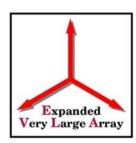


CMP: Control Monitor Processor

Hichem Ben Frej Kevin Ryan



Introduction

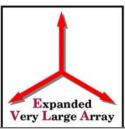


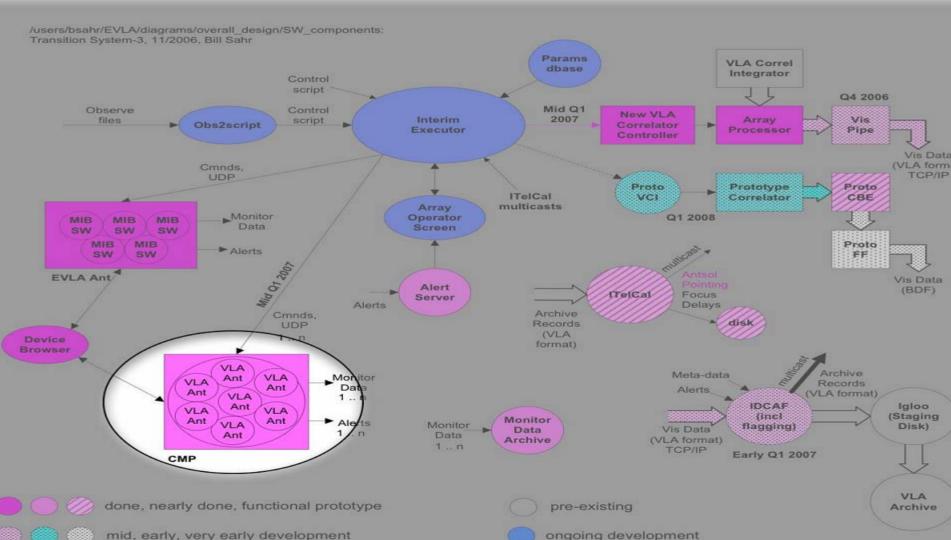
• What is the CMP?

- Monitor & Control the VLA antennas through the EVLA M&C.
- Real Time Monitor & Control System.
- Temporary system during the transition period from VLA to EVLA.
- Lasts as long as the VLA correlator is in use
 - To control the D-Racks, Flukes and other devices in the control building
- It is an important part of the MODCOMP retirement plan.
- A unified interface for the EVLA M&C.
 - A similar behavior and interface to the MIBs



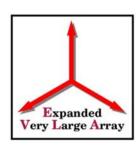
Place in the System







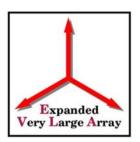
Terminology

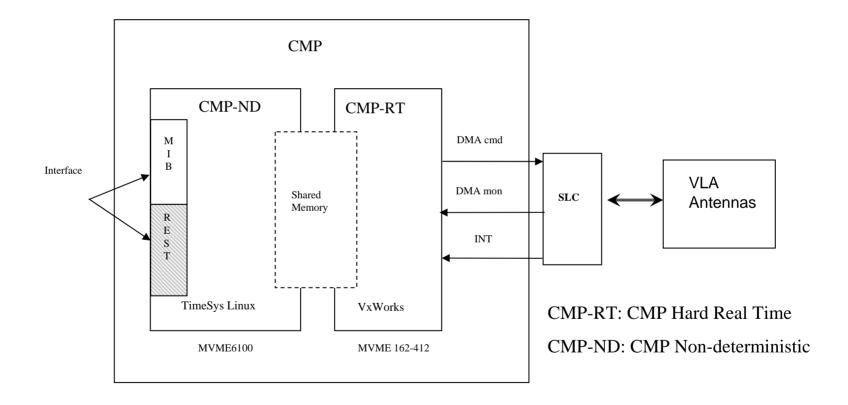


- DCS#: Digital Control System.
 - DCS addresses are associated with "D"-Rack physical location sequenced from 1 through 33₈ starting with "D"-Rack 1 on the southwest arm of "D"-Racks.
- SLC: Serial Line Controller.
- DMA: Direct Memory Access
- ISR: Interrupt Service Routine. Code that get executed when an interrupt is triggered.
- COTS: commercial off-the-shelf.



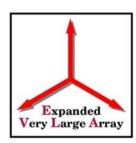
CMP Architecture

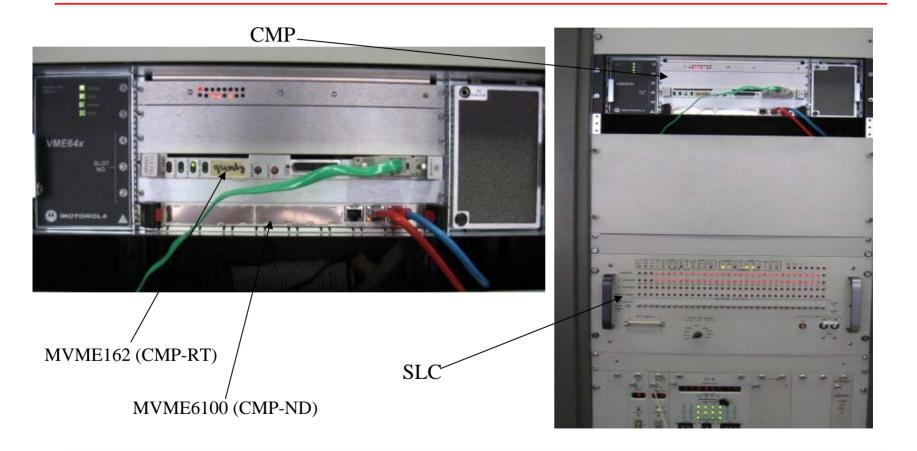






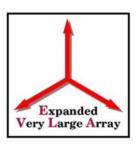
Picture







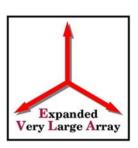
CMP Hardware



- CMP is a cooperation of 2 COTS VME boards:
 - A MVME 162-412 board running VxWorks 5.3
 - 25MHz MC68LC040
 - 4MB of RAM
 - 2 IP-Unidig-P cards used to DMA in & out data.
 - CIO-32 card to intercept interrupts
 - Talks to the SLC (Serial Line Controller)
 - Synchronized with the Wave Guide Cycle
 - Handles all deterministic and real time operations.



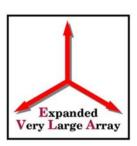
CMP HW (cont')



- A MVME6100 board, running Real Time Linux from TimeSys.
 - 1.267 GHz MPC7457 PowerPC
 - 1GB DDR memory
 - 128MB Flash
 - Dual Gigabit Ethernet
- The two boards communicate through a shared memory
 - The MVME 162-412 is mapped to the memory of the MVME6100 board which makes all of it accessible.



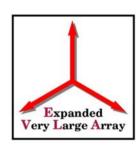
CMP Software Characteristics

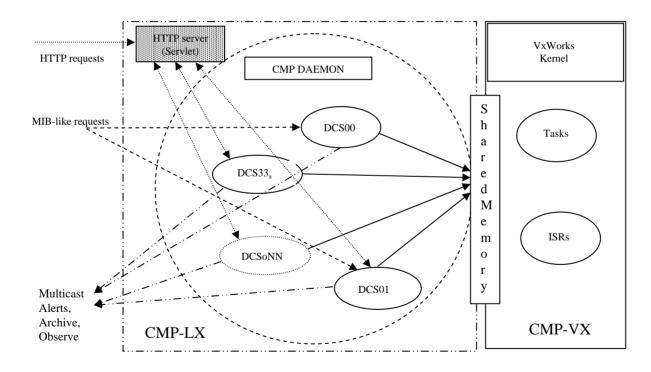


- Hide all the details (DS and MUX) from the high level user/application: the CMP is in charge of mapping properties, commands with the right DS and MUXs.
- To be able to sequence deferred commands internally.
- Execute deferred commands in sync with the Waveguide cycle.
- Present a similar interface to the MIB
 - Service Port
 - Data Port.
 - Telnet interface
 - Multicasting Data & alerts
- Each DCS# is addressed & managed independently



Software Architecture

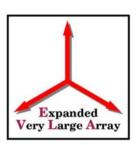


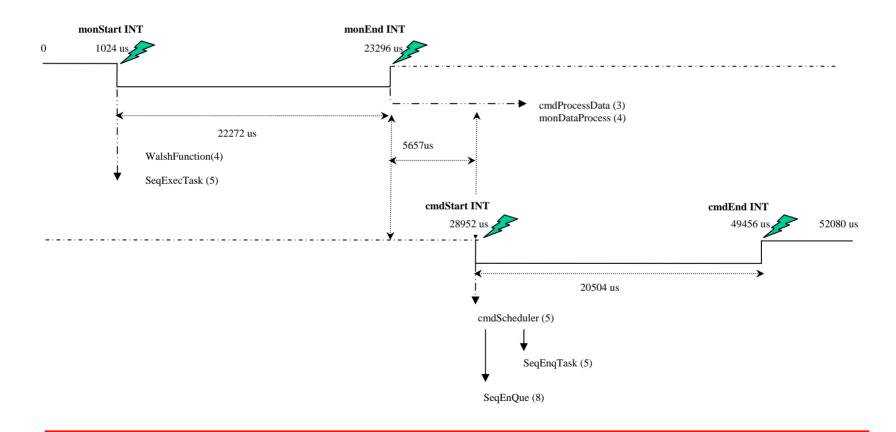


CMP = Set of Virtual Antennas



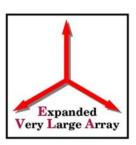
HW Interrupts/ISRs/Tasks







Software - CMP VxWorks

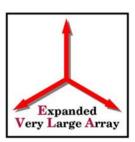


ISRs: Respond to interrupts from the SLC

- isrMonitorStart: triggered by an interrupt at Start Monitor Cycle
 - Sets the DMA engines to transfer the data from the SLC to the board memory
 - Prepares the system for the End Monitor event.
- isrMonitorEnd: triggered by an interrupt at End Monitor Cycle
 - Verifies the DMA transfer of monitor data
 - Prepares the system for next Monitor Cycle.
- isrCommandStart: triggered by an interrupt at Start Command Cycle
 - Sets up the DMA engine to start the transfer of commands from the board's memory to the SLC.
 - Prepares the system for the End Command event.
- isrCommandEnd: triggered by an interrupt at End Command Cycle
 - Verifies the integrity of the DMA transfer of commands
 - Prepares the system for the next Command cycle.



Software - CMP VxWorks



Tasks:

- Sequencer
 - Queues commands internally for execution in sync with the waveguide cycle.
- ACU function
 - Takes care of doing all the calculation and update for the ACU unit
- Walsh function
 - Used to inject the Walsh sequence
- Data collection
 - Once data is ready, signaled by the SLC, data is processed and presented to the higher board
- Commands collection
 - Prepares commands in a buffer for the DMA transfer
- Shared memory worker
 - Collects commands from the shared memory and executes them or passes them to the sequencer
- Watchdog Timer:
 - if this task fails to run within a 2 seconds interval, a reset signal is issued and both boards are reset.
- TimeKeeper:
 - Keeps the time in sync with the NTP time server.



Software - CMP Linux



Main function

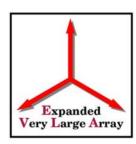
 Public interface, including multicasting the archive, observing stream (o-stream) and alerts data, accepts command input and handles any non deterministic operations.

IP aliasing

- Assign multiple IP addresses to the same physical interface.
- Every DCS# can have it's own IP address.
- Every DCS# is addressed individually & independently



Software - CMP Linux



Multithreaded design and implementation

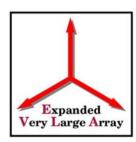
- Every DCS# is managed by an independent thread
- The interface to a DCS# is very similar to the MIB interface and includes
 - Data port
 - Service port
 - Telnet interface
 - Archive data stream
 - Observing data stream (o-stream)
 - Alerts.

• Entry point: CMPdaemon

- Spawns a thread for every managed DCS#
- Acts as supervisor to watch for the health of the threads and the system
- Offers a diagnostic interface.



Software - CMP Linux

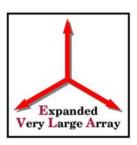


Tasks

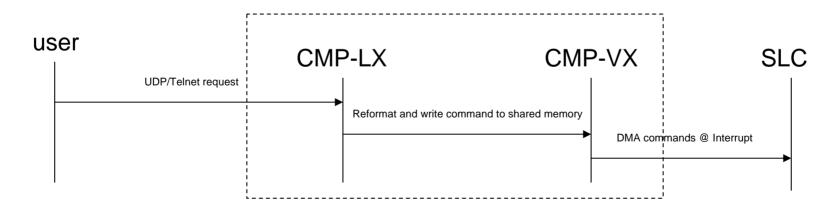
- Archive
 - Takes care of multicasting archive, observing stream (o-stream) data
- Service port
 - Listens for incoming commands and schedule them for execution.
- Telnet
 - Listens for Telnet requests and handles them
- Periodic scan Task
 - Collects data from the shared memory and makes it ready for the others tasks.



Commands Path

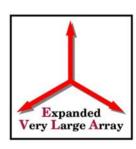


- Commands initiated from user through Telnet session or UDP port
- Received on CMP board running Linux. If the command is not internal to the CMP, reformat and write to shared memory.
- A task running on VxWorks periodically checks the shared memory for new commands.
- If new command present, check for immediate execution or to be sequenced. If immediate, execute. Otherwise, pass to the sequencer task.
- CMP-VX interrupted at the start of command cycle => DMA commands to the SLC.

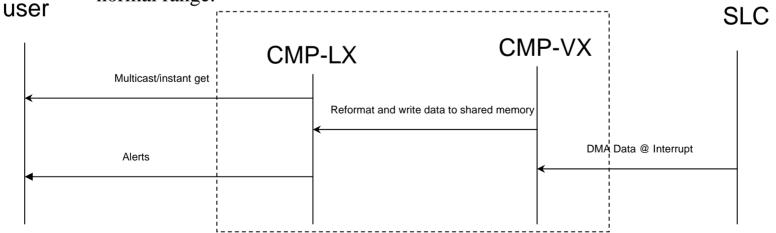




Data Path

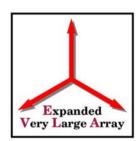


- Data collected every Waveguide Cycle (52 ms)
- CMP is interrupted every 52 ms to receive the data from the SLC
- Data is DMAed, formatted, and saved in shared memory
- The Scan task running on CMP-LX, collects the data from the shared memory
- The Archive task multicasts the data
- Alert task goes through the data and generates alerts for any data outside the normal range.





Testing & Deployment

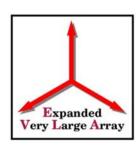


Testing

- Phase 1: done on the test bench.
 - Test and verify the interface and communication with higher level application/users.
 - Stability testing
 - Stress testing
 - Performance measurement.
- Phase 2: done @ the VLA site
 - Test and verify the CMP-SLC-antennas communication.
 - Test and verify the data collection process.
 - Test and verify the commands path.
 - Test and verify the complete path from the high level applications /users to the antennas and vise-versa.
 - Test and verify the timing and synchronization.



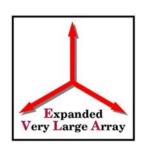
Current Status



- The CMP is up and running and has been collecting monitor data for few months.
- Archive, observe data and alerts are active.
- Used in the experimental control of a subset of 2 VLA antennas with the EVLA antennas.
- Ongoing testing and tweaking.



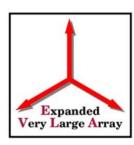
Work to be completed



- Use the system to control the whole VLA array
- Add a hard disk to the CMP-LX for better debugging and ease of deployment
- Final deployment



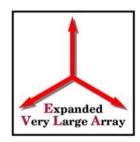
Demo



- Device browser
- Telnet interface







Questions