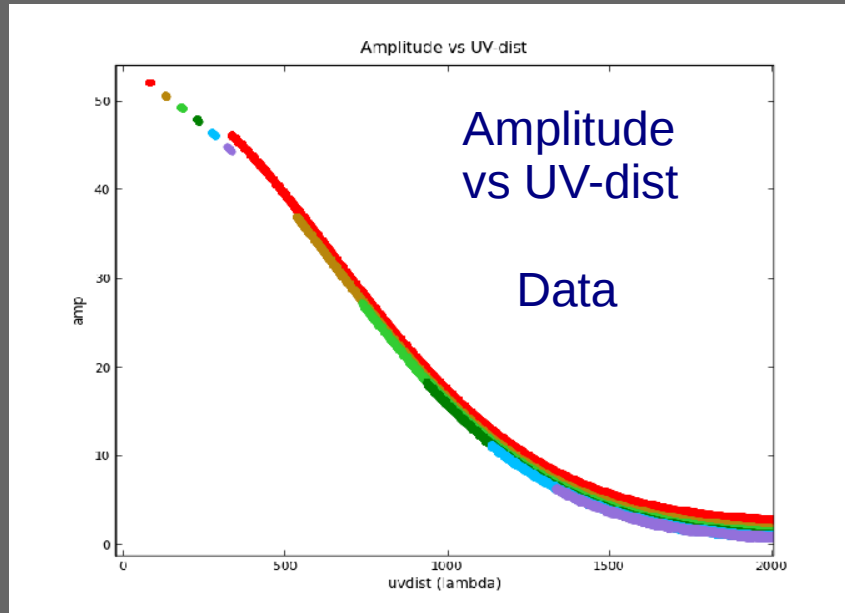
Very large spatial scales - without short-spacing data

The spectrum at the largest spatial scales is NOT constrained by the data



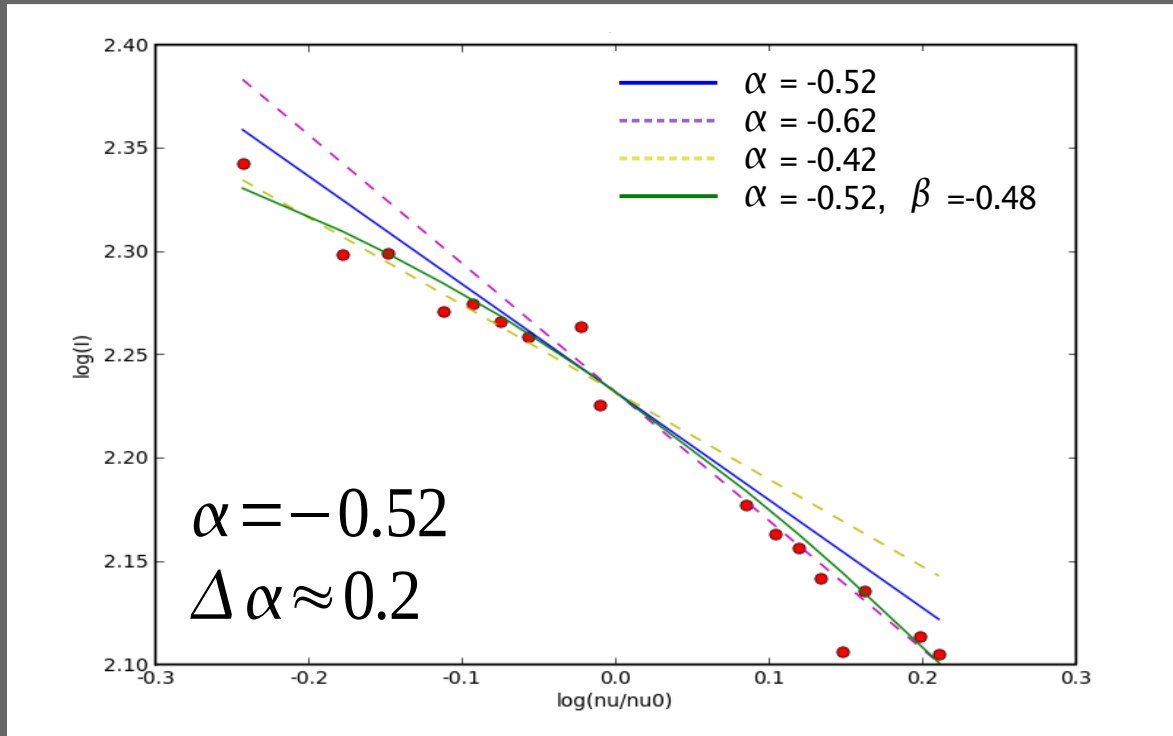
Very large spatial scales – with short-spacing data

External short-spacing constraints help (visibility data, or starting image model)



Spectral Curvature : VLA data : M87 1.1-1.8 GHz

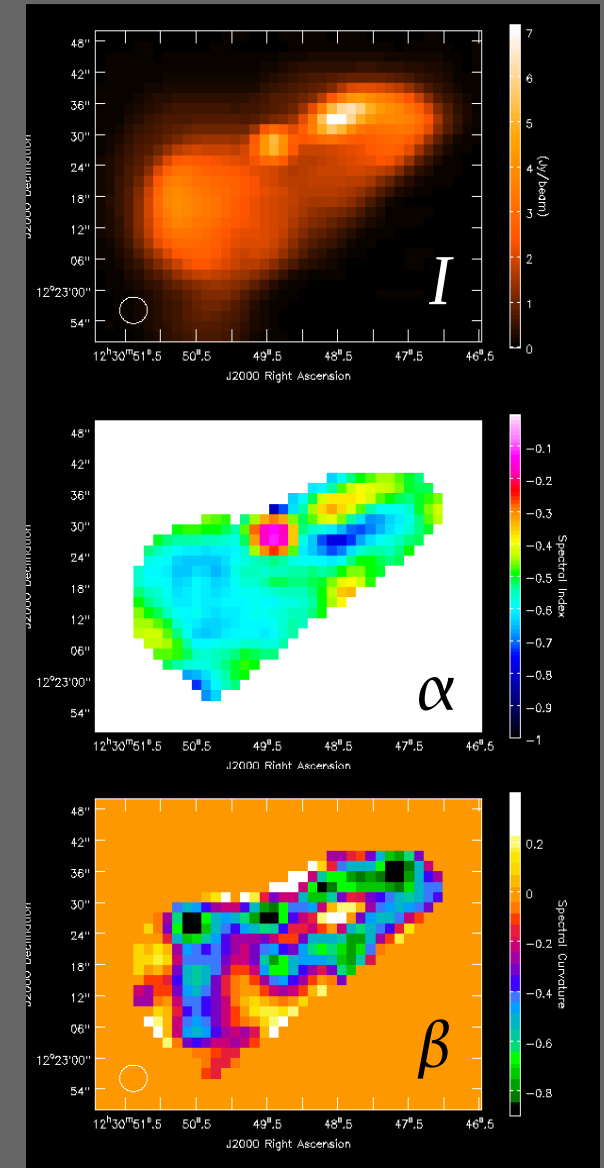
Data : 10 VLA snapshots at 16 frequencies across L-band



From existing P-band (327 MHz), L-band(1.42 GHz) and C-band (5.0 GHz) images of the core/jet

P-L spectral index : $-0.36 \sim -0.45$

L-C spectral index : $-0.5 \sim -0.7$

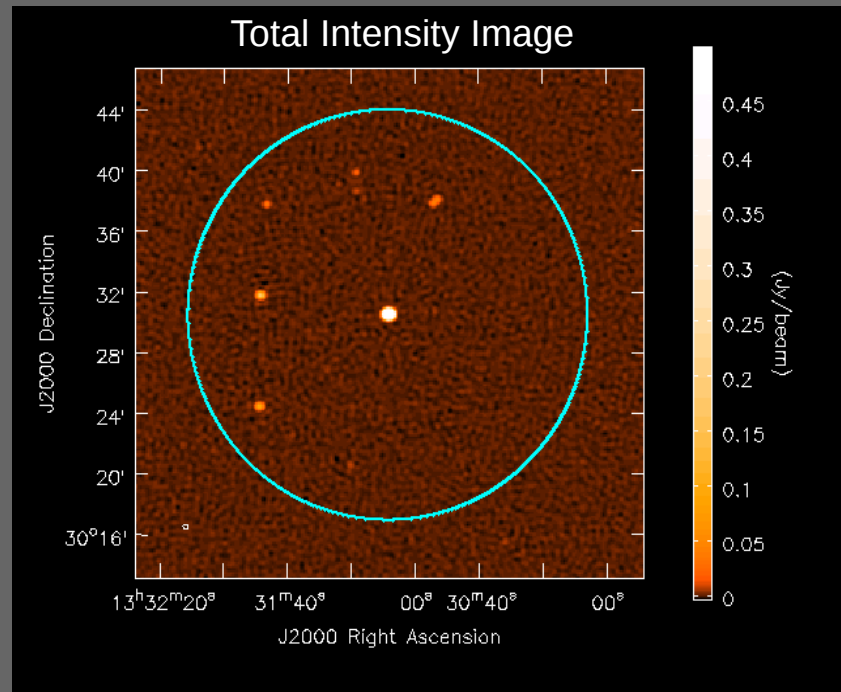


=> Need SNR > 100 to fit spectral index variation ~ 0.2 (at the 1-sigma level ...)

=> Be careful about interpreting β

Wide-Field issues : Wide-band Primary-Beam

3C286 field , C-config , L-band

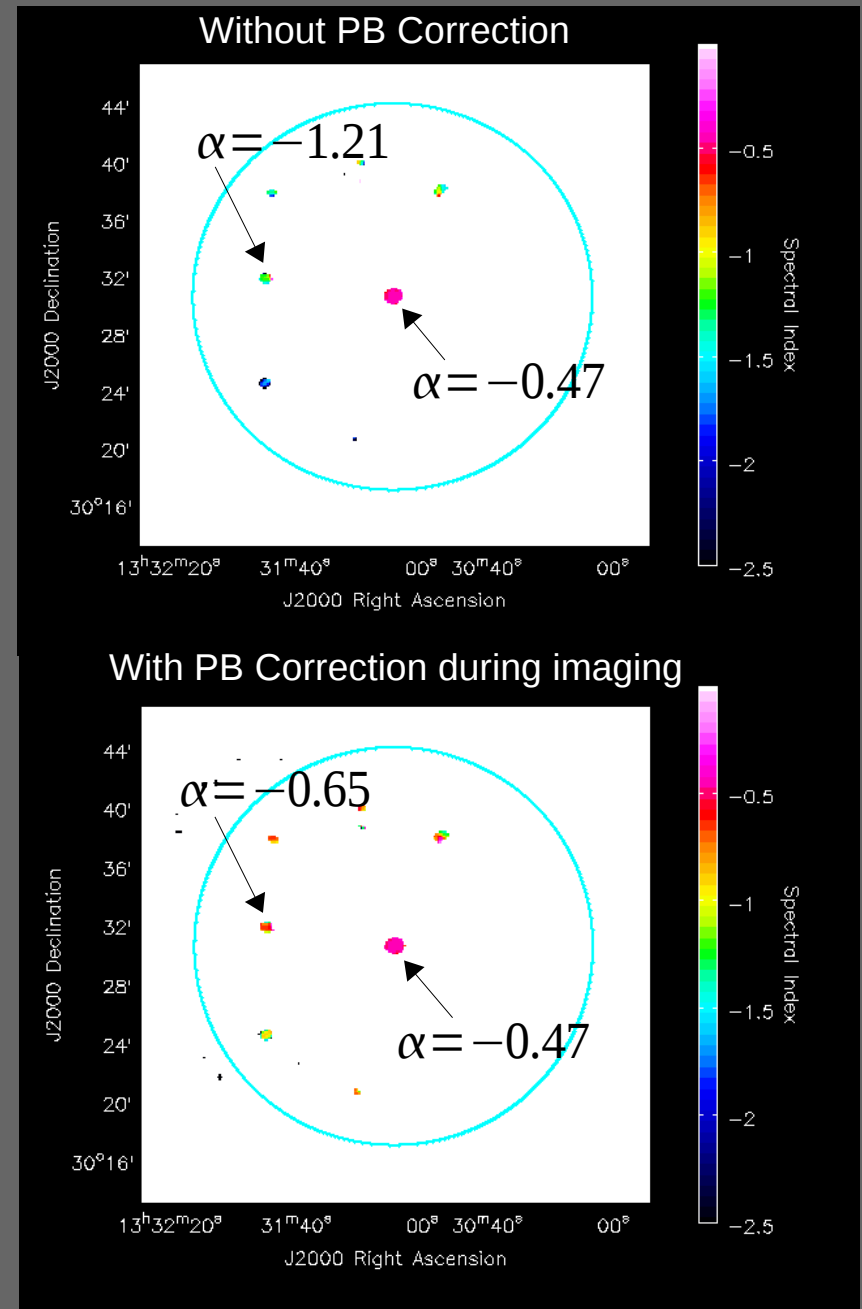


Verified spectral-indices by pointing directly at one background source.

→ compared α_{center} with 'corrected' $\alpha_{off.center}$

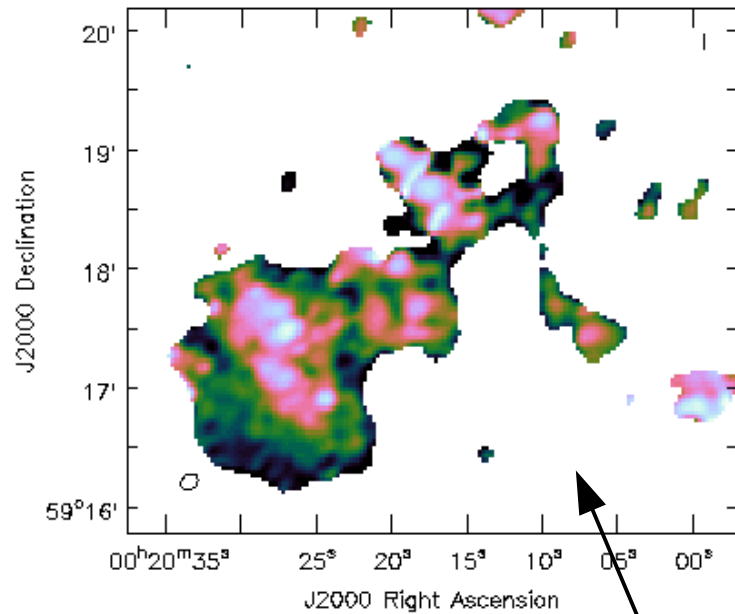
Obtained $\delta \alpha = 0.05$ to 0.1 for SNR or 1000 to 20

Also verified via holography observations at two frequencies

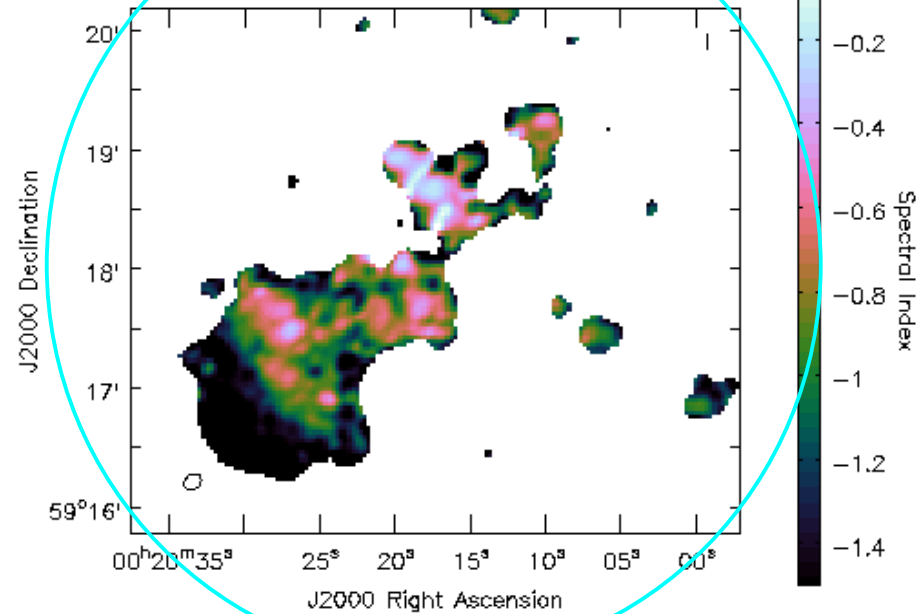


IC10 dwarf-galaxy : spectral-index : Wideband PB correction + angular resolution offered by MS-MFS

After PB-correction



Before PB-correction



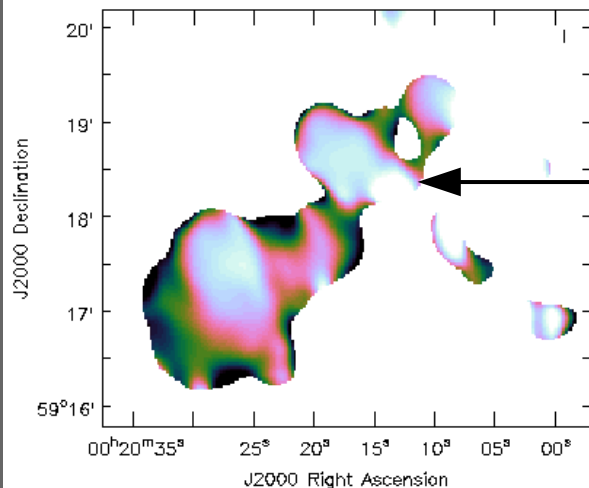
50% of PB

(2011ApJ...739L..23H , arXiv:1108.0401)

Result of post-MS-MFS wide-band PB-correction (CASA)

For comparison, spectral-index map made by PB-correcting single-SPW images smoothed to the lowest resolution (AIPS).

A Post-deconvolution correction assumes that the primary-beam does not vary / rotate during the observation....



Choices that effect errors during wide-band imaging

- Artifacts in the continuum image due to too few Taylor-terms.
Very high signal-to-noise, point-sources : use a higher-order polynomial.
Otherwise, use 2 or 3 terms to prevent over-fitting.
- Error in spectral index/curvature due to too many Taylor-terms.
Low signal-to-noise : use a linear approximation.
Again, $n_{\text{terms}}=2$ or 3 is safer for low signal-to-noise extended emission.
- Error propagation during the division of one noisy image by another.
Extended emission : use multiple spatial scales to minimize this error
Choice of scale sizes : by eye, and verifying that the total-flux converges
- Flux-models that are ill-constrained by the measurements
Choose scales/ n_{terms} appropriately. For very large scales, add short-spacing information.
- Wide-field errors : Time and Frequency-variability of the Primary Beam
Use W-projection, A-projection along with MS-MFS (software in progress)

Positive things : Increased imaging sensitivity (over wide fields), high-fidelity high dynamic-range reconstructions of both spatial and spectral structure.

Choices that effect performance (current MS-MFS implementation)

- Major Cycle runtime $\propto N_{taylor}$ (and size of dataset)
 - N_Taylor residual images are gridded separately; N_Taylor model images are 'predicted'.
 - Wide-field corrections are applied during gridding (A-W-Projection, mosaicing).
- Minor Cycle runtime $\propto N_{taylor} N_{scales} N_{pixels}$
- Minor Cycle memory $\propto \left[0.5 \left(N_{taylor} N_{scales} \right)^2 + N_{taylor} + N_{taylor} N_{scales} \right] N_{pixels}$

Rate of convergence : Typical of steepest-descent-style optimization algorithms : logarithmic. Can control 'loop gain', 'cleaning depth'

Some source structures will handle loop-gains of 0.3 to 0.5 or more (0.3 is safe).

Runtimes reported by different people have ranged from 1 hr to several days.

=> Different choices of parameters => Choose only what you really need.

Example : SNR G55.7+3.4

7 hour synthesis, L-Band, 8 spws x 64 chans x 2 MHz, 1sec integrations

Due to RFI, only 4 SPWs were used for initial imaging (1256, 1384, 1648, 1776 MHz)

(All flagging and calibration done by D.Green, before averaging to 10sec)

J2000 Declination

22°00'

45'

30'

15'

21°00'

45'

Imaging Algorithms applied : MS-MFS with W-Projection

(nterms=2, multiscale=[0, 6, 10, 18, 26, 40, 60, 80])

Peak Flux : 6.8 mJy

Peak residual : 65 micro Jy

Off-source RMS : 10 micro Jy (theoretical = 6 micro Jy)

19^h26^m

24^m

23^m

22^m

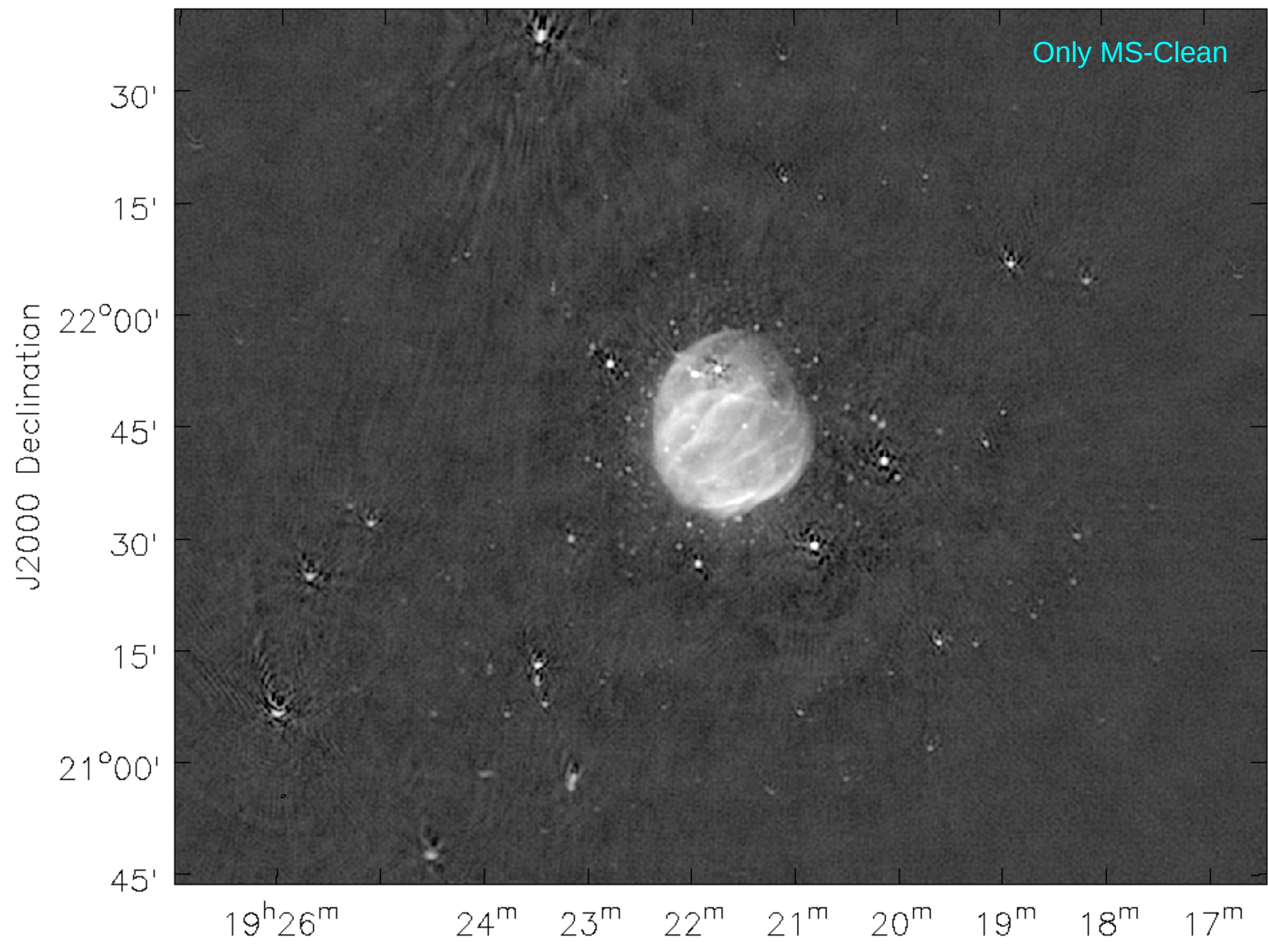
21^m

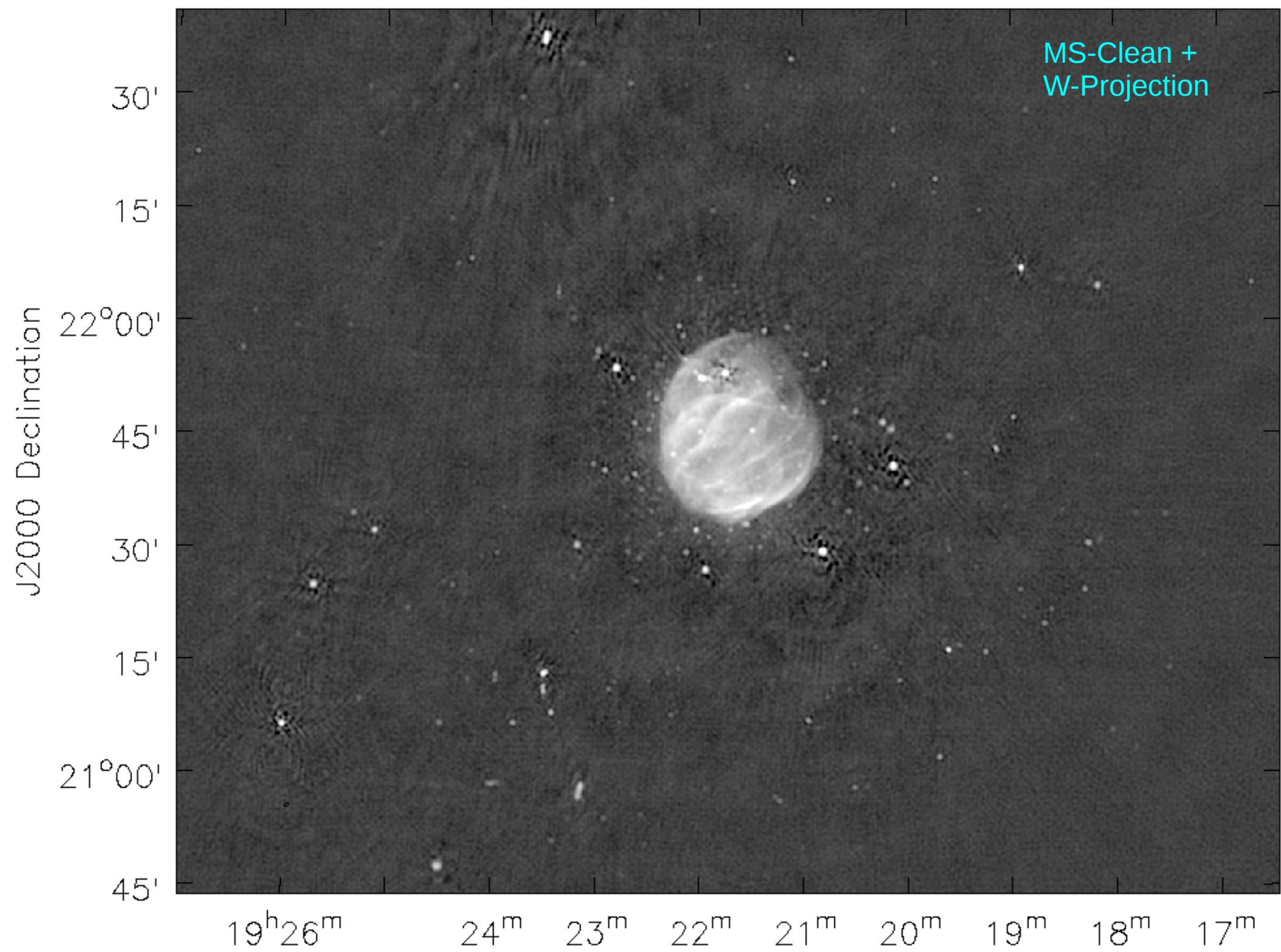
20^m

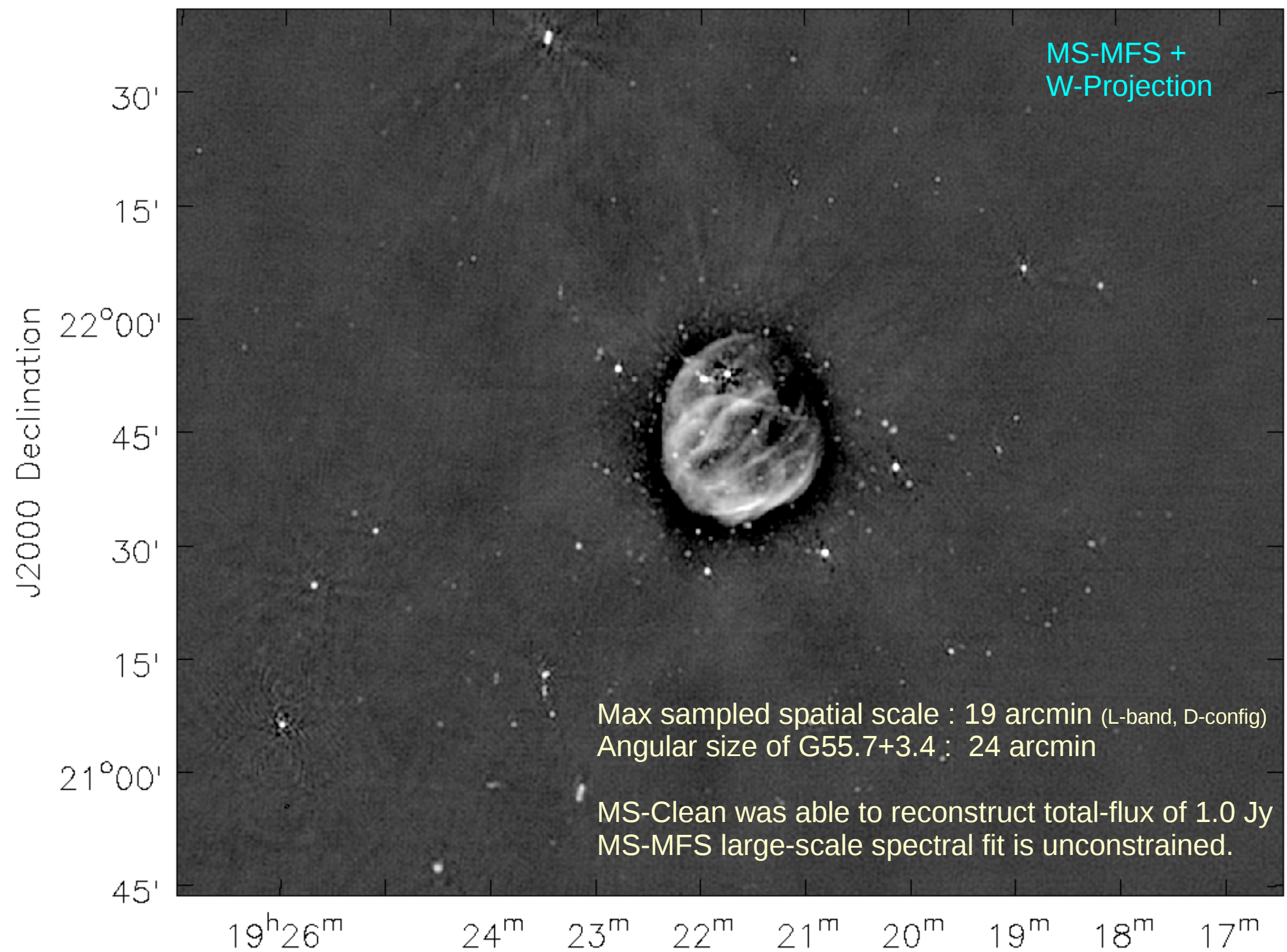
19^m

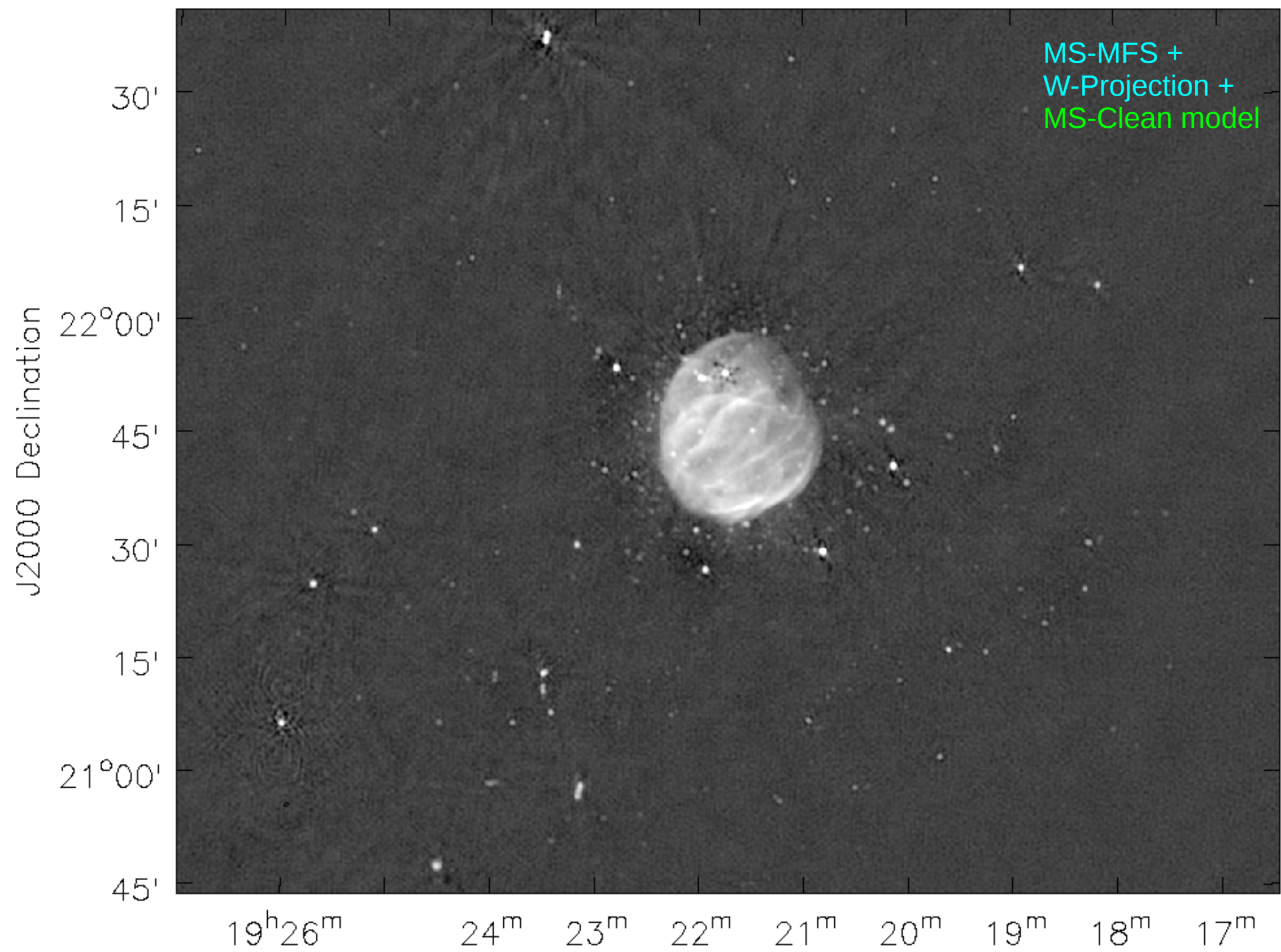
18^m

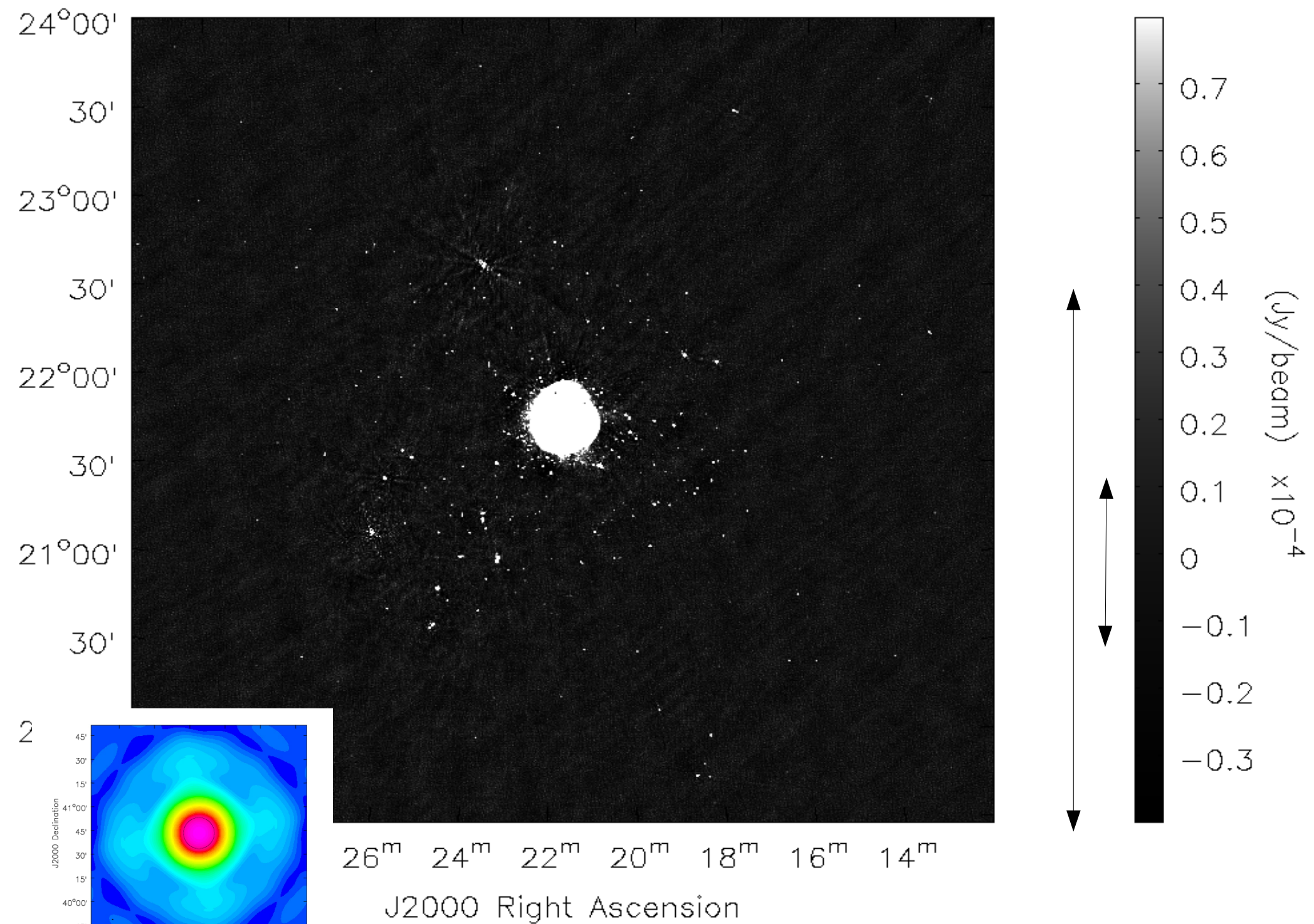
17^m



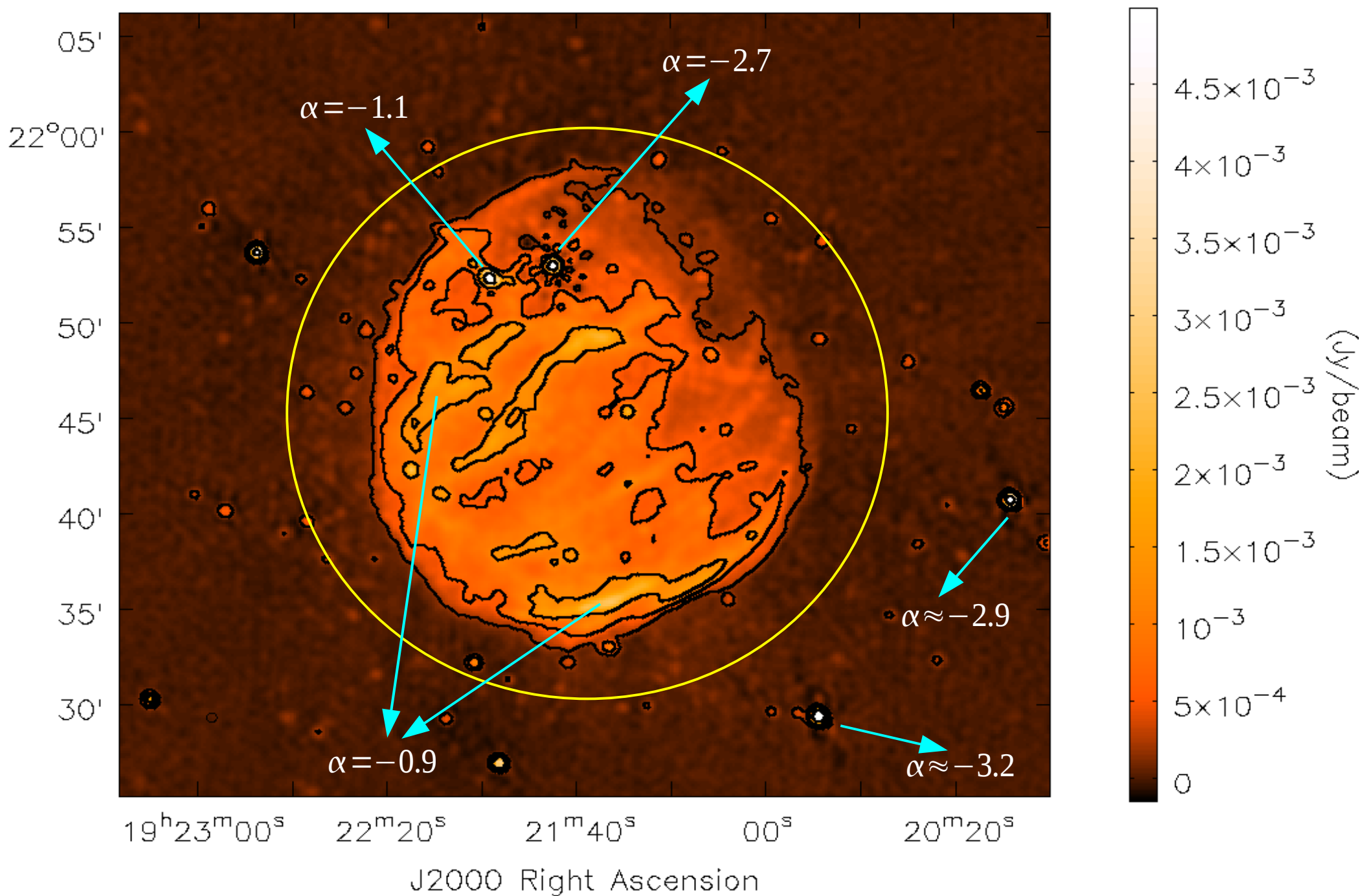






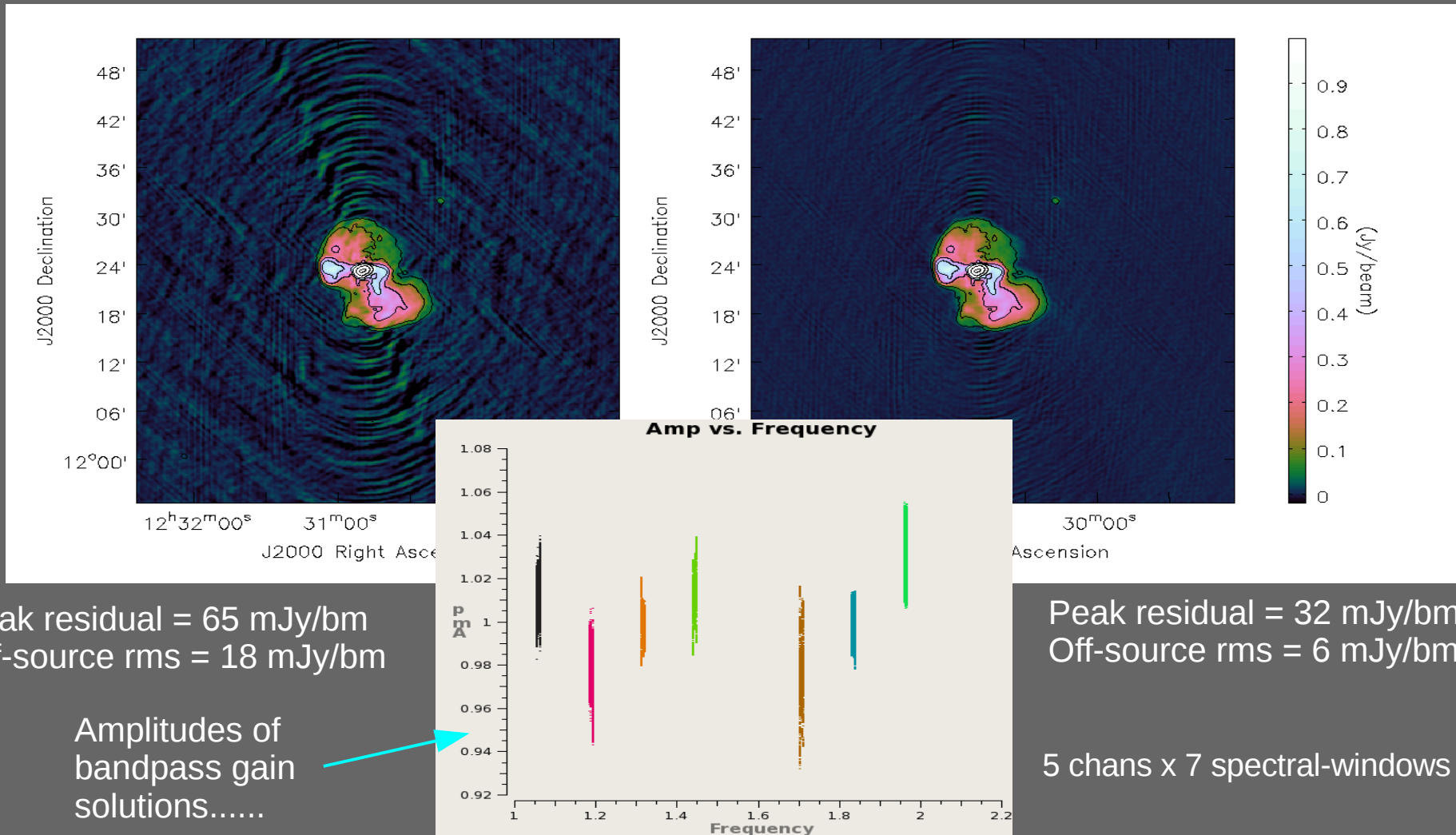


G55.7+3.4 : within the main lobe of the PB



Wide-band Self-calibration (using MS-MFS wideband model)

In CASA, 'clean' writes wide-band model visibilities to disk (calready=True). Or, use 'ft'.



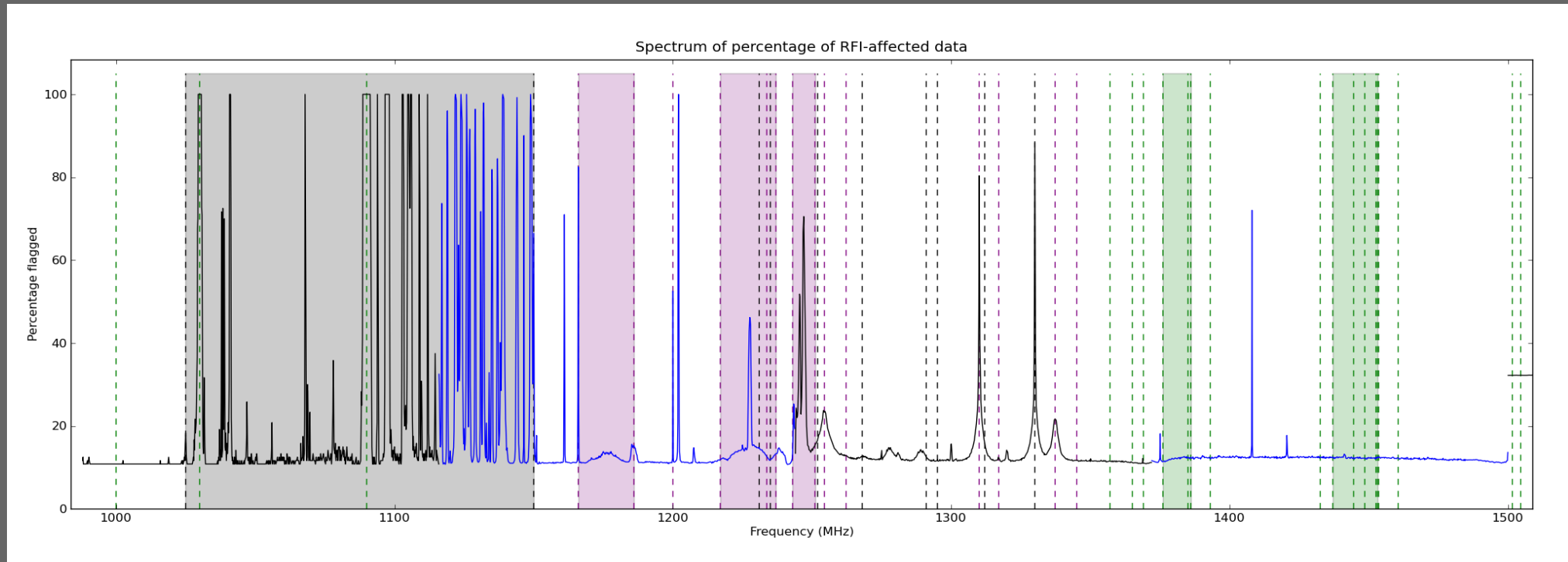
- Can use MS-MFS on your calibrators too, if you don't know their spectra.
- Can also use this wide-band model for continuum subtraction.

RFI and automatic flagging

At L-Band, can use ~500 MHz with very rough flagging, ~800 MHz if done carefully.

CASA : TFCrop (fit a smooth function to the time-freq plane, and find outliers)

AIPS : RFLAG (statistics-based flagger with automatic threshold-calculation)

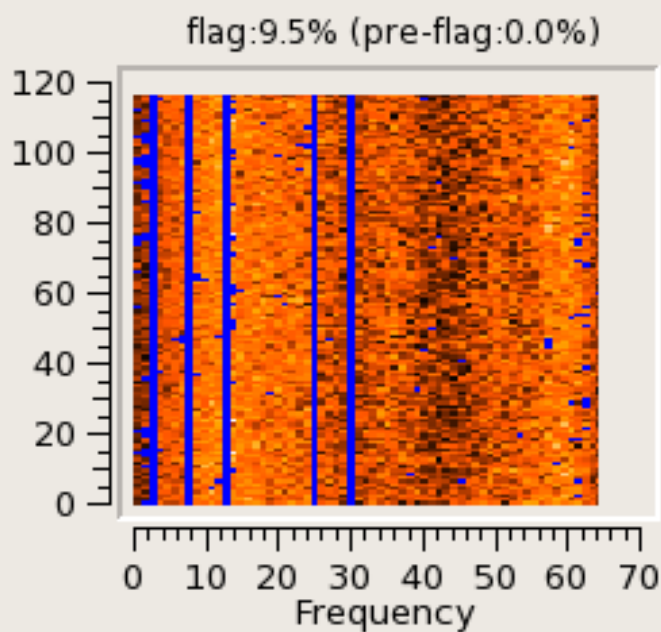
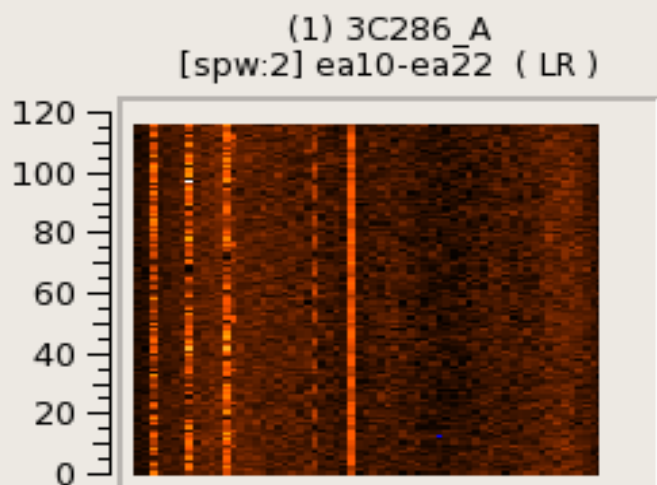


One way to examine your data, is to run 'autoflag' and look at flag counts

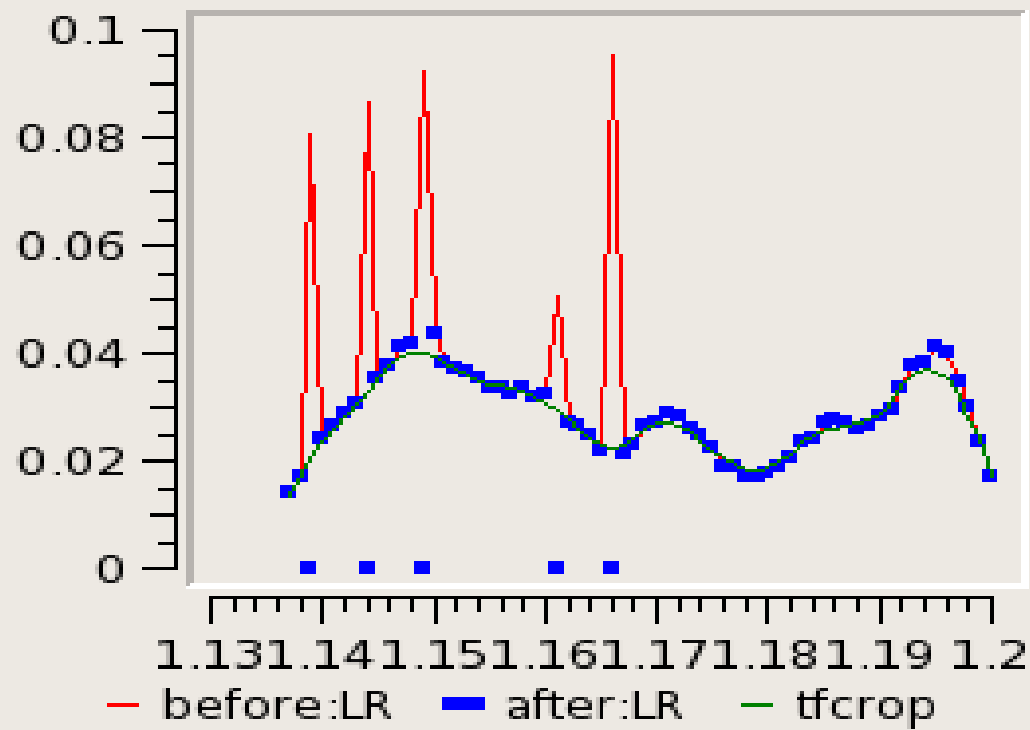
- Inspect uncalibrated data to identify 'clean' regions
- Get an estimate of the fraction of total bandwidth usable for imaging.
- Obtain a flagversion to use as a starting point (first calibration/imaging pass).
- Run it on RFI monitoring data – feed-back information about un-documented RFI

TFCrop : Detect outliers on the 2D time-frequency plane

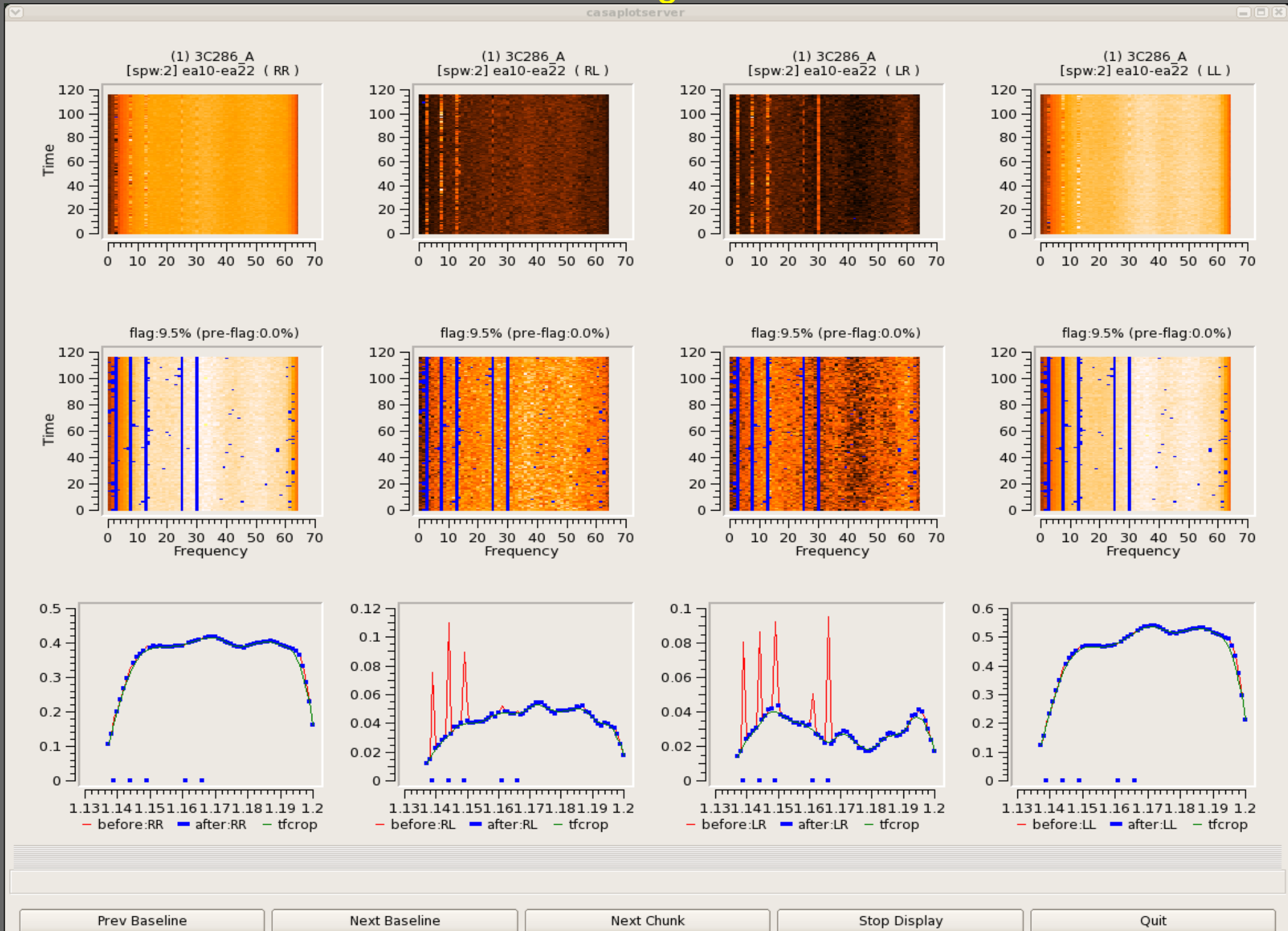
(testautoflag in CASA)



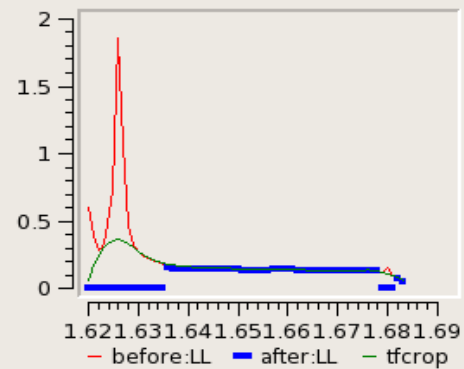
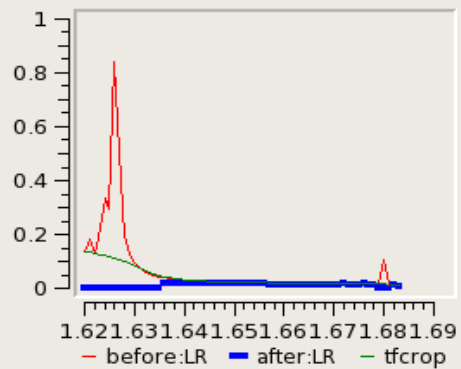
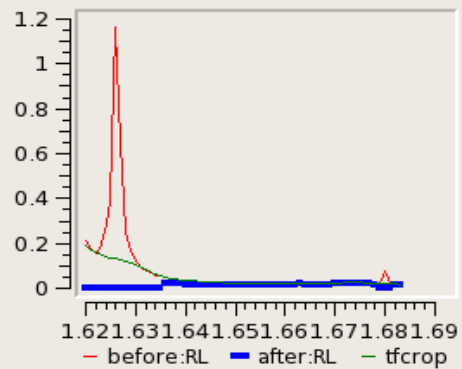
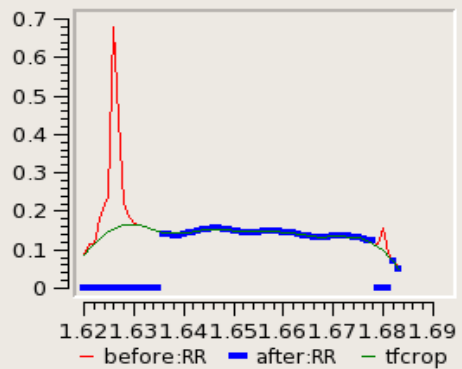
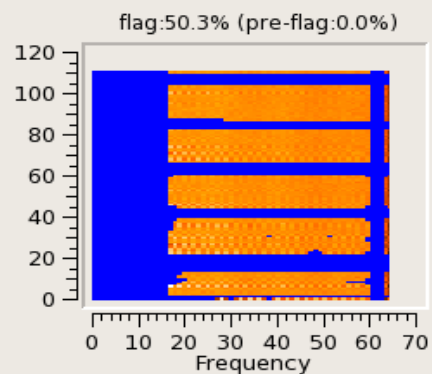
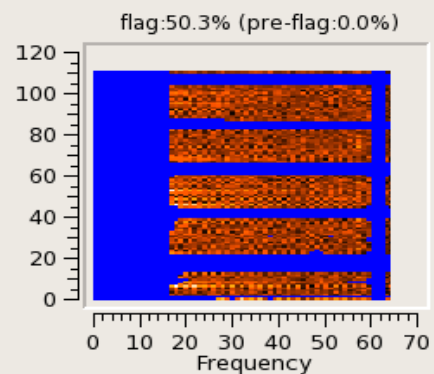
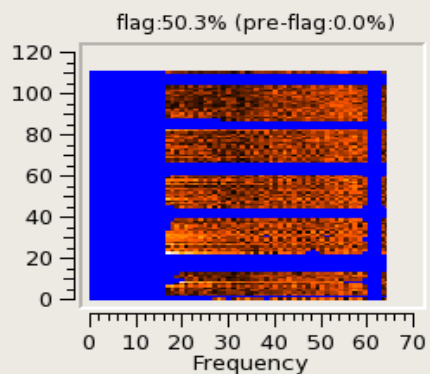
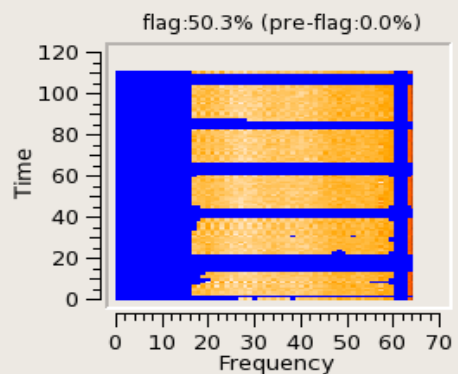
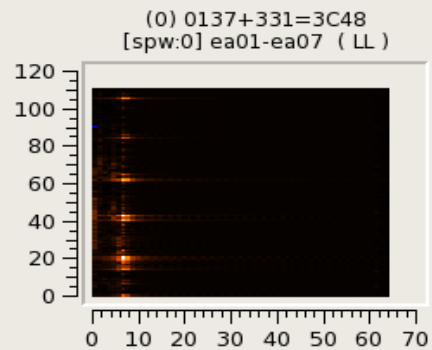
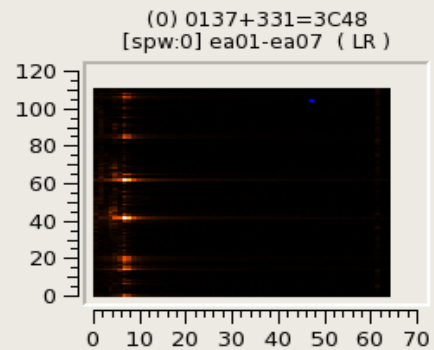
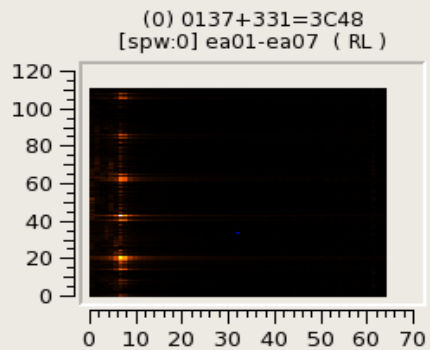
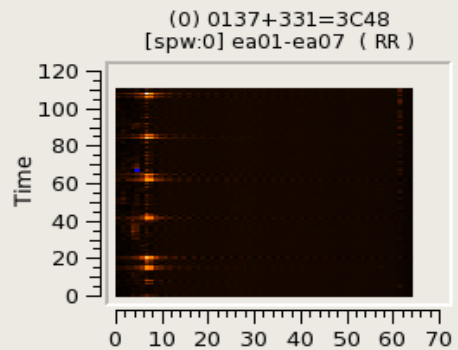
- Average the data along one dimension
- Fit a piece-wise polynomial to the base of RFI spikes
 - calculate 'sigma' of data - fit.
- Flag points deviating from the fit by more than N-sigma
- Repeat along the second dimension.
- Extend flags along time, frequency, polarization



Visualize Data/Flags at run-time



Example 1



Prev Baseline

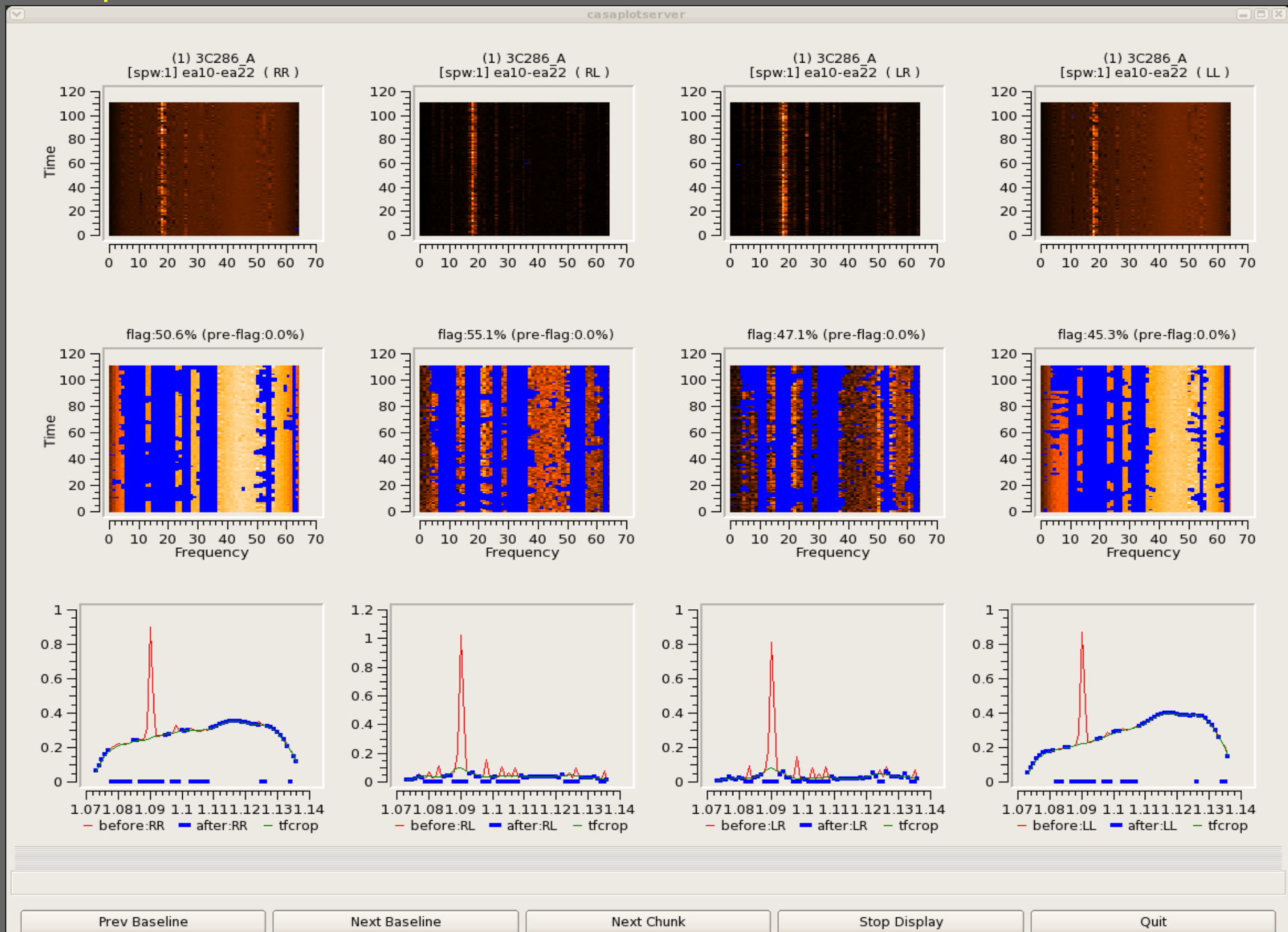
Next Baseline

Next Chunk

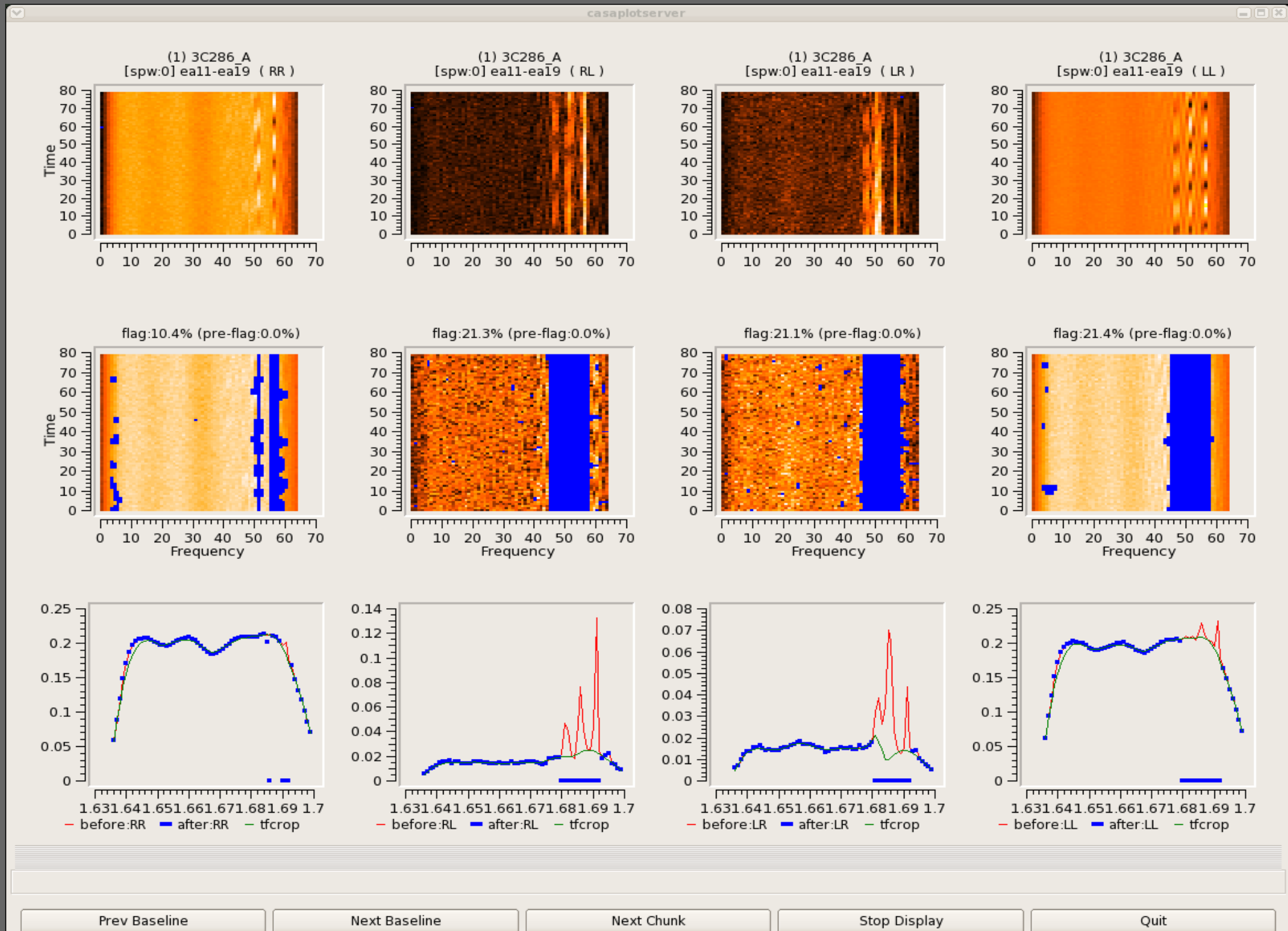
Stop Display

Quit

Example 2



Example 3



RFI identification strategies

- RFI is in-general frequency and direction-dependent (satellites / local/ ...)
 - => Inspect and decide flagging strategies separately per SPW / IF and Field.
 - => Inspect baseline groups (short, mid, long...), especially at higher frequencies
- Choose which correlations to operate on (extend flags to others)
 - => RL, LR have higher RFI signal-to-noise, and RR and LL have stronger band-shape information (depends on what you're looking for)
- Operate on bandpass-corrected data
 - => Do a bandpass calibration in a separate step, or use methods that account for uneven bandpass levels.
- Hanning Smoothing
 - => when there is very strong RFI with ringing in nearby channels.
(for weak RFI, this can spread the RFI to more channels)

Summary

Broad-band receivers

=> better sensitivity

To achieve this sensitivity

=> Careful RFI removal

=> Spatial and spectral image reconstructions along with corrections for wide-field instrumental effects.

User choices (start simple):

- Will single-SPW imaging suffice ?
- If not, then use MS-MFS :
 - N-terms (is there enough SNR ?)
 - Multi-scales (measured vs desired)
- Wide Field-of-view ?
 - W-term, Primary-beam

Imaging results so far (high SNR) :

- Point sources : OK
- Extended emission : DR of few 1000,
- Spectral-index accuracy : 0.02 ~ 0.2
- Wideband PB-correction : Upto HPBW
- RFI at L-Band : Lose 200 ~ 500 MHz

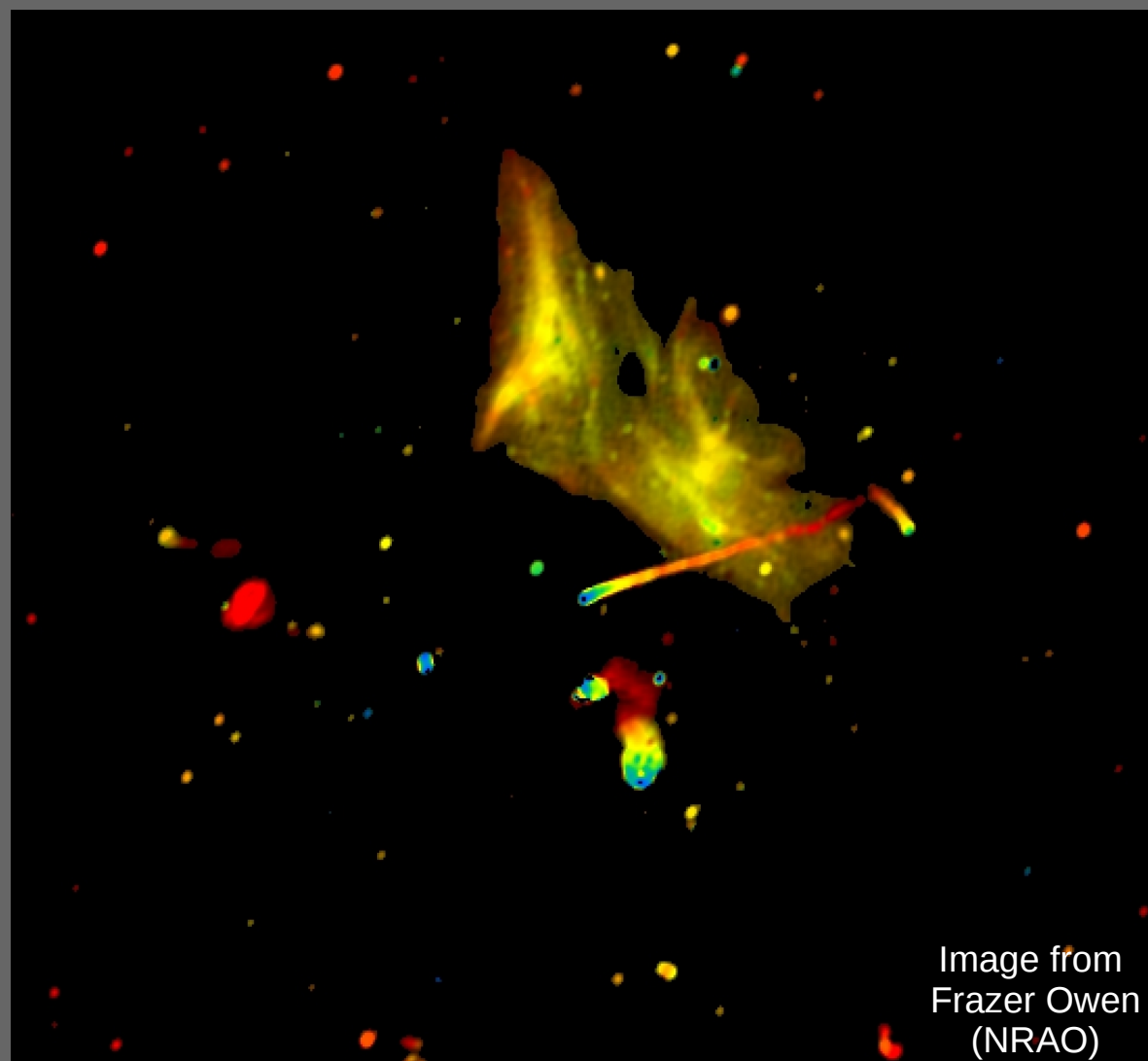


Image from
Frazer Owen
(NRAO)

Abell-2256 : intensity-weighted spectral-index

Ongoing work : HPC methods + more software integration + more efficient minor-cycle algorithms + uncertainty estimates, improving autoflag.....