1 Introduction

The format described in this document is part of the Science Data Model (SDM) being used by the ALMA and EVLA projects. Each application (e.g., ALMA-B correlator data, ALMA total power data, EVLA WIDAR correlator data) is expected to implement only a part of the format described herein, and in that sense, this format is a generalization of the specific formats used by all applications. The generic SDM binary format, and, consequently, its application-specific variants, are all supported by the CASA post-processing software through a CASA-provided measurement set filler.

Where necessary, notations in this document are used to provide application-specific implementation features or details related to the subject under description.

An SDM dataset is composed of a set of tables with specified in-memory representations, and representations as XML documents for data exchange and persistence. The amount of actual data produced by various processors (correlators, square law detectors, radiometers, etc.) being in general very large, data from these sources are stored in binary blocks with unique labels for reference from the SDM tables. These data, comprising the actual data (cross-correlations, auto-correlations), auxiliary data (zero-lags) and associated meta-data (flags, etc.), are grouped into binary large objects (BLOBs). Each processor produces data dumps sequentially in time as the observations proceed, and the data flow is fed by a set of processors producing data concurrently. A single BLOB may consist of a time series of dumps, or, alternatively, a more complex object when the time axis is part of the data structure. The former case is driven by the need to support data streaming; the latter case, by the need to provide efficient storage with minimal overhead for those processors that regularly produce smaller “chunks” of data, although possibly at a moderately high rate (e.g., the data produced by ALMA’s baseband-wide detectors).

Although the data format described in this document could support rather complex data organizations, in practice, for both ALMA and EVLA, we are considering one BLOB per processor per sub-scan. For the ALMA-B correlator the finest temporal granularity of the SDM data is a sub-integration, whereas for the EVLA WIDAR correlator the finest granularity is an integration. Therefore, for the purposes of this document, a BLOB always contains data for the set of (sub-)integrations comprising a sub-scan for a given set of antennas (i.e., subarray).

The specification of the data format as described by this document is, in itself, incomplete. A complete specification is provided by the present document together with the associated XML schemata (see section 7.1). All of the documents required for a complete specification are maintained as a single project under a revision control system. In an attempt to maintain a somewhat higher level of description in the present document, some of the low-level details of the format that are specified by the XML schemata are not provided here. An implementation that reads or writes data in this format will necessarily require information about the XML parts of the format that are best provided by the XML schemata.

1.1 Context

Here we present a short description of the context in which this data format is used by each of the applications.

**EVLA WIDAR note**

The correlator output binary data format applies to the output data stream of the WIDAR correlator backend. The data produced in the binary data format are primarily spectral in nature, although supplemental, non-spectral data are also a part of the format. Typically, the data stream is sent to the
EVLA archive and TelCal, while metadata are sent to MCAF for inclusion in the science data model. Note that there may be other data products produced by the correlator backend; however, their specification is not addressed by the present document.

As of this writing, correlator backend will write its output data stream to a shared filesystem. In the EVLA design, the backend consists of a cluster of computers that accepts the correlator hardware-produced lag frames as input, processes the lag sets, and writes the output data files. One node in the cluster will have the role of the fast formatter, which will initialize the output files prior to access by the other cluster nodes, provide output data not available to individual nodes, and send the completed files to the EVLA archive (the fast formatter node will also provide data to MCAF, but those data are not of concern here.) Cluster nodes handling the lag frames will write data to the output file(s) concurrently as needed. Of course, nothing in this specification prohibits sending the data stream over a network rather than being produced as a file.

**ALMA note**

The ALMA-B correlator produces lag results which are transferred (or dumped) to the CDP (Correlator Data Processor) Node computers via physical connections. The dump interval is programmable. The CDP nodes process the lag data into raw spectra which are then transferred to the CDP Master computer at each integration or sub-integration – there are an integral number of sub-integrations per integration. The master computer organizes these raw spectra according to the binary data format described in this document and transfers them to a data distributor via a network connection to the Archive, TelCal, and QuickLook Pipeline.

The ACA correlator software functions in a similar mode, except that ACA correlator is an FX type generating spectra as its raw output and that the dump interval is non-programmable.
2 High-level organization

In the binary data format, the data are organized hierarchically. While there is considerable flexibility in the format, header fields are sufficient to describe the organization of any instance of the format. The data are organized at the top level using the MIME (Multipurpose Internet Mail Extensions) format. In the application of the MIME format to the binary data format, it provides a hierarchically organized container for data headers in XML format and binary data sections.

Although other applications of the format may vary, as an illustrative example, this document will describe the high-level organization of the data as it is used for the ALMA and EVLA correlators. The binary data format supports applications using an organizational hierarchy with greater depth than is currently used by the aforementioned correlators, but no such applications are known to exist, and the format lacks some specification to fully support this feature. Applications with a lesser hierarchy are supported fully (e.g., the ALMA total power data), but are not yet illustrated with examples in this document. The specification of the hierarchy used to organize the data in any instance of the binary data format is provided by the dimensionality and/or numTimes header elements (which are described in section 6.1).

For the ALMA and EVLA correlators, a BLOB in the binary data format comprises spectral data blocks for a single sub-scan. Each sub-scan contains all the spectral data for all integrations for all baselines of a given set of antennas, all bins, all polarizations, and APC (Atmospheric Phase Correction) data sets.

The parts of a MIME message in the binary data format are of three types: the main data header, the data subset headers, and the binary data components. The main data header contains general information about the sub-scan, and all properties shared by the (sub-)integrations. The subset headers contain information specific to each integration or sub-integration in the sub-scan. The binary data for the (sub-)integration, grouped into several components, follow each subset header. Schematically, the data are organized as follows (for the sub-scan-based grouping used by the ALMA and EVLA correlators).

Data container (sub-scan)

- Main data header (sub-scan-wide metadata)
- Data subset container 1 (first (sub-)integration)
  - Data subset header ((sub-)integration metadata)
  - Binary component 1.1
  - Binary component 1.2
  ...
  - Binary component 1.n
- Data subset container 2 (second (sub-)integration)
  - Data subset header ((sub-)integration metadata)
  - Binary component 2.1
  ...
  - Binary component 2.n
...

Data subset container N (Nth (sub-)integration)

Data subset header ((sub-)integration metadata)

Binary component N.1

...

Binary component N.n

Note that, in general, each additional level of hierarchy in the structure of the data would introduce, in a nested fashion, an equivalent of the “data subset containers” shown in the example above.

The schematic view represented above can be converted into the structure of a MIME message by replacing each “container” with a multipart MIME message. We do not reiterate here all of the relevant MIME specifications; instead we describe the application of the MIME standards to the binary data format, noting only what is specific to this application, including any exceptions to the MIME standards that are allowed under this application. Further information regarding the MIME standards may be found in references [RFC2045], [RFC2046], [RFC2387], and [RFC2557]. With the overall MIME structure of the data format as background, we note the following additional specifications for MIME messages that conform to the binary data format.

- The Content-Type header value of the top-level MIME message is multipart/mixed.
- The Content-Type header value of the MIME messages corresponding to the data subset containers is multipart/related.
- The top-level MIME Content-Description header value is of the form `telescopeName/processorType/processorName/spectralResolution`.

**EVLA WIDAR note**

The top-level MIME Content-Description header value is EVLA/CORRELATOR/WIDAR/FULL_RESOLUTION.

**ALMA note**

For ALMA, we have `telescopeName = ALMA`, `processorType = CORRELATOR`, `processorName = ALMA_ACA` or `ALMA_BASELINE` or `ALMA_BASELINE_ATF` or `ALMA_BASELINE_PROTO_OSF`, `spectralResolution = CHANNEL_AVERAGE` or `FULL_RESOLUTION`

- To preclude scanning through large chunks of binary data before generating a MIME boundary string, sequences of bytes that duplicate a MIME boundary string are allowed to occur in the parts of the MIME message with a Content-type of application/octet-stream. Because the sizes of these parts can be determined from the data headers, true MIME boundary strings can be differentiated from sequences of bytes in the binary parts that happen to match a boundary string. Clearly, with this relaxation of the MIME standard, special applications are required to read the binary format reliably; generic MIME applications could, in theory, fail to parse these messages correctly. All other standard requirements on MIME boundary string values apply to this format.

- The Content-Location header value of the top-level MIME message is the base URI for the resolution of relative URIs in the descendant MIME parts. The value is effectively the data object identifier (dataOID) of the data in the MIME message.

- The Content-Location header value of the MIME parts for the main and subset data headers is the relative URI of the header (with respect to the base URI given in the Content-Location header value of the top-level MIME message). The value consists of the relative project path for the data described by the header.
and the term “desc.xml”, joined by a “/” character. The relative project path for
the main data header comprises the execution block number, the scan number
and the sub-scan number of the data in the MIME message, wherein these
numbers are joined by “/” characters. For the subset data headers, the relative
project path begins with the relative project path in the main data header, and
has appended to it a (sub-)integration number.

- The Content-Location header value of each of the MIME parts for the binary
  components is similarly the relative URI for the binary component. The trailing
  part of each of these URIs is a name derived from the type of the binary
  component together with a “.bin” suffix, for example,
  1/10/3/2/actualDurations.bin. The name in the header value is that of the
  subset header element associated with the binary component type as described
  in section 5.4.

Snippets of MIME messages that conform to the data format can be found in the
appendices.
# 3 Enumerations

Several enumerations are used by the data format to provide a semantic basis for certain terms, and to create a bridge to the enumerations used in the other components of the SDM. Enumeration values have both string and integer representations. In the table below, enumeration values are presented in their proper order; however, the integer values are not specified, because they are of no direct use.

<table>
<thead>
<tr>
<th>Enumeration type</th>
<th>Enumeration values</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AtmPhaseCorrection</td>
<td>AP_UNCORRECTED</td>
<td>uncorrected for atmospheric phase</td>
</tr>
<tr>
<td></td>
<td>AP_CORRECTED</td>
<td>corrected for atmospheric phase</td>
</tr>
<tr>
<td></td>
<td>AP_MIXED</td>
<td>mixture of baselines with and without atmospheric phase correction</td>
</tr>
<tr>
<td>AxisName</td>
<td>TIM</td>
<td>time</td>
</tr>
<tr>
<td></td>
<td>BAL</td>
<td>baseline</td>
</tr>
<tr>
<td></td>
<td>ANT</td>
<td>antenna</td>
</tr>
<tr>
<td></td>
<td>BAB</td>
<td>baseband</td>
</tr>
<tr>
<td></td>
<td>SPW</td>
<td>spectral window</td>
</tr>
<tr>
<td></td>
<td>BIN</td>
<td>bin (e.g., pulsar phase, frequency)</td>
</tr>
<tr>
<td></td>
<td>APC</td>
<td>atmospheric phase correction bin</td>
</tr>
<tr>
<td></td>
<td>SPP</td>
<td>spectral point (channel)</td>
</tr>
<tr>
<td></td>
<td>POL</td>
<td>polarization</td>
</tr>
<tr>
<td></td>
<td>HOL</td>
<td>holography</td>
</tr>
<tr>
<td>BasebandName</td>
<td>BB_1</td>
<td>baseband 1</td>
</tr>
<tr>
<td></td>
<td>BB_2</td>
<td>baseband 2</td>
</tr>
<tr>
<td></td>
<td>BB_3</td>
<td>baseband 3</td>
</tr>
<tr>
<td></td>
<td>BB_4</td>
<td>baseband 4</td>
</tr>
<tr>
<td></td>
<td>BB_5</td>
<td>baseband 5</td>
</tr>
<tr>
<td></td>
<td>BB_6</td>
<td>baseband 6</td>
</tr>
<tr>
<td></td>
<td>BB_7</td>
<td>baseband 7</td>
</tr>
<tr>
<td></td>
<td>BB_8</td>
<td>baseband 8</td>
</tr>
<tr>
<td>CorrelationMode</td>
<td>CROSS_ONLY</td>
<td>cross-correlation data only</td>
</tr>
<tr>
<td></td>
<td>AUTO_ONLY</td>
<td>auto-correlation data only</td>
</tr>
<tr>
<td></td>
<td>CROSS_AND_AUTO</td>
<td>both cross-correlation and auto-correlation data</td>
</tr>
<tr>
<td>CorrelatorName</td>
<td>ALMA_ACA</td>
<td>ALMA_BASELINE</td>
</tr>
<tr>
<td>------------------------</td>
<td>---------------</td>
<td>---------------</td>
</tr>
<tr>
<td>PrimitiveDataType</td>
<td>INT16_TYPE</td>
<td>16-bit signed integer</td>
</tr>
<tr>
<td></td>
<td>SHORT_TYPE</td>
<td>IDL short, XMLW3C short, C/C++ short, Java short</td>
</tr>
<tr>
<td></td>
<td>UINT16_TYPE</td>
<td>16-bit unsigned integer</td>
</tr>
<tr>
<td></td>
<td>INT32_TYPE</td>
<td>32-bit signed integer</td>
</tr>
<tr>
<td></td>
<td>INT_TYPE</td>
<td>IDL int, XMLW3C int, C/C++ int, Java</td>
</tr>
<tr>
<td></td>
<td>UINT32_TYPE</td>
<td>32-bit unsigned integer</td>
</tr>
<tr>
<td></td>
<td>UNSIGNED_INT_TYPE</td>
<td>IDL int, XMLW3C unsignedInt, C/C++ unsigned int, Java int</td>
</tr>
<tr>
<td></td>
<td>INT64_TYPE</td>
<td>64-bit signed integer</td>
</tr>
<tr>
<td></td>
<td>UINT64_TYPE</td>
<td>64-bit unsigned integer</td>
</tr>
<tr>
<td></td>
<td>LONGLONG_TYPE</td>
<td>64-bit signed integer</td>
</tr>
<tr>
<td></td>
<td>FLOAT32_TYPE</td>
<td>IEEE 754 single format floating point number (32 bits)</td>
</tr>
<tr>
<td></td>
<td>FLOAT64_TYPE</td>
<td>IEEE 754 double format floating point number (64 bits)</td>
</tr>
<tr>
<td>ProcessorType</td>
<td>CORRELATOR</td>
<td>digital correlator</td>
</tr>
<tr>
<td></td>
<td>RADIOMETER</td>
<td>radiometer</td>
</tr>
<tr>
<td></td>
<td>SPECTROMETER</td>
<td>multi-channel spectrometer</td>
</tr>
<tr>
<td>NetSideband</td>
<td>NOSB</td>
<td>no sideband</td>
</tr>
<tr>
<td></td>
<td>USB</td>
<td>upper sideband</td>
</tr>
<tr>
<td></td>
<td>LSB</td>
<td>lower sideband</td>
</tr>
<tr>
<td></td>
<td>DSB</td>
<td>double sideband</td>
</tr>
<tr>
<td>SpectralResolutionType</td>
<td>FULL_RESOLUTION</td>
<td>high spectral resolution data</td>
</tr>
<tr>
<td></td>
<td>CHANNEL_AVERAGE</td>
<td>lower spectral resolution data</td>
</tr>
<tr>
<td></td>
<td>BASEBAND_WIDE</td>
<td>data applying to the whole baseband</td>
</tr>
<tr>
<td>StokesParameter</td>
<td>Description</td>
<td></td>
</tr>
<tr>
<td>---------------</td>
<td>-----------------------------------------</td>
<td></td>
</tr>
<tr>
<td>RR</td>
<td>right-right polarization product</td>
<td></td>
</tr>
<tr>
<td>RL</td>
<td>right-left polarization product</td>
<td></td>
</tr>
<tr>
<td>LR</td>
<td>left-right polarization product</td>
<td></td>
</tr>
<tr>
<td>LL</td>
<td>left-left polarization product</td>
<td></td>
</tr>
<tr>
<td>XX</td>
<td>X-X polarization product</td>
<td></td>
</tr>
<tr>
<td>XY</td>
<td>X-Y polarization product</td>
<td></td>
</tr>
<tr>
<td>YX</td>
<td>Y-X polarization product</td>
<td></td>
</tr>
<tr>
<td>YY</td>
<td>Y-Y polarization product</td>
<td></td>
</tr>
</tbody>
</table>

*Table 1: Enumerations*
4 Data stream types

The binary data are classified according to the "mode" under which the data processor has produced the data. The binary data format supports a concept of mode under which the data format varies slightly according to this mode. Because the data formats are somewhat different for the different modes, we classify a sequence of files (i.e., MIME messages) in the binary data format produced under a given mode (by a single data processor) by the term data stream. A data stream is parameterized by two values, one of type CorrelationMode, and one of type SpectralResolutionType. Any given data processor will likely produce data in only a small subset of the nine possible types of data streams.

The specification of a data stream type affects the binary data format by restricting the set of allowed binary components, as well as their structures. Effects are also present in the main data header and the data subset headers as a consequence.

**EVLA WIDAR note**
The EVLA WIDAR correlator backend produces a single data stream per subarray. For this stream, the CorrelationMode value is CROSS_AND_AUTO, and the SpectralResolutionType value is FULL_RESOLUTION. Note that the data stream may be smoothed or averaged by the correlator backend — setting the SpectralResolutionType to FULL_RESOLUTION is done simply to match the ALMA convention, where this means “highest available spectral resolution”.

**ALMA note**
For ALMA, CorrelationMode = CROSS_ONLY is not allowed.

To highlight the dependencies in the format on the data stream type, small grids filled with one-letter annotations are used whenever some aspect of the format that varies with data stream type is being described. These grids appear in the left margin of the page, adjacent to the presentations of elements, attributes, and components as needed. The following table shows the structure of these marginal grids; the grids themselves appear without row headers, column headers, or grid lines.

<table>
<thead>
<tr>
<th>CorrelationMode</th>
<th>SpectralResolutionType</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>FULL_RESOLUTION</td>
</tr>
<tr>
<td>CROSS_ONLY (C)</td>
<td>M/O/X</td>
</tr>
<tr>
<td>AUTO_ONLY (A)</td>
<td>M/O/X</td>
</tr>
<tr>
<td>CROSS_AND_AUTO (B)</td>
<td>M/O/X</td>
</tr>
</tbody>
</table>

Table 2: Key to format variation marginal grids. Symbols: M - mandatory, O - optional, X - excluded. The letters in parentheses are the abbreviated forms of the table headers used in the marginal grids.

For example, the grid in the margin to the left shows that the element named “EXAMPLE” is optional whenever the CorrelationMode value of the data stream is CROSS_ONLY, or the CorrelationMode value is CROSS_AND_AUTO and the SpectralResolutionType value is undefined or has the value BASEBAND_WIDE; excluded (that is, prohibited) whenever the CorrelationMode value is AUTO_ONLY; and mandatory whenever the CorrelationMode value is CROSS_AND_AUTO and the SpectralResolutionType value is either FULL_RESOLUTION or CHANNEL_AVERAGE.¹

¹ A format change to be adopted soon will define zeroLags for both full resolution and channel average, so the SpectralResolutionType will become meaningless and will be dropped.
5 Binary components

5.1 Types

Seven types of binary components are supported by the binary data format. The set of binary component types is meant to be extensible, but for the purposes of the present version of the format described in this document, the following list shall be considered exhaustive. The descriptions in the following list of binary component types are merely brief summaries; for more detailed information, refer to section 5.4.

FLAGS
flagging information

ACTUAL_TIMES
time centroid associated with data

ACTUAL_DURATIONS
total amount of time used in deriving the data

WEIGHTS
data weights

ZERO_LAGS
zero lags

CROSS_DATA
cross-correlation data

AUTO_DATA
auto-correlation data

EVLA WIDAR note
The EVLA correlator backend is able to produce all of the above binary component types.

ALMA note
The ALMA CDP does not produce WEIGHTS. The ACA correlator produces neither WEIGHTS nor ZERO_LAGS.

5.2 Tree structure

The data in the binary components are organized in a tree structure, in which the trees are of uniform depth, and the nodes are ordered. Data elements are associated with the leaf nodes of the tree, and the in-memory and persistent representations of the data correspond to an in-order traversal of the leaf nodes of the tree. Each level of the tree corresponds with a data axis along which the data are indexed. Each axis in an ordered list corresponds with a level in the tree structure of the binary data, the levels descending the tree as the axis list is traversed in order.

5.3 Axes

The axes that can be used to index the binary data components are listed in Table 1 under the AxisName enumeration type. Note that the order of the axes given in Table 1 is significant for the binary components; although not all axes are required for a binary component, the axes that are used must be ordered as given by the table. For example, if the $N^{th}$ level of a tree is indexed by the SPW axis, the $N+1^{th}$ level may be indexed by
any one of the BIN, APC, SPP, or POL axes, but not the TIM, BAL, ANT or BAB axes. The axis ordering therefore imposes a hierarchy on the data structure of all binary components. As an example, the number of spectral windows may depend on the baseband, but not on the set (or list) of polarizations.

**EVLA WIDAR note**

The bin axis, BIN, is used primarily for pulsar phase binning.

The atmospheric phase correction axis, APC, initially will have a size of one; the single element having a value of AP_UNCORRECTED.

**ALMA note**

The bin axis is used for nutator or frequency switching.

An important exception to the hierarchical nature of the axes named by the `AxisName` enumeration type is that the BAL and ANT axes are at the same level. This means that when the sequence “BAL, ANT” is given in a list of axes: 1) the ANT nodes are to be considered as equivalent to a baseline of length zero; 2) the “true” baseline-based (i.e., non-zero baseline length) data appear before the antenna-based data when traversing the tree nodes in order; and 3) both types of nodes appear at a single level of the tree.

### 5.3.1 Lists

The structure of a binary component is thus greatly dependent upon the axes used for indexing the data in the component. Metadata for each binary component specifies an ordered list of axes along which the data are indexed. Applications of this format may restrict the set of allowed axes lists for the various binary components, but such restrictions are not a part of the format specification.

### 5.3.2 Sizes

The size (or length) of an axis is equal to the number of children of a node at the level corresponding to that axis. For a generic tree, each node at any given level could have a different number of children, but in the binary data format, the number of children at various nodes in a tree may be constrained.

The sizes of the axes of a binary component tree are specified in various ways, as follows.

- **TIM**: Size is set by the `numTimes` element of the main data header, if present; otherwise, the axis size is one.

  **EVLA WIDAR note**

  The size of the TIM axis is one in the EVLA WIDAR format (for sub-band cross- and auto-correlations), meaning that each data subset contains data associated with a single time (that being all the data within one integration interval).

  **ALMA note**

  The size of the TIM axis is one in the ALMA-B correlator format (for sub-band cross- and auto-correlations), meaning that each data subset contains data associated with a single time (that being all the data within one integration interval).

- **BAL**: Size is determined by the value of the `numAntenna` element of the main data header. If the value of `numAntenna` is represented by $N_a$, the size of this axis is $\frac{N_a(N_a - 1)}{2}$.

- **ANT**: Size is set by the `numAntenna` element of the main data header.

- **BAB**: Size is equal to the number of `baseband` elements in the main data header.
- **SPW**: Size is equal to the number of spectralWindow elements within a baseband element (hence, the axis size may vary with baseband).
- **BIN**: Size is set by the numBin attribute of a spectralWindow element (hence, the axis size may vary with spectral window).

  **ALMA note**
  
  numBin is common to all spectral windows defined in a baseband.

- **APC**: Size is equal to the number of enumerators appearing in the (list) value of the apc attribute of the dataStruct element of the main data header.
- **SPP**: Size is set by the numSpectralPoint attribute of a spectralWindow element of the main data header (hence, the number of spectral points may vary with spectral window).
- **POL**: For AUTO_DATA and CROSS_DATA binary components, the axis size is equal to the number of enumerators in the (list) value of the sdPolProduct and crossPolProduct attributes, respectively, of a spectralWindow element. For the FLAGS binary component, the size of this axis depends on whether the flagging is done on the basis of polarizations or polarization products. In the case of polarization-based flagging, this means that if the sdPolProduct or crossPolProduct lists have more than two items, the POL axis size is two, otherwise, it is one. For WEIGHTS, ACTUAL_TIMES and ACTUAL_DURATIONS binary components, the size of the axis can be 1, 2, 3 or 4.

### 5.3.3 List reduction

Generally, a tree can always be indexed with its complete set of axes. However, when the size of an axis is one (in all tree branches), and the logical node value on that axis is constant in all tree branches, that axis may be omitted from the list of axes. Reducing the axis list in this way has no impact on either the number of elements in the tree, or on the structure of elements in the tree. The only effect of axis list reduction is on the description of the tree. Note the requirement that for list reduction the logical node value on the axis must be constant on all tree branches; this means that, for example, if on one tree branch the POL axis has data for the single value XX, no other tree branch has data on the POL axis for a different value of the StokesParameter enumeration.

### 5.3.4 Element ordering

Ordering of index values along an axis depends on the axis as follows.

**ANT**

Integer order (e.g., 1, 2, 5, 10, 12)

  **ALMA note**
  
  ALMA antennas are alphanumeric strings and ordered accordingly, e.g., A01, A02, A10, D1, D3.

**BAL**

In a matrix formed by labelling rows and columns with antenna indexes, and where each matrix element is the pair (row antenna index, column antenna index), the ordering of the BAL axis corresponds to the column-major traversal of the matrix's upper triangle. This ordering allows baselines introduced through the addition of a new antenna to appear at the end of the list. For example, for antennas in the set \{1, 2, 4, 7\}, the order of baselines is (1, 2), (1, 4), (2, 4), (1, 7), (2, 7), (4, 7).
Note that for the special case in which the axis list contains the sequence “BAL, ANT”, in the previous example, the complete list of antenna “pairs” along the unified “BAL, ANT” axis is (1, 2), (1, 4), (2, 4), (1, 7), (2, 7), (4, 7), (1, 1), (2, 2), (4, 4), (7, 7).

Finally, note that the order of the correlation products recorded in the binary must agree with the order of antennas in each baseline. For example if the baseline is (1, 2), the product must be 1 * 2, not 2 * 1.

**BAB**

Order of *BasebandName* type values (see Table 1)

**SPW**

Order of *spectralWindow* elements within a *baseband* element in the main data header

**BIN**

Integer order

**APC**

Order of *AtmPhaseCorrection* type values (see Table 1)

**SPP**

Integer order

**EVL A WIDAR note**
The WIDAR correlator can produce either frequency or lag spectra. The conversion from integer SPP axis values to frequency or lag number is provided by the SDM metadata.

**ALMA note**
For upper sidebands, the frequency order decreases with increasing channel number and for lower sidebands, the frequency order increases with increasing channel number.

**POL**

Order of *StokesParameter* type values (see Table 1)

### 5.4 Components

The data in each binary component type are described below in terms of the quantity represented, the units used to express that quantity, and the type used to represent the data. Additionally, for each binary component type, the name of the element in the main or subset data header that provides metadata for the binary component is identified. Finally, because the presence or absence of a binary component is meaningful, a description of such meaning is also given where relevant.

**FLAGS**

- datum: occurrence of flag conditions
- units: N/A, bitfield
- data type: 32 bit integer (INT32_TYPE)
- header element: `flags`
- Absence of this component means that no flag conditions occurred during data acquisition. Note that the flag conditions are application specific.
**ACTUAL_TIMES**
- datum: centroid of (MJD) time interval associated with data subset, allowing for blanking
- units: nanoseconds
- data type: 64 bit integer (INT64_TYPE)
- header element: actualTimes
- If this component is absent, then no data blanking has occurred during the time interval, and the time stored in the data subset header (by the time element) is to be used for the time associated with the data subset.

**ACTUAL_DURATIONS**
- datum: total amount of time used in deriving the data subset, allowing for blanking. Proportional to the number of valid samples.
- units: nanoseconds
- data type: 64 bit integer (INT64_TYPE)
- header element: actualDurations
- If this component is absent, then no data blanking has occurred during the time interval, and the duration stored in the data subset header (by the interval element) is to be used for the exposure time associated with the data subset.

**ZERO_LAGS**
- datum: lag zero value (real-valued)
- data type: single format IEEE 754 floating point number (FLOAT32_TYPE)
- header element: zeroLags

For the ALMA-BL correlator, data are always present for FULL_RESOLUTION. The ACA correlator does not produce ZERO_LAGS.

**AUTO_DATA**
- datum: auto-correlation value (real- or complex-valued)
- data type: 1 or 2 * single format IEEE 754 floating point number (FLOAT32_TYPE)
- header element: autoData

**CROSS_DATA**
- datum: cross-correlation value (complex-valued)
- data type: 2 * single format IEEE 754 floating point number (FLOAT32_TYPE), integer (INT_TYPE), or short integer (SHORT_TYPE) (specified in the data subset header crossDataType element)
- header element: crossData

Initially EVLA will use 2 * FLOAT32_TYPE.

ALMA uses scaled 16- or 32-bit signed integers. See [Scott].
WEIGHTS

- datum: data weight lookup table index (lookup table is located in weights element of main data header)
- data type: variable, a word of $N$ bits to encode $2^N$ lookup table index values
- header element: weights

**EVLA WIDAR note**
Initially, the number of bits allowed for the weights will be small multiples of 8; eventually, other values will be accommodated.

**ALMA note**
ALMA does not use weights.

### 5.4.1 Data stream dependencies

The following table lists the mandatory and optional binary components as a function of data stream type (specifically, the value of a `CorrelationMode` parameter only).

<table>
<thead>
<tr>
<th>Binary component type</th>
<th>CROSS_ONLY</th>
<th>AUTO_ONLY</th>
<th>CROSS_AND_AUTO</th>
</tr>
</thead>
<tbody>
<tr>
<td>FLAGS</td>
<td>O</td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>ACTUAL_TIMES</td>
<td>O</td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>ACTUAL_DURATIONS</td>
<td>O</td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>ZERO_LAGS</td>
<td>O</td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>AUTO_DATA</td>
<td>X</td>
<td>M</td>
<td>M</td>
</tr>
<tr>
<td>CROSS_DATA</td>
<td>M</td>
<td>X</td>
<td>M</td>
</tr>
<tr>
<td>WEIGHTS</td>
<td>O</td>
<td>O</td>
<td>O</td>
</tr>
</tbody>
</table>

*Table 3: Mandatory and optional binary components. Symbols: O - optional, X - excluded, M - mandatory*
6 Header elements

The parts of a MIME message in the binary data format that contain header information are represented as XML elements. The following sections provide an overview of these elements, their content, and their attributes. Further detailed, technical information about these elements, such as the formats and/or types of attribute values, can be found in the XML schemata associated with this document (see section 7.1).

6.1 Main data header

The main data header appears once in every binary data format BLOB (that is, once per sub-scan). The header itself has the name sdmDataHeader, and it has the following attributes:

- **xmlns**, a string which defines the SDM binary schema namespace with the fixed value: “http://TBD/XSDM/sdmBin”. Note that 'TBD' must be defined for the appropriate archive repository.
- **xmlns:xsi**, the namespace of the schema instance which has the fixed value of “http://www.w3.org/2001/XMLSchema-instance”
- **xmlns:xlink**, which has a fixed value of "http://www.w3.org/1999/xlink";
- **xmlns:xvers**, which has a fixed value of "http://TBD/XVERSION" Note that 'TBD' must be defined for the appropriate archive repository.
- **xsi:schemaLocation**, the location of the schema.

**ALMA note**

This value is "http://TBD/XSDM/sdmbin 0/sdmDataObject.xsd". Note that 'TBD' must be defined for the appropriate archive repository.

- **xvers:schemaVersion**, the version number of the XML schema to which the XML header elements in the BLOB conform and has the form of "http://TBD/XVERSION"; Note that 'TBD' must be defined for the appropriate archive repository.
- **xvers:revision** the schema revision number.

**ALMA note**

This value is related to the CVS version of the schema.

- **mainHeaderId**, which has a fixed value of “sdmDataHeader”;
- **byteOrder**, the endianness of the binary data elements;

**ALMA note**

This value is “IEEE_LowEndian”

- **projectPath**, a string that identifies the data in the BLOB by execution block number, scan number and sub-scan number (see section 2 for a description of these strings).

The content of the sdmDataHeader element is composed of a sequence of the following eight elements.

**startTime**

The time at which the acquisition of the data in the BLOB was started, as an MJD value in nanoseconds.
The URI of the BLOB; may be used as a reference to the BLOB from the SDM. The element is empty (in the XML sense), and has the following attributes:

- xlink:type, which has a fixed value; "locator"
- xlink:href, the URI of the BLOB (the same as the top-level MIME X-uid header value); and
- xlink:title, a user-defined, descriptive name for the BLOB.

**EVLA WIDAR note**
The xlink:title attribute has a fixed value of “EVLA WIDAR Visibility Data”.

**ALMA note**
The xlink:title attribute has a values of “ALMA BL Correlator Spectral Data”, “ALMA BL Correlator Channel Average Data”, “ALMA ACA Correlator Spectral Data”, “ALMA ACA Correlator Channel Average Data”

### dimensionality or numTimes

The choice between these two elements depends on the data structure. The dimensionality element must be used for data streams that produce a sequence of subsets in a time series of data dumps. The use of the dimensionality element allows a BLOB to contain a structured hierarchy of data subsets. Alternatively, if the data acquired sequentially in time are blocked into chunks, with one chunk per subset, the numTimes element must be used.

When the data that are described by the main data header comprise a series of data subsets, the dimensionality element is applicable. In this case, the element specifies the axes along which the data subsets are ordered, with each axis corresponding to a level (or MIME multi-part section) in the high-level structure of the document.

When the data that are described by the main data header comprise a single data subset in which the data are ordered by time, the numTimes element is applicable. In this case, the element specifies the size of the time axis in the binary parts.

The dimensionality element has a single attribute:

- axes, the list of names of axes along which the data subsets are ordered (using AxisName enumeration values from Table 1).²

**EVLA WIDAR note**
For the EVLA WIDAR format (for sub-band cross- and auto-correlations), this element is fixed to be “<dimensionality axes='TIM'>1</dimensionality>”.

**ALMA note**
For the ALMA-B correlator format (for sub-band cross- and auto-correlations), this element is fixed to be “<dimensionality axes='TIM'>1</dimensionality>”.

The numTimes element has no attributes, and its content is an integer specifying the size along the TIM axis of the data in the binary parts.

² Note that, currently, only the TIM axis is supported by the known implementations of the format.
execBlock
Defines the execution block information for the data in the BLOB. It is the starting point of an outbound link to the execBlock SDM dataset. This element has the following attributes:

- xlink:href, the execution block URI is of the form: "uid://X1/2/3/4"; and
- xlink:type, which has a fixed value. "simple"

correlationMode
One of the two elements that defines the data structure (or format variant) of the BLOB; it is a required element. Its content is a value of the CorrelationMode enumeration type.

| EVLA WIDAR note | Content has fixed value of CROSS_AND_AUTO. |
| ALMA note       | Content can be AUTO_ONLY or CROSS_AND_AUTO. |

correlationMode
One of the two elements that defines the data structure (or format variant) of the BLOB; it is a required element. Its content is a value of the CorrelationMode enumeration type.

| EVLA note | Content has fixed value of FULL_RESOLUTION. |
| ALMA note | Content can be FULL_RESOLUTION or CHANNEL_AVERAGE |

dataStruct
Provides the description of the data structure. This element must be typed at the instance level by selecting a type in a type hierarchy. The range of element types is constrained by the context set primarily by the correlationMode element but also, for refinements, by the spectralResolution element.

The contents and attributes of this element depend on the type of the element (defined by the value of the required xsi:type attribute). In the following descriptions of all possible child elements and attributes of the dataStruct element notations of the context in which each may or must appear are provided.

There are two possible attributes of the dataStruct element:

- xsi:type, the type declaration; and
- apc, the AtmPhaseCorrection value(s) of the data on the APC axis (the attribute is present if and only if cross-correlations are in the data stream).

The value of the xsi:type attribute must be consistent with the type of the data stream in which the dataStruct element appears, as shown in Table 4.
Table 4: Values of dataStruct.xsi:type attribute as a function of data stream type.

<table>
<thead>
<tr>
<th>correlationMode</th>
<th>spectralResolution</th>
<th>CHANNEL_AVERAGE</th>
<th>BASEBAND_WIDE</th>
<th>undefined</th>
</tr>
</thead>
<tbody>
<tr>
<td>CROSS_ONLY</td>
<td>CrossDataFull-Resolution</td>
<td>CrossDataChannel-Average</td>
<td>N/A</td>
<td>CrossData</td>
</tr>
<tr>
<td>AUTO_ONLY</td>
<td>AutoDataFull-Resolution</td>
<td>AutoDataChannel-Average</td>
<td>AutoDataBaseband-Wide</td>
<td>AutoData</td>
</tr>
<tr>
<td>CROSS_AND_AUTO</td>
<td>CrossAndAutoDataFullResolution</td>
<td>CrossAndAutoData-ChannelAverage</td>
<td>N/A</td>
<td>CrossAndAutoData</td>
</tr>
</tbody>
</table>

**EVLA WIDAR note**
The EVLA WIDAR correlator data stream only uses the CrossAndAutoDataFullResolution type; the others may be ignored.

**ALMA note**
Data stream can be FULL_RESOLUTION: AutoDataFullResolution or CrossAndAutoDataFullResolution or CHANNEL_AVERAGE: AutoDataChannelAverage or CrossAndAutoDataChannelAverage. The ACA correlator

The allowed child elements are baseband, flags, actualTimes, actualDurations, crossData, autoData, zeroLags, and weights. The occurrence of these child elements may depend on the declared type of the dataStruct element; see the following sections for details.

**baseband**
A named group of spectral windows. At least one of these elements appears in every dataStruct element, and may appear multiple times. Each baseband element has a single attribute:

- name, the baseband name, a value of type BasebandName.

The content of a baseband element is a sequence of spectralWindow elements.

**spectralWindow**
Metadata describing the binary data structure for a spectral window. The element is empty, and the attributes that may appear depend on the type of the dataStruct element of which the spectralWindow is a descendant. The possible attributes, together with the context in which they may or must appear, are the following:

- numSpectralPoint, the number of spectral points (or channels) (i.e., length of the SPP axis), required;
- numBin, the number of bins (i.e., length of the BIN axis), required;
- crossPolProducts, the ordered list of polarization products produced for each cross-correlation (i.e., the StokesParameter names of the points on the POL axis);
- scaleFactor, the scaling factor for visibilities recorded as integers;
- sdPolProducts, the ordered list of polarization products produced for single dish data (i.e., the StokesParameter names of the points on the POL axis);
id, a unique identifier for the spectral window across all basebands whose value is of the form `spw_N` where `N` is an integer;

- `image`, for double sideband receivers, this identifies the `image` sideband of this spectral window whose value is of the form `spw_N` where `N` is an integer; and

- `sideband`, the sideband type whose value is of type `NetSideBand`, required.

**EVLA WIDAR note**

id and image are not used, and sideband always has the value NOSB.

**flags, actualTimes, actualDurations, crossData, autoData, zeroLags, weights**

Each of these elements provides metadata for the structure of binary components of a particular type in the BLOB. The associations of these elements with the types of binary components is given in section 5.4, and the table in the following section shows which of these elements may appear in a BLOB of a given of data stream type. Each of these elements has the following attributes:

- `size`, the maximum number of primitive data type values in the binary component within all data subsets (note that this number is not necessarily the number of elements in the component because two primitive data type values are used to represent a complex number); and

- `axes`, the list of axes for the binary component (as described in Section 5.3).

**flags**

Associated with FLAGS binary component. Attributes as shown above.

**actualTimes**

Associated with ACTUAL_TIMES binary component. Attributes as shown above.

**actualDurations**

Associated with ACTUAL_DURATIONS binary component. Attributes as shown above.

**crossData**

Associated with CROSS_DATA binary component. Attributes as shown above.

**autoData**

Associated with AUTO_DATA binary component. Attributes as shown above.

**zeroLags**

Associated with ZERO_LAGS binary component. Attributes as shown above.

**weights**

Associated with WEIGHTS binary component. Attributes as shown above. This element contains the lookup table for the data elements in the binary component. The size of the lookup table must be an integral power of two. The content of this element is the ordered list of lookup table values as single precision floating point numbers.

---

1 Whereas these elements with a main data header provide metadata for the binary components, the similarly named elements that exist within the subset data headers provide references to particular instances of the binary components for the given data subset.
6.1.1 Data stream dependencies

<table>
<thead>
<tr>
<th>correlationMode</th>
<th>spectralResolution</th>
</tr>
</thead>
<tbody>
<tr>
<td>FULL_RESOLUTION</td>
<td>CHANNEL_AVERAGE</td>
</tr>
</tbody>
</table>

| CROSS_ONLY       | crossData flags actualTimes actualDurations weights zeroLags | crossData flags actualTimes actualDurations weights |
| AUTO_ONLY        | autoData flags actualTimes actualDurations zeroLags          | autoData flags actualTimes actualDurations           |
| CROSS_AND_AUTO   | crossData autoData flags actualTimes actualDurations weights zeroLags | crossData autoData flags actualTimes actualDurations weights |

Table 5: Mandatory and optional header elements by data stream. Optional elements are italicized.

6.2 Data subset header

The data subset header appears once for every (sub-)integration in a binary format BLOB. The XML header element, `sdmDataSubsetHeader`, is also typed at the instance level, with the range of element types being determined by the data stream type.

The contents of this element depend on the type of the element, defined by the value of the required `xsi:type` attribute. The element has the following two attributes:

- `xsi:type`, the type declaration (required); and
- `projectPath`, a string that identifies the data in the (sub-)integration by execution block number, scan number, sub-scan number, integration number, and, if applicable, sub-integration number (see section 2) (required).

The value of the `xsi:type` attribute must be consistent with the type of the data stream in which the `dataRef` element appears, as shown below in Table 6.

<table>
<thead>
<tr>
<th>correlationMode</th>
<th>spectralResolution</th>
</tr>
</thead>
<tbody>
<tr>
<td>FULL_RESOLUTION</td>
<td>CHANNEL_AVERAGE</td>
</tr>
<tr>
<td>CROSS_ONLY</td>
<td>BinaryCrossDataFullResolution</td>
</tr>
<tr>
<td>AUTO_ONLY</td>
<td>BinaryAutoDataFullResolution</td>
</tr>
<tr>
<td>CROSS_AND_AUTO</td>
<td>BinaryCrossAndAutoDataFullResolution</td>
</tr>
</tbody>
</table>

Table 6: Values of `sdmDataSubsetHeader.xsi:type` attribute as a function of data stream type.
**EVLA WIDAR note**
The only type used by the EVLA WIDAR correlator is `BinaryCrossAndAutoDataFullResolution`; the others may be ignored.

**ALMA note**
ALMA correlators support `BinaryCrossAndAutoDataFullResolution, BinaryAutoDataFullResolution, BinaryCrossAndAutoDataChannelAverage, BinaryAutoDataChannelAverage`.

The content of the `sdmDataSubsetHeader` element is composed of a sequence of the following elements. The first two elements described below are required in all cases, whereas the remaining elements are mandatory, optional or excluded depending on the type of the data stream in which the `sdmDataSubsetHeader` element appears.

**schedulePeriodTime**
The scheduled time and duration of the time interval associated with the data in the current data subset, to be used as fallback metadata when the `ACTUAL_TIMES` and/or `ACTUAL_DURATIONS` binary components are absent from the data subset. These values are given by the content of the following two child elements of the `schedulePeriodTime` element:

- **time**
  the time at the midpoint of the interval, as an MJD value in nanoseconds; and

- **interval**
  the duration of the interval, in nanoseconds.

**dataStruct**
A reference to the main data header that describes the structure of the binary components in the current subset. The element itself is empty, but it has the following attribute:

- **ref**, a reference to the main data header (i.e., the `mainHeaderId` attribute value of the referenced element).

**abortObservation**
If a subscan is prematurely ended, this element appears together with the `schedulePeriodTime` and `dataStruct` elements as the only children of the `sdmDataSubsetHeader` element. No flags, `actualTimes`, `actualDurations`, `crossData`, `autoData`, `zeroLags`, or `weights` elements should exist in the same `sdmDataSubsetHeader` element with an `abortObservations` element. An `abortObservation` element is written anytime a subscan is aborted, i.e., by user intervention or by a detected software error. This element contains two required child elements:

- **stopTime**, the time at which the subscan is stopped. This time is as an MJD value in nanoseconds; and

- **reason**, a string providing a description of the reason for the aborted subscan.

The remaining seven child elements of the `sdmDataSubsetHeader` element provide the relative URIs of the binary components in the data subset. In all cases, the elements have the attribute `xlink:href`, which specifies the URI of the associated binary component (i.e., the `Content-Location` header value of the MIME part containing the binary component); any additional attributes are described below for each element individually.
flags
Provides the URI of the FLAGS binary component.

actualTimes
Provides the URI of the ACTUAL_TIMES binary component.

actualDurations
Provides the URI of the ACTUAL_DURATIONS binary component.

crossData
Provides the URI of the CROSS_DATA binary component. It has one additional required attribute:

- **type**, the primitive data type used to represent the cross-correlation data in the referenced binary component. Its value is one of the following *PrimitiveDataType* enumeration values: SHORT_TYPE, LONG_TYPE, INT16_TYPE, INT32_TYPE, FLOAT32_TYPE.

ALMA note
Currently, ALMA only supports SHORT_TYPE and LONG_TYPE.

autoData
Provides the URI of the AUTO_DATA binary component.

zeroLags
Provides the URI of the ZERO_LAGS binary component.

weights
Provides the URI of the WEIGHTS binary component.
7 Appendices

7.1 XML schemata

XML schemata for the binary data format may be found in the same repository and project under which the master copy of the present document exists.

REPOSITORY ACCESS INSTRUCTIONS GO HERE

7.2 MIME format example

MIME-Version:1.0
Content-Type: multipart/mixed; boundary="ABCDE01234"; type="text/xml"
Content-Description: EVLA/CORRELATOR/WIDAR/FULL_RESOLUTION
Content-Location: uid://X1/2/3/4

--ABCDE01234
Content-Type: text/xml; charset="UTF-8"
Content-Transfer-Encoding: 8bit
Content-Location: sdmDataHeader.xml

[MAIN DATA HEADER]

--ABCDE01234
Content-type: multipart/related; boundary="abcd";type="text/xml";
Content-description: data and metadata subset

--abcd
Content-Type: text/xml; charset="UTF-8"
Content-Location: 1/10/3/1/desc.xml

[DATA_SUBSET HEADER]

--abcd
Content-Type: application/octet-stream
Content-Location: 1/10/3/1/actualTimes.bin

[ACTUAL_TIMES binary data]

--abcd
Content-Type: application/octet-stream
Content-Location: 1/10/3/1/actualDurations.bin

[ACTUAL_DURATIONS binary data ]

--abcd
...
--abcd--

--ABCDE01234
Content-type: multipart/relate; boundary="efgh"
Content-description: data subset

--efgh
Content-Type: text/xml; charset="UTF-8"
Content-Location: 1/10/3/2/desc.xml

[DATA_SUBSET HEADER]

--efgh
Content-Type: application/octet-stream
Content-Location: 1/10/3/2/actualTimes.bin

[ACTUAL_TIMES binary data]

--efgh
...
--efgh--
--ABCDE01234--
7.3 Schematic representation of times

Data blanking implies that part or all of the data in an integration is ignored. This affects the actual times and durations of the integration. The following diagram schematically presents how actual times and durations for a baseline are determined.

7.4 ALMA implementation details

7.4.1 Spectral data stream

7.4.1.1 Binary component sizes

Here we discuss the sizes of the binary attachments in bytes. The number of basebands, \( N_{bb} \), corresponds to the number of baseband nodes in the sequences; the number of spectral windows per baseband, \( N_{sw} \), corresponds to the number of spectral window nodes, children of a baseband node. These are defined as sequences in the schema with the XML header setting the actual order of the data given common to all baselines.

In the formulas used to determine the size of the arrays, one must take into account the following possible cases as indicated by the value of the SDM item, \( correlationMode \):

- \( N_{ant} = 0 \) and \( N_{bl} > 0 \) if \( correlationMode = CROSS ONLY \)
- \( N_{ant} > 0 \) and \( N_{bl} = 0 \) if \( correlationMode = AUTO ONLY \)
- \( N_{ant} > 0 \) and \( N_{bl} > 0 \) if \( correlationMode = CROSS AND AUTO \)
When the $\text{correlationMode} = \text{CROSS\_AND\_AUTO}$, the number of polarization products, $N_{pp}^{\alpha}$, may not be the same for the auto-correlation (single-dish) and cross-correlation (interferometric) data. For this reason, a superscript is added. $N_{pp}^{\alpha}$ is used for the auto-correlation data and $N_{pp}^{oo}$ for the cross-correlation data. The following constraints apply:

- if $\text{correlationMode} = \text{CROSS\_ONLY}$: $N_{pp}^{oo} = 1, 2, \text{ or } 4$ and $N_{pp}^{\alpha}$ is undefined
- if $\text{correlationMode} = \text{AUTO\_ONLY}$: $N_{pp}^{oo}$ is undefined and $N_{pp}^{\alpha}$ is 1, 2, or 3
- if $\text{correlationMode} = \text{CROSS\_AND\_AUTO}$: $N_{pp}^{oo} = 1, 2, \text{ or } 4$ and

$$N_{pp}^{\alpha} = \begin{cases} 
N_{pp}^{\alpha}, & \text{if } N_{pp}^{oo} \leq 2 \\
3, & \text{if } N_{pp}^{oo} = 4 \text{ (standard mode)} \\
2, & \text{if } N_{pp}^{oo} = 4 \text{ (non-standard mode)}
\end{cases}$$

Note that when $N_{pp}^{oo} = 3$, the data are in a set of two real values plus a complex value for the polarization cross products. Else, when $N_{pp}^{oo} \leq 2$, the data consist of $N_{pp}^{\alpha}$ real values.

The term $N_{apc}$ derives from the sequence of SDM enumerations: $\text{AP\_UNCORRECTED}$, $\text{AP\_CORRECTED}$, or $\text{AP\_MIXED}$. $N_{apc}$ is simply the number of items in this sequence.

**Error! Bookmark not defined.FLAGS**

These data are long unsigned 32-bit integers and are antenna based. The number of elements is computed as such:

$$N_{\text{act}} \sum_{i=1}^{N_{\text{bin}}} N_{\text{bin}}(i) N_{pp}^{\alpha}(i)$$

**ACTUAL\_TIMES**

The size of the actual integration time stamp (centroid) for each baseline, bin, polarization product, and baseband. This is the intersection of the 2 antennas (self or cross) of a baseline taking into account any gaps due to blanking in either antenna. The number of elements is computed as such:

$$N_{\text{bt}} \sum_{i=1}^{N_{\text{hh}}} N_{\text{bin}}(i) N_{pp}^{oo}(i) + N_{\text{ant}} \sum_{i=1}^{N_{\text{hh}}} N_{\text{bin}}(i) N_{pp}^{\alpha}(i)$$

**ACTUAL\_DURATIONS**

The actual integration duration (exposure) for each baseline, bin, polarization product, and baseband. This is the intersection of the 2 antennas of a baseline taking into account any gaps due to blanking in either antenna. The number of elements is computed as such:

$$N_{\text{bt}} \sum_{i=1}^{N_{\text{hh}}} N_{\text{bin}}(i) N_{pp}^{oo}(i) + N_{\text{ant}} \sum_{i=1}^{N_{\text{hh}}} N_{\text{bin}}(i) N_{pp}^{\alpha}(i)$$

**ZERO\_LAGS**
The size of the zero lag values for each antenna, spectral window, polarization product and baseband. The number of elements is computed as such:

\[ N_{\text{ant}} \sum_{i=1}^{N_{\text{bin}}(i)} N_{\text{sw}}(i) f(N_{\text{pp}})(i) \]

with

\[ f(N_{\text{pp}}) = \begin{cases} 
1 & \text{if } N_{\text{pp}}^o(i) = 1 \text{ or } N_{\text{pp}}^{oo}(i) = 1 \\
2 & \text{if } N_{\text{pp}}^o(i) > 1 \text{ or } N_{\text{pp}}^{oo}(i) > 1 
\end{cases} \]

**CROSS_DATA**

The size of the cross correlation spectral data for each cross baseline, spectral window, polarization product, bin, and baseband. These data are complex values. The number of elements is computed as such:

\[ 2 \times N_{\text{ant}} \sum_{i=1}^{N_{\text{bb}}} \left( N_{\text{bin}}(i) N_{\text{pp}}^{oo}(i) \sum_{j=1}^{N_{\text{sp}}}(j) \right) \]

where a factor of 2 is due to complex visibilities.

**AUTO_DATA**

The size of the auto correlation spectral data. Note that the data can be a mixture of real and complex values due to the cross polarization products when using full polarization. The number of elements is computed as such:

\[ N_{\text{ant}} \sum_{i=1}^{N_{\text{bb}}} \left( N_{\text{bin}}(i) f(N_{\text{pp}})(i) \sum_{j=1}^{N_{\text{sp}}}(j) \right) \]

where for pure auto-correlation data, i.e., \texttt{correlationMode = AUTO ONLY}

\[ f(N_{\text{pp}})(i) = \begin{cases} 
N_{\text{pp}}^{oo}(i), & \text{if } N_{\text{pp}}^o(i) \leq 2 \\
4, & \text{if } N_{\text{pp}}^o(i) = 3 
\end{cases} \]

and for \texttt{correlationMode = CROSS_AND_AUTO}

\[ f(N_{\text{pp}})(i) = \begin{cases} 
N_{\text{pp}}^{oo}(i), & \text{if } N_{\text{pp}}^{oo}(i) \leq 2 \text{ (i.e. } 1 \text{ re if } N_{\text{pp}}^{oo}(i) = 1, 2 \text{ re if } N_{\text{pp}}^{oo}(i) = 2) \\
N_{\text{pp}}^{oo}(i), & \text{if } N_{\text{pp}}^{oo}(i) = 4 \text{ (i.e. } 3 \text{ re } + 1 \text{ im, standard mode}) \\
2, & \text{if } N_{\text{pp}}^{oo}(i) = 2 \text{ (i.e. } 2 \text{ re, non-standard mode}) 
\end{cases} \]

Note that in order to support the non-standard mode case, one needs to add a boolean item to the SDM and to the XML header - This is currently a TBD item.

<table>
<thead>
<tr>
<th>Binary component</th>
<th>Data type</th>
<th>Data Size</th>
<th>Min. Quantity</th>
<th>Max. Quantity (size in bytes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FLAGS</td>
<td>unsigned long integer</td>
<td>4</td>
<td>1</td>
<td>(4) 133,120 (532,480)</td>
</tr>
<tr>
<td>ACTUAL_TIMES</td>
<td>SDM::Time</td>
<td>8</td>
<td>1</td>
<td>(8) 133,120 (1,064,960)</td>
</tr>
<tr>
<td>ACTUAL_DURATIONS</td>
<td>SDM::Time</td>
<td>8</td>
<td>1</td>
<td>(8) 133,120 (1,064,960)</td>
</tr>
<tr>
<td>ZERO_LAGS</td>
<td>float</td>
<td>4</td>
<td>1</td>
<td>(4) 131,072 (524,288)</td>
</tr>
<tr>
<td>Binary component</td>
<td>Data type</td>
<td>Data Size</td>
<td>Min. Quantity</td>
<td>Max. Quantity (size in bytes)</td>
</tr>
<tr>
<td>-------------------</td>
<td>-------------------------</td>
<td>-----------</td>
<td>---------------</td>
<td>-----------------------------</td>
</tr>
<tr>
<td>CROSS_DATA</td>
<td>scaled short/long integer</td>
<td>2/4</td>
<td>0 (0)</td>
<td>1,056,964,608 (4,227,858,432)</td>
</tr>
<tr>
<td>AUTO_DATA</td>
<td>float</td>
<td>4</td>
<td>256 (1024)</td>
<td>8,388,608 (33,554,432)</td>
</tr>
<tr>
<td>Total size in bytes</td>
<td></td>
<td></td>
<td>1,048</td>
<td>~4 GB (4,264,599,552)</td>
</tr>
</tbody>
</table>

### 7.4.1.2 Example of Full Resolution Data

```xml
<MIME-Version: 1.0
Content-Type: multipart/mixed; boundary="MIME_boundary-1"; type="text/xml";
Content-Description: ALMA/CORRELATOR/ALMA_BASELINE/FULL_RESOLUTION
Content-Location: uid://X1/1/0/0
--MIME_boundary-1
Content-Type: text/xml; charset="UTF-8"
Content-Transfer-Encoding: 8bit
Content-Location: sdmDataHeader.xml

<?xml version="1.0" encoding="UTF-8"?>
<sdmDataHeader
  xmlns="http://TBD/XSDM/sdmbin"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xlink="http://www.w3.org/1999/xlink"
  xmlns:xvers="http://TBD/XVERSION"
  xsi:schemaLocation="http://TBD/XSDM/sdmbin 0/sdmDataObject.xsd"
  xvers:schemaVersion="0"
  xvers:revision="0.0.96"
  mainHeaderId="sdmDataHeader"
  byteOrder="IEEE_Low_Endian"
  projectPath="3/1/2/">
  <startTime>4647257068000000000</startTime>
  <dataOID xlink:type="locator"
    xlink:href="uid://X1/1/0/0"
    xlink:title="ALMA BL Correlator Spectral Data"/>
  <dimensionality axes="TIM">1</dimensionality>
  <execBlock xlink:href="uid://X1/1/0/1" xlink:type="simple"/>
  <numAntenna>2</numAntenna>
  <correlationMode>CROSS_AND_AUTO</correlationMode>
  <spectralResolution>FULL_RESOLUTION</spectralResolution>
```
7.4.1.3 Data rate

The quantity of correlator spectral data can vary greatly. A minimal header and data for a single antenna is about 2 KB. For all 64 antennas the data can extend to over 2 GB for all four basebands. With an integration period of 1 second this exceeds the SSR-specified maximum peak data rates, consequently the SSR values of 6 MB/sec average and 60 MB/sec peak are used.

7.4.2 Channel average data stream

7.4.2.1 Binary component sizes

FLAGS

These data are long unsigned integers. The number of elements is computed as such:

\[ N_{\text{bl}} \sum_{i=1}^{N_{\text{bl}}} N_{\text{bin}}(i) N_{pp}^{00}(i) + N_{\text{ant}} \sum_{i=1}^{N_{\text{ant}}} N_{\text{bin}}(i) N_{pp}^{0}(i) \]

ACTUAL_TIMES

The size of the actual sub-integration time stamp (centroid) for each baseline, bin, polarization product, and baseband taking into account any blanking, see appendix Error! Reference source not found. for details. The number of elements is computed as such:

\[ N_{\text{bl}} \sum_{i=1}^{N_{\text{bl}}} N_{\text{bin}}(i) N_{pp}^{00}(i) + N_{\text{ant}} \sum_{i=1}^{N_{\text{ant}}} N_{\text{bin}}(i) N_{pp}^{0}(i) \]

ACTUAL_DURATIONS

The actual sub-integration duration (exposure) for each baseline, bin, polarization product, and baseband. This is the intersection of the 2 antennas of a baseline taking into account any gaps due to blanking in either antenna. Error! Reference source not found. The number of elements is computed as such:

\[ N_{\text{bl}} \sum_{i=1}^{N_{\text{bl}}} N_{\text{bin}}(i) N_{pp}^{00}(i) + N_{\text{ant}} \sum_{i=1}^{N_{\text{ant}}} N_{\text{bin}}(i) N_{pp}^{0}(i) \]

CROSS_DATA
The size of the cross correlation channel averages. These data are complex values. The number of elements is computed as such:

\[ 2 \times N_{bi} \sum_{i=1}^{N_{bi}} \left( N_{bin} N_{pp}^0 (i) \sum_{j=1}^{N_{pp}} N_{sp} (j) \right) \]

where a factor of 2 is due to complex visibilities.

**AUTO_DATA**

The size of the auto correlation channel averages. Note that the data can be a mixture of real and complex values due to the cross polarization products when using full polarization. The number of elements is computed by the following formula. For full polarization:

\[ N_{ant} \sum_{i=1}^{N_{bh}} \left( N_{bin} f\left( N_{pp}^0 (i) \right) \sum_{j=1}^{N_{pp}} N_{sp} (j) \right) \]

where for pure auto-correlation data, i.e., \( \text{correlationMode} = \text{AUTOONLY} \)

\[ f\left( N_{pp}^0 (i) \right) = \begin{cases} 
N_{pp}^0 (i) & \text{if } N_{pp}^0 (i) \leq 2 \\
4 & \text{if } N_{pp}^0 (i) = 3
\end{cases} \]

and for \( \text{correlationMode} = \text{AUTO_AND_CROSS} \)

\[ f\left( N_{pp} (i) \right) = \begin{cases} 
N_{pp}^0 (i) & \text{if } N_{pp}^0 (i) \leq 2 \text{ (i.e. } 1 \text{ re if } N_{pp}^0 (i) = 1, 2 \text{ re if } N_{pp}^0 (i) = 2) \\
N_{pp}^0 (i) & \text{if } N_{pp}^0 (i) = 4 \text{ (i.e. } 3 \text{ re + 1 im, standard mode)} \\
2 & \text{if } N_{pp}^0 (i) = 2 \text{ (i.e. } 2 \text{ re, non-standard mode)}
\end{cases} \]

Using these mapping rules and the header information, the sizes of data are shown in the following table with the number of bytes is shown in parentheses.

<table>
<thead>
<tr>
<th>Binary component</th>
<th>Data type</th>
<th>Data Size</th>
<th>Min. Quantity</th>
<th>Max. Quantity (size in bytes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FLAGS</td>
<td>Unsigned long integer</td>
<td>4</td>
<td>1</td>
<td>133,120 (532,480)</td>
</tr>
<tr>
<td>ACTUAL_TIMES</td>
<td>SDM::Time</td>
<td>8</td>
<td>1</td>
<td>133,120 (1,064,960)</td>
</tr>
<tr>
<td>ACTUAL_DURATIONS</td>
<td>SDM::Time</td>
<td>8</td>
<td>1</td>
<td>133,120 (1,064,960)</td>
</tr>
<tr>
<td>CROSS_DATA</td>
<td>scaled short / integer</td>
<td>2/4</td>
<td>0</td>
<td>20,643,840 (82,575,360)</td>
</tr>
<tr>
<td>AUTO_DATA</td>
<td>float</td>
<td>4</td>
<td>1</td>
<td>327,680 (1,310,720)</td>
</tr>
<tr>
<td>Total sizes</td>
<td></td>
<td>4</td>
<td>24</td>
<td>(~86 MB) (86,548,480)</td>
</tr>
</tbody>
</table>

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7.4.2.2 Example of Channel Average Data

MIME-Version: 1.0
Content-Type: multipart/mixed; boundary="MIME_boundary-1"; type="text/xml";
Content-Description: ALMA/CORRELATOR/ALMA_BASELINE/CHANNEL_AVERAGE
Content-Location: uid://X1/1/0/0

--MIME_boundary-1
Content-Type: text/xml; charset="UTF-8"
Content-Transfer-Encoding: 8bit
Content-Location: sdmDataHeader.xml

<?xml version="1.0" encoding="UTF-8"?>
<sdmDataHeader xmlns="http://TBD/XSDM/sdmbin"
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xmlns:xlink="http://www.w3.org/1999/xlink"
xmns:xvers="http://TBD/XVERSION"
xsi:schemaLocation="http://TBD/XSDM/sdmBinXSD/0/sdmDataObject.xsd"
xvers:schemaVersion="0"
xvers:revision="0.0.96"
mainHeaderId="sdmDataHeader"
byteOrder="IEEE_Low_Endian"
projectPath="3/1/2/"
<startTime>4647257068000000000</startTime>
<dataOID xlink:type="locator" xlink:href="uid://X1/1/0/0" xlink:title="ALMA BL Correlator Channel Average Data"/>
<dimensionality axes="TIM">1</dimensionality>
<execBlock xlink:href="uid://X1/1/0/1" xlink:type="simple"/>
<numAntenna>2</numAntenna>
<correlationMode>CROSS_AND_AUTO</correlationMode>
<spectralResolutionΧref="CHANNEL_AVERAGE"/>
<dataStruct xsi:type="CrossAndAutoDataChannelAverage" apc="AP_UNCORRECTED"/>
<baseband name="BB_1">
<spectralWindow id="spw_1" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="7" numBin="1"/>
<spectralWindow id="spw_2" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="7" numBin="1"/>
<spectralWindow id="spw_3" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="7" numBin="1"/>
<spectralWindow id="spw_4" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="7" numBin="1"/>
</baseband>
<baseband name="BB_3">
<spectralWindow id="spw_5" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="8" numBin="1"/>
<spectralWindow id="spw_6" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="8" numBin="1"/>
<spectralWindow id="spw_7" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="8" numBin="1"/>
<spectralWindow id="spw_8" sdPolProducts="XX" crossPolProducts="XX"
scaleFactor="3225.523213" numSpectralPoint="8" numBin="1"/>
</baseband>
<flags size="6" axes="BAL ANT BAB"/>
<actualTimes size="6" axes="BAL ANT BAB"/>
<actualDurations size="6" axes="BAL ANT BAB"/>
<crossData size="112" axes="BAL BAB SPW SPP"/>
<autoData size="112" axes="ANT BAB SPW SPP"/>
</dataStruct>
</sdmDataHeader>
--MIME_boundary-1
Content-Type: multipart/related; boundary="MIME_boundary-2"; type="text/xml";
Content-Description: data and metadata subset
--MIME_boundary-2
Content-Type: text/xml; charset="UTF-8"
Content-Location: 3/1/2/1/1/desc.xml
<sdmDataSubsetHeader xsi:type="BinaryCrossAndAutoDataChannelAverage"
projectPath="3/1/2/1/1/">
  <schedulePeriodTime>
    <time>4647257062560000000</time>
    <interval>512000000</interval>
  </schedulePeriodTime>
  <dataStruct ref="sdmDataHeader"/>
  <flags xlink:href="3/1/2/1/1/flags.bin"/>
  <actualTimes xlink:href="3/1/2/1/1/actualTimes.bin"/>
  <actualDurations xlink:href="3/1/2/1/1/actualDurations.bin"/>
  <crossData xlink:href="3/1/2/1/1/crossData.bin" type="SHORT_TYPE"/>
  <autoData xlink:href="3/1/2/1/1/autoData.bin"/>
</sdmDataSubsetHeader>
--MIME_boundary-2
Content-Type: application/octet-stream
Content-Location: 3/1/2/1/1/flags.bin
[BINARY DATA HERE]
--MIME_boundary-2
Content-Type: application/octet-stream
Content-Location: 3/1/2/1/1/actualTimes.bin
[BINARY DATA HERE]
--MIME_boundary-2
Content-Type: application/octet-stream
Content-Location: 3/1/2/1/1/actualDurations.bin
[BINARY DATA HERE]
--MIME_boundary-2
Content-Type: application/octet-stream
Content-Location: 3/1/2/1/1/crossData.bin
[BINARY DATA HERE]
--MIME_boundary-2
Content-Type: application/octet-stream
Content-Location: 3/1/2/1/1/autoData.bin
[BINARY DATA HERE]
--MIME_boundary-2--
--MIME_boundary-1--
7.4.2.3 Data rate

Assume that the channel average integration header is ~2KB bytes. Note that the size of the channel data in the maximum case can be huge. This, of course, violates the maximum data rate specified by the SSR. A typical maximum rate would be ~500KB per sub-integration interval.

<table>
<thead>
<tr>
<th>Data Description</th>
<th>Data Quantity (bytes)</th>
<th>Instances per transmission</th>
<th>Transmission Interval (seconds)</th>
<th>Data Rate (average/peak)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Channel Aver. Bulk Data (1 antenna)</td>
<td>2KB</td>
<td>1</td>
<td>0.5</td>
<td>2/4 KB/sec</td>
</tr>
<tr>
<td>Channel Aver. Bulk Data (64 antennas)</td>
<td>11 MB</td>
<td>1</td>
<td>0.5</td>
<td>11/22 MB/sec</td>
</tr>
</tbody>
</table>

*Table 7 - Channel average data flow*

7.4.3 Data capture information

After each subscan, a CORBA binary structure is sent to the Data Capture component for a given subarray. This structure contains identifiers from Control and run-time information from Control and Correlator.

The function is defined in ICD/OFFLINE/idl/DataCapture.idl as:

```cpp
void sendSubScanCorrelatorData( in string arrayId,
                                in Correlator::subScanCorrelatorData subScanData )
raises( DataCaptureExceptions::DataErrorEx, DataCaptureExceptions::TableUpdateErrorEx);
```

Where *Correlator::subScanCorrelatorData* is defined in ICD/CORR/ws/idl/CorrDataCapture.idl as

```cpp
struct SubScanCorrelatorData {
    long totalIntegrations;
    long numberSubIntegrationsPerIntegration;
    boolean flagRowIntegrations;
    boolean flagRowSubIntegrations;
};
```

The SDM has one row in the table for all integrations and one row for all sub-integrations. Thus we need to send the total number of integrations in the subscan and the total number of sub-integrations in each integration. Finally a row flag for the integrations and sub-integrations. Note that the data OIDs are delivered to DataCapture via the Control subsystem at the beginning of a subscan.

The data items produced by the correlator are:

- **totalIntegrations**, the total number of integrations in the subscan
- **numberSubIntegrationsPerIntegration**, the total number of sub-integrations in each integration
- **flagRowIntegrations**, general flag set by correlator to flag entire row of integrations with TRUE = 'bad', FALSE = 'good'.
- **flagRowSubIntegrations**, general flag set by correlator to flag entire row of sub-integrations with. TRUE = 'bad', FALSE = 'good'.

Data flow rates are minimal as at most four sets of SubScanCorrelatorData would be sent simultaneously at the end of each subscan resulting in tens of bytes per second.
7.4.4 Data transmission
This section describes how data will be transferred from the CDP master computer which organizes the binary data to the Archive and other data receivers.

7.4.4.1 Overview
The general approach is that for each subscan, the CDP master sends `startSend()` and `send()` commands to the BulkData Distributor which contains header information regarding all of the data to be sent in the subscan. At each integration, the CDP master sends the SDM subset headers and binary data via the `send()` command. At the end of the subscan, the CDP master sends a `stopSend()` command signaling the receiver that no more data is coming for this subscan. The current design has a separate pair of flows per subarray, one for the integrations and one for the sub-integrations. Throughout this discussion, the term “sub-integration” can replace “integration”.

7.4.4.2 Subscan start
When a `startSubScan()` command is received by the CDP master, it constructs the SDM data header and calculates the maximum expected data size of text and binary data. This header information is sent via the `startSend()` and `send()`. Note that the actual data may be less than the maximum due to the baselineFlags, actualTimes, and actualDuration attachments not being sent.

7.4.4.3 Sending data
For each integration, the CDP master sends integration subset data as currently defined.

7.4.4.4 Subscan end
At the end of a subscan, the CDP master invokes the `stopSend()` function which signals the receivers that no more binary data for this subscan will be sent. Note that the `stopSend()` function is sent even if the subscan is ended prematurely, i.e., before the expected number of bytes defined in the `startSend()` function are sent. The CDP master also invokes the `sendSubScanCorrelatorData()` function on the DataCapturer.
7.5  **EVLA WIDAR implementation**

7.5.1 **Data stream example**

No example is available yet. One will appear in this section shortly after the WIDAR backend software is capable of producing a file in the BDF format.

7.5.2 **Data rates**

TBD
7.6 References


[RFC2557] J. Palme, A. Hopmann, N. Shelness, “MIME Encapsulation of Aggregate Documents, such as HTML (MHTML)”, IETF RFC 2557, March 1999