

Fundamentals of Radio Interferometry I: The Basics



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Topics

- **Introduction:**
 - **Motivation: Mapping the Sky**
 - **Why Interferometry?**
- **The Basic Interferometer**
 - **Simplifying Assumptions**
 - **'Fringe' patterns**
 - **Response to a Point Source**
 - **Sine and Cosine Fringes**
 - **Response to Extended Emission**
 - **The Complex Correlator and Complex Visibilities**
 - **Illustrations to aid visualization**
- **Important Note:**
 - **The concepts I'll be speaking about are not difficult – but they are unfamiliar to beginners.**



Our Goal: Mapping the Sky Brightness

- In astronomy, we wish to know the angular distribution of the emission (brightness, or specific intensity) of distant radiating sources.
 - This can be a function of frequency, polarization, and time.
- ‘Angular Distribution’ means we are interested in the **brightness distribution** of the emission.
- And this requires **resolving** the emission – utilizing an instrument of sufficient angular resolution.
- Because our targets are so far away, the emission is extremely weak, and of very small angular size.
 - Power from strongest radio source (Cygnus A) collected over the entire Earth in 1 GHz bandwidth ~1 watt!
 - 1 arcsecond = angular width of a US quarter at ~3 miles distance!
- Early (1950s) surveys of the radio sky employed single dishes.
- Nowadays, most (but not all!) observations are done with interferometers.



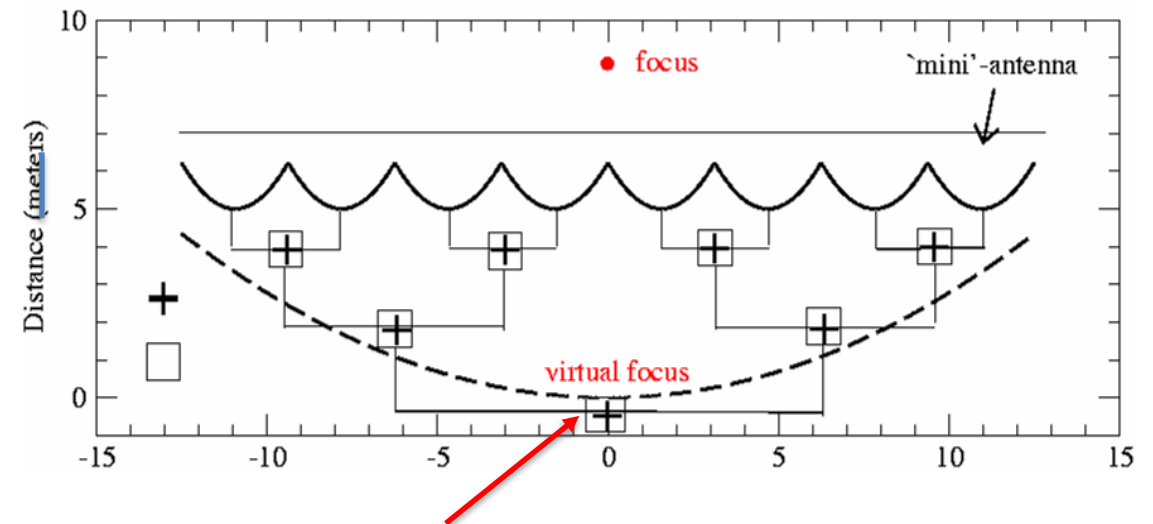
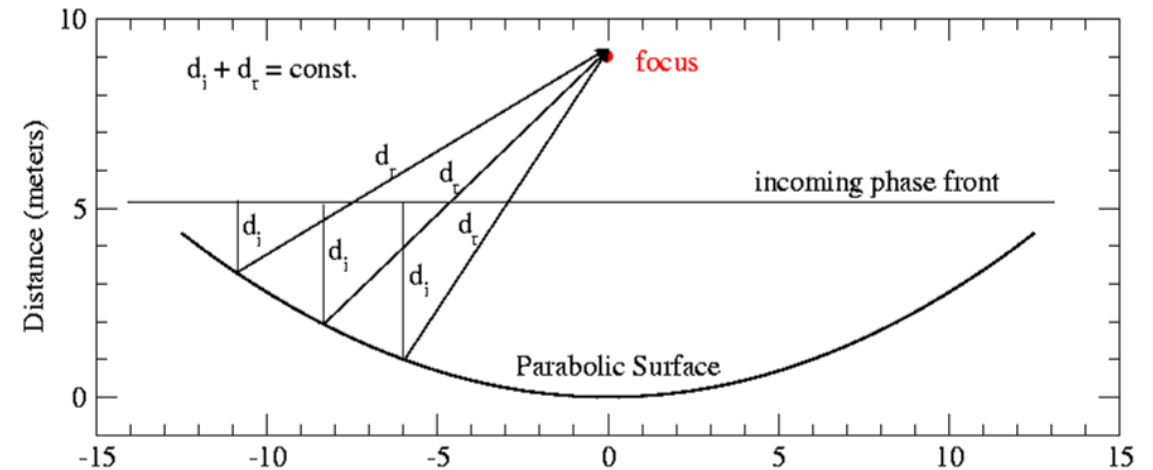
Why Interferometry?

- It's due to **Diffraction** – a consequence of the wave nature of light.
- Radio telescopes coherently sum electric fields over an aperture of size D . For this, diffraction theory applies –
- The angular resolution is:
$$\theta_{rad} \approx \lambda / D$$
Or, in practical units
$$\theta_{arcsec} \approx 2 \lambda_{cm} / D_{km}$$
- To obtain 1 arcsecond resolution at a wavelength of 21 cm, we require an aperture of ~42 km – not feasible.
- The largest single, fully-steerable apertures are the 100-m antennas in Bonn, and Green Bank. Nowhere big enough.
- Can we synthesize a larger aperture with separated antennas?
- The technique of synthesizing a larger effective aperture through combinations of separated pairs of antennas is called 'aperture synthesis'.



Interferometry – Basic Concepts

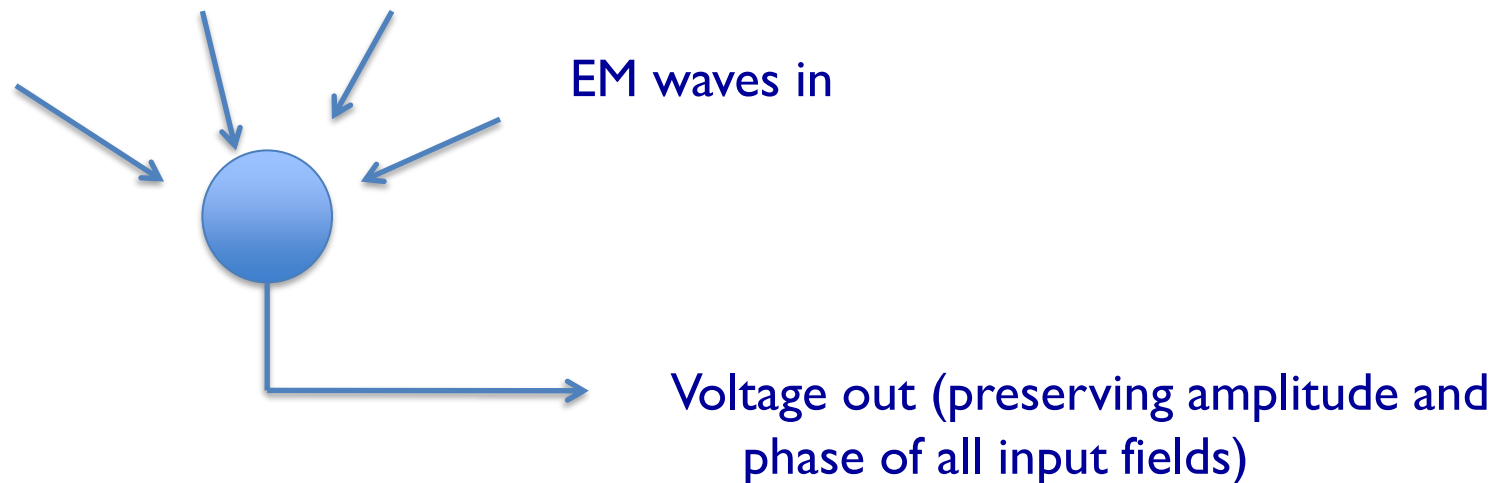
- A parabolic dish coherently sums EM fields at the focus.
- The same sum can be obtained by adding voltages from individual elements with a wired network.
 - Note – they need not be adjacent.
- This is the basic concept of interferometry – coherent summation of voltages from separated antennas.
- Aperture Synthesis is an extension of this concept.



Signals summed here equivalent to those collected at prime focus

The Role of the Sensor (aka Antenna)

- Coherent interferometry is based on the ability to correlate the electric fields measured at spatially separated locations.
- To do this (without mirrors) requires conversion of the electric field $E(\mathbf{r}, \nu, t)$ at some place (\mathbf{r}) to a voltage $V(\nu, t)$ which can be conveyed to a central location for processing – without losing the phase information.
- For our purpose, the sensor (a.k.a. ‘antenna’) is simply a device which senses the electric fields at some place and converts this to a voltage which faithfully retains the amplitudes and phases of the electric fields.

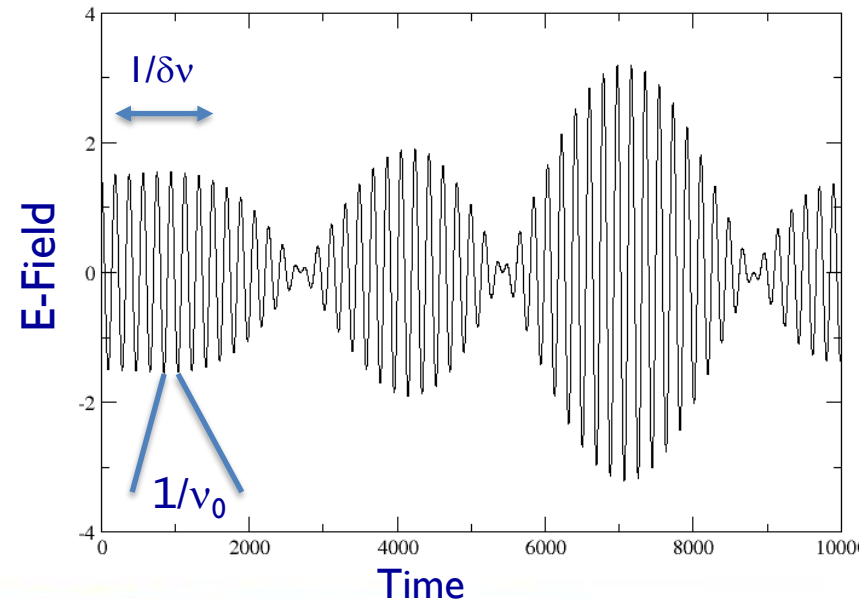


Quasi-Monochromatic Radiation

- Mathematical analysis of wideband noise is difficult.
- Analysis is simple if the fields are monochromatic – a single frequency of zero bandwidth – but such signals cannot exist in nature.
- So we consider instead ‘quasi-monochromatic’ radiation, where the bandwidth $\delta\nu$ is very small, but not zero.
- Then, for a time $dt \sim 1/\delta\nu$, the electric fields will be sinusoidal, with unchanging amplitude E and constant phase ϕ , described by

$$E_\nu(t) = E \cos(2\pi\nu t + \phi)$$

The figure shows an ‘oscilloscope’ trace of a narrow bandwidth noise signal. The period of the wave is $T_1 = 1/\nu_0$, the duration over which the signal is closely sinusoidal is $T_2 \sim 1/\delta\nu$. There are $N \sim T_2/T_1 \sim \nu_0/\delta\nu$ oscillations in a ‘wave packet’.



Simplifying Assumptions

- We now consider the most basic interferometer, and seek a relation between the characteristics of the product of the voltages from two separated antennas and the distribution of the brightness of the originating source emission.
- To establish the basic relations, the following simplifications are introduced:
 - Isotropic sensors fixed in space – no rotation or motion
 - Quasi-monochromatic radiation
 - Point source in the far-field ($D \gg B^2/\lambda$, $\theta \ll \lambda/B$)
 - No frequency conversions (an 'RF interferometer')
 - Single polarization
 - Propagation in vacuum, without distortions (no ionosphere, atmosphere ...)
 - Idealized electronics (perfectly linear, perfectly uniform in frequency and direction, perfectly identical for both elements, no added noise.
- I will later relax most of these restrictions.



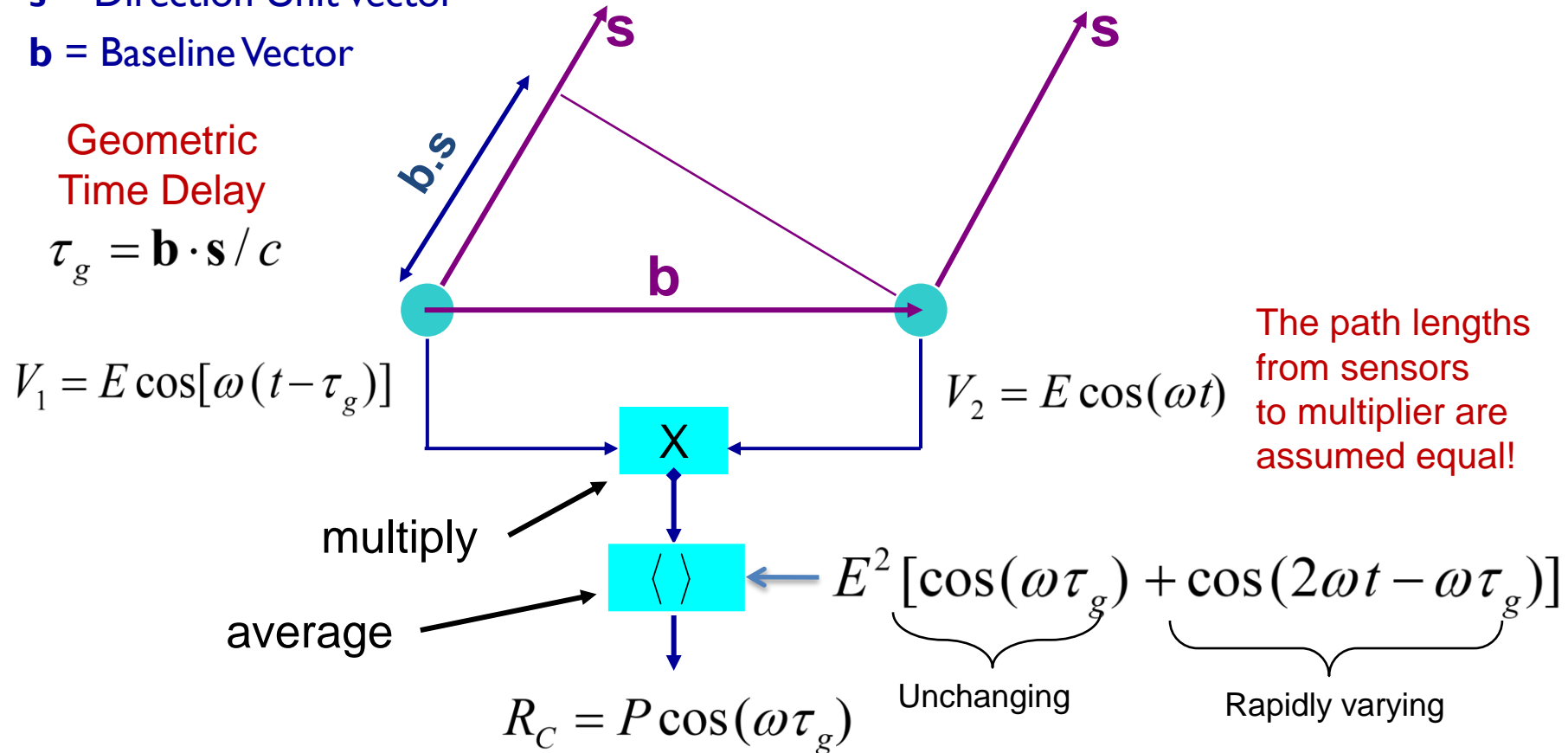
The Stationary, Quasi-Monochromatic Radio-Frequency Interferometer

\mathbf{s} = Direction Unit Vector

\mathbf{b} = Baseline Vector

Geometric
Time Delay

$$\tau_g = \mathbf{b} \cdot \mathbf{s} / c$$



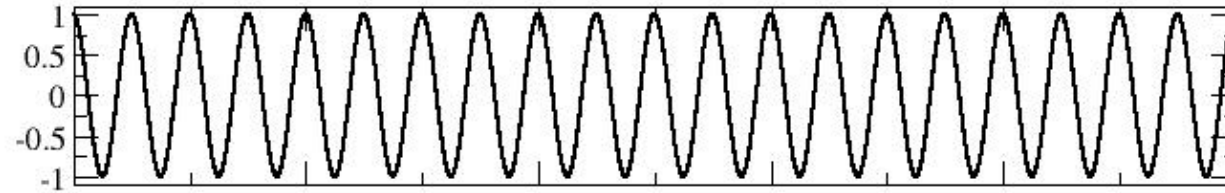
Where I replaced E^2 with P (power), and ignored factors of 2

Pictorial Example: Signals In Phase

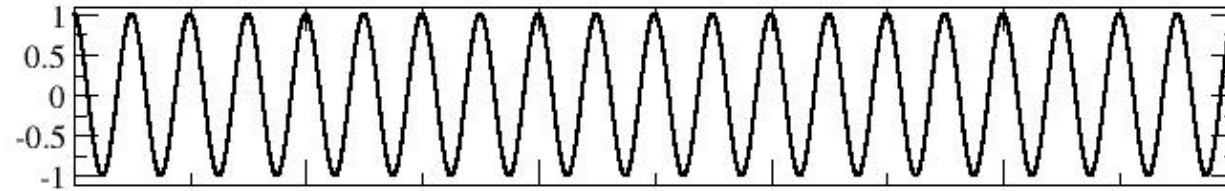
2 GHz Frequency, with voltages in phase:

$$\mathbf{b.s} = n\lambda, \text{ or } \tau_g = n/v, \text{ so } \cos(\omega\tau) = \cos(2\pi n) = 1$$

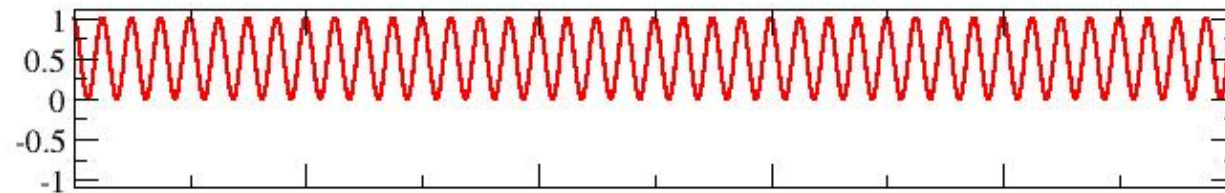
• Antenna 1
Voltage



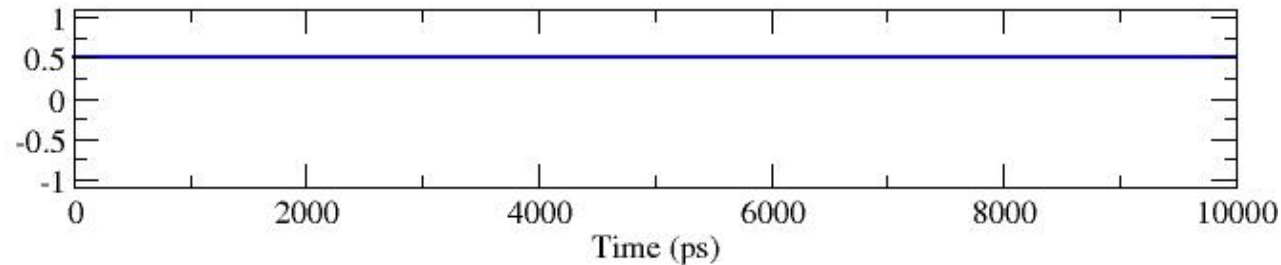
• Antenna 2
Voltage



• Product
Voltage



• Average



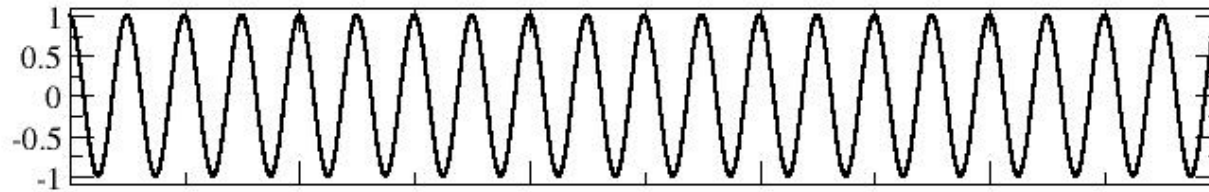
Positive
constant

Pictorial Example: Signals out of Phase

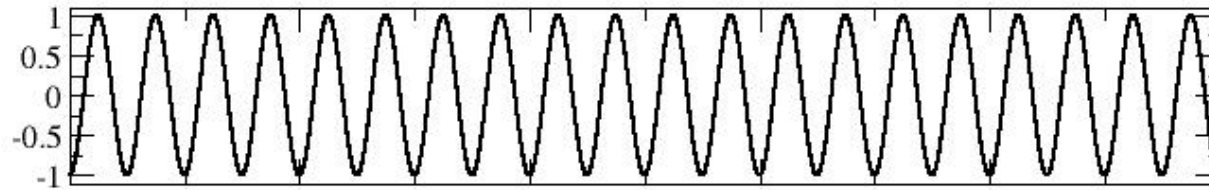
2 GHz Frequency, with voltages out of phase:

$$b.s = (n \pm \frac{1}{2})\lambda \quad \tau_g = (n \pm \frac{1}{2})/\nu \quad \text{SO} \quad \cos(\omega\tau + \pi) = \cos(\pi(2n+1)) = -1$$

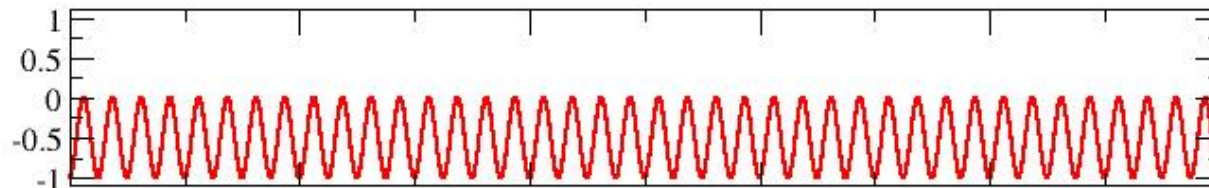
• Antenna 1
Voltage



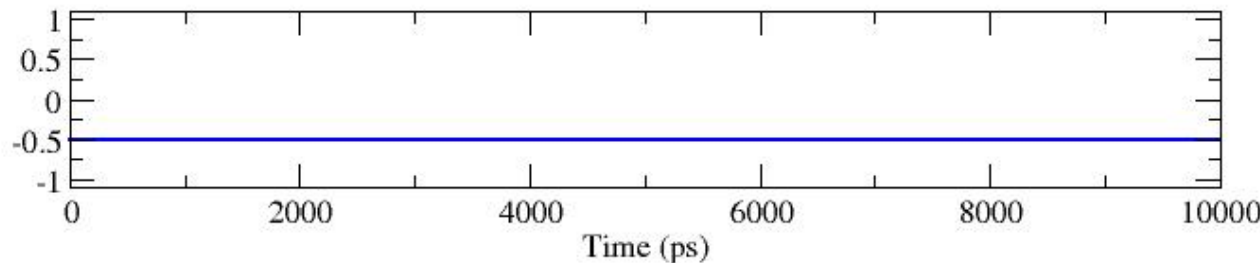
• Antenna 2
Voltage



• Product
Voltage



• Average



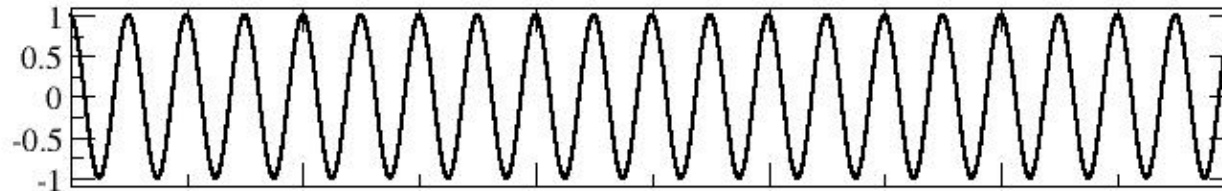
Negative
constant

Pictorial Example: Signals in Quad Phase

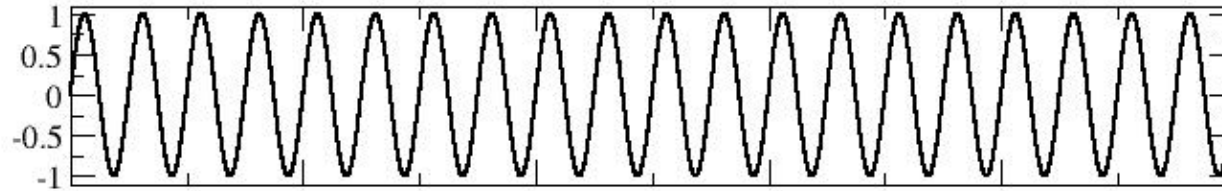
2 GHz Frequency, with voltages in quadrature phase:

$$b.s = (n \pm 1/4)\lambda, \tau_g = (n \pm 1/4)/v \text{ so } \cos(\omega\tau + \pi/2) = \cos(\pi(2n+1/2)) = 0$$

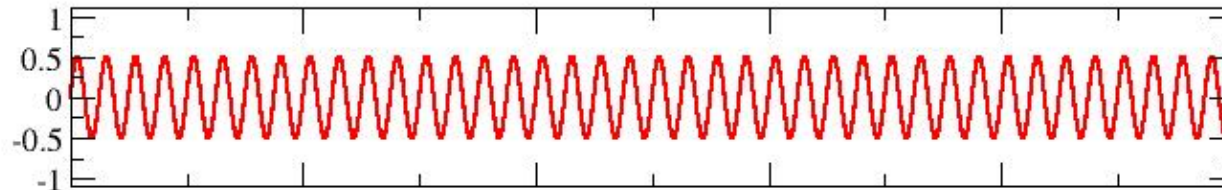
• Antenna 1
Voltage



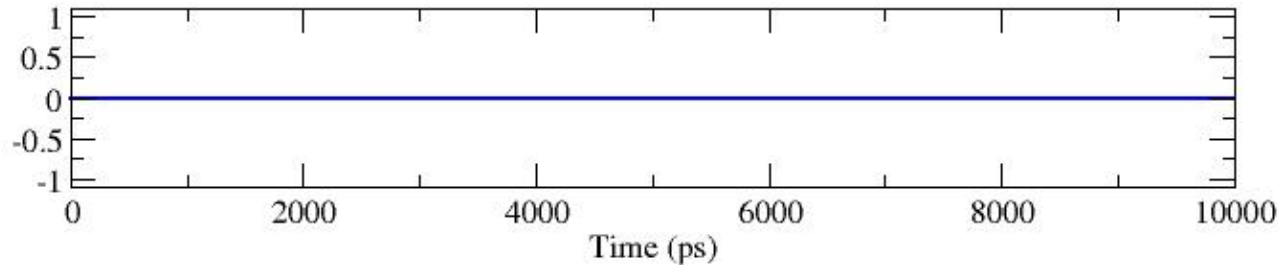
• Antenna 2
Voltage



• Product
Voltage



• Average



Zero
constant

General Comments on this Product

- The averaged product R_C is dependent on the received power, $P = E^2/2$ and geometric delay, τ_g , and hence on the baseline orientation and source direction. From slide 9, we have:

$$R_C = P \cos(\omega\tau_g) = P \cos\left(2\pi \frac{\mathbf{b} \cdot \mathbf{s}}{\lambda}\right)$$

- Note that R_C is not a function of:
 - The time of the observation -- provided the source itself is not variable!
 - The location of the baseline -- provided the emission is in the far-field.
 - The actual phase of the incoming signal – the distance to the source -- provided the source is in the far-field.
- The strength of the product is also dependent on practical factors such as the antenna sizes, electronic gains, bandwidth and time averaging – but these factors are ignored here (and can be calibrated for).



Define the Direction Cosine

- Consider a single baseline, and define the x-axis to extend along this baseline.

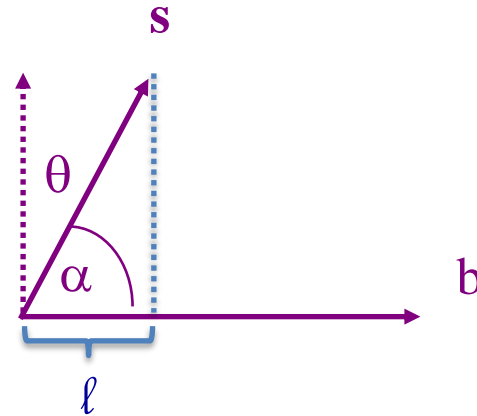


- Write $\mathbf{b} = u \hat{\mathbf{x}}$ where $u = |\mathbf{b}|/\lambda$ is the baseline length in wavelengths, and $\hat{\mathbf{x}}$ = the unit direction vector.
- Define the 'direction cosine' as:

$$l = \hat{\mathbf{x}} \cdot \mathbf{s} = \cos \alpha = \sin \theta$$

- Then:

$$\frac{\mathbf{b} \cdot \mathbf{s}}{\lambda} = u \cos \alpha = u \sin \theta = ul$$



- So the interferometer response is:

$$R_C = P \cos(\omega \tau_g) = P \cos\left(2\pi \frac{\mathbf{b} \cdot \mathbf{s}}{\lambda}\right) = P \cos(2\pi ul)$$

Two Illustrative Examples

- Consider the response R_C , as a function of angle, for two different baselines with $u = b/\lambda = 10$, and $u = 25$ wavelengths.

- Since
$$R_C = \cos(2\pi ul)$$

- We have, for $u = 10$:
$$R_C = \cos(20\pi l)$$

- And, for $u = 25$:
$$R_C = \cos(50\pi l)$$

- These are simple functions of angle on the sky.

Remember:

u = baseline length in wavelengths

$l = \sin \theta$,

θ = angular offset from plane perpendicular to the baseline



Whole-Sky Response

- Top:

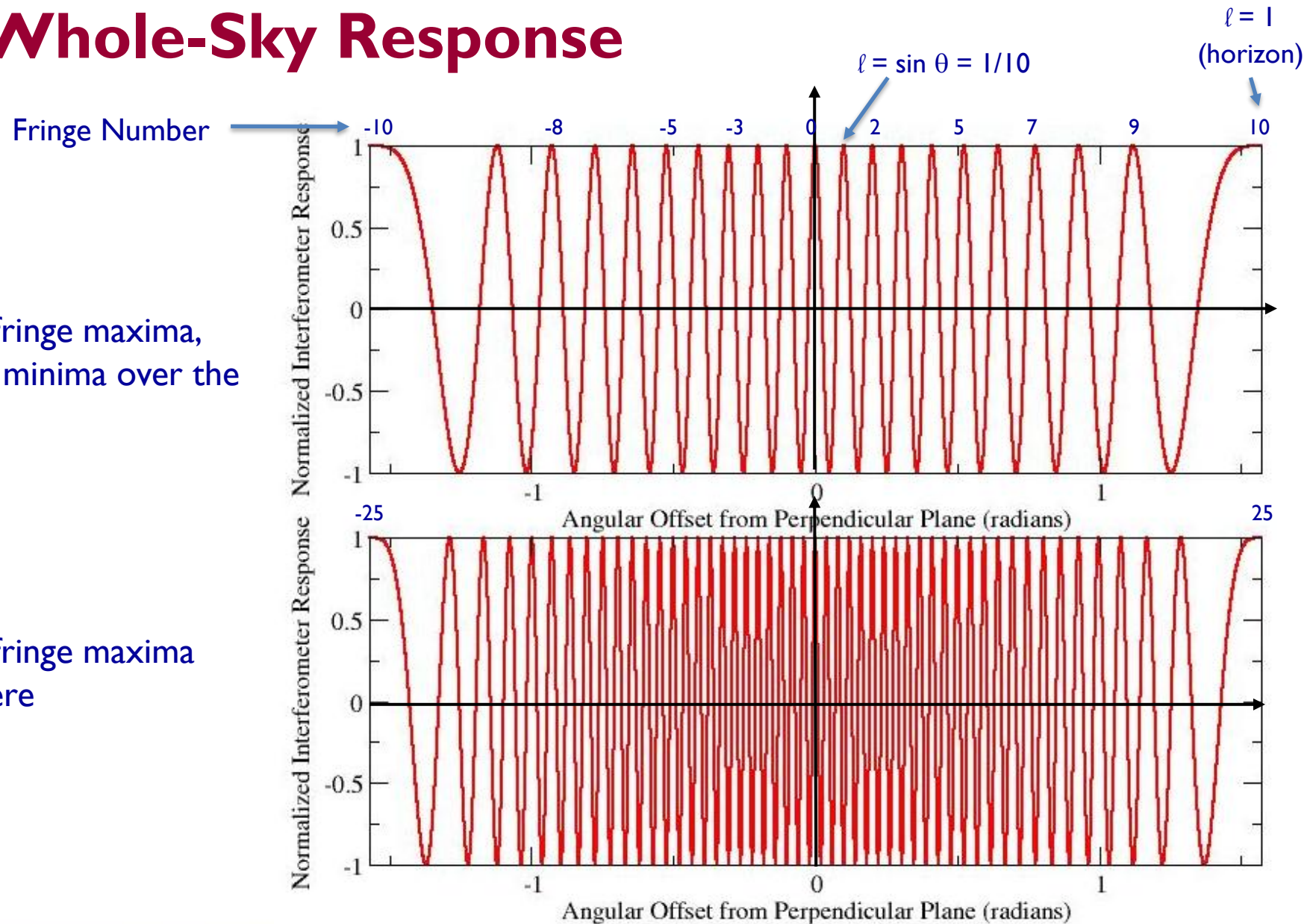
$$u = 10$$

There are 21 fringe maxima, and 20 fringe minima over the sphere.

- Bottom:

$$u = 25$$

There are 51 fringe maxima over the sphere

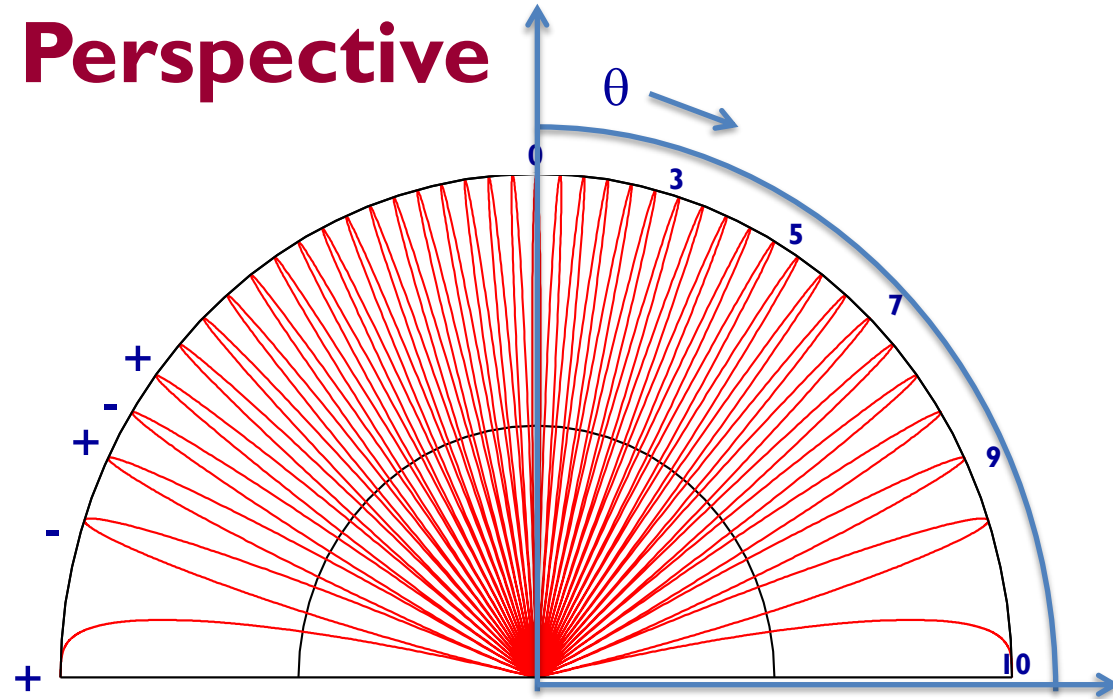


From an Angular Perspective

Top Panel:

The absolute value of the response for $u = 10$, as a function of angle.

The 'lobes' of the response pattern alternate in sign.

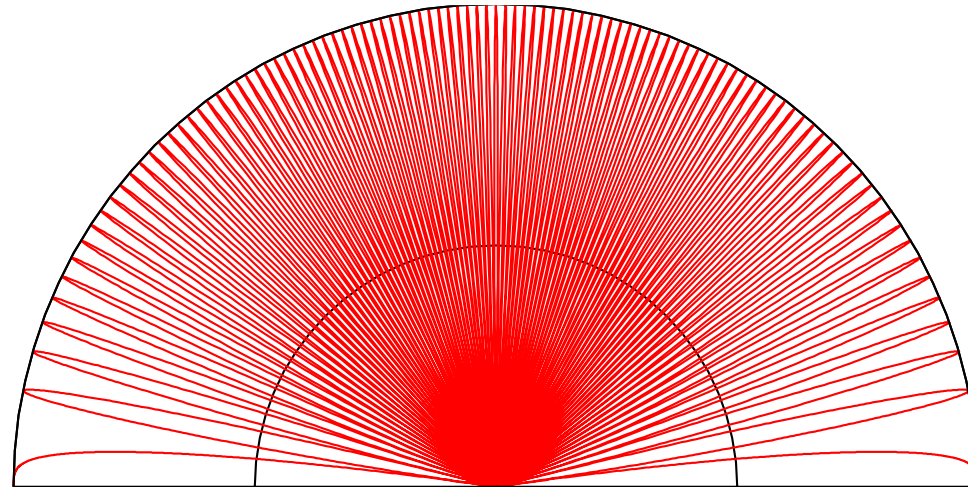


Bottom Panel:

The same, but for $u = 25$.

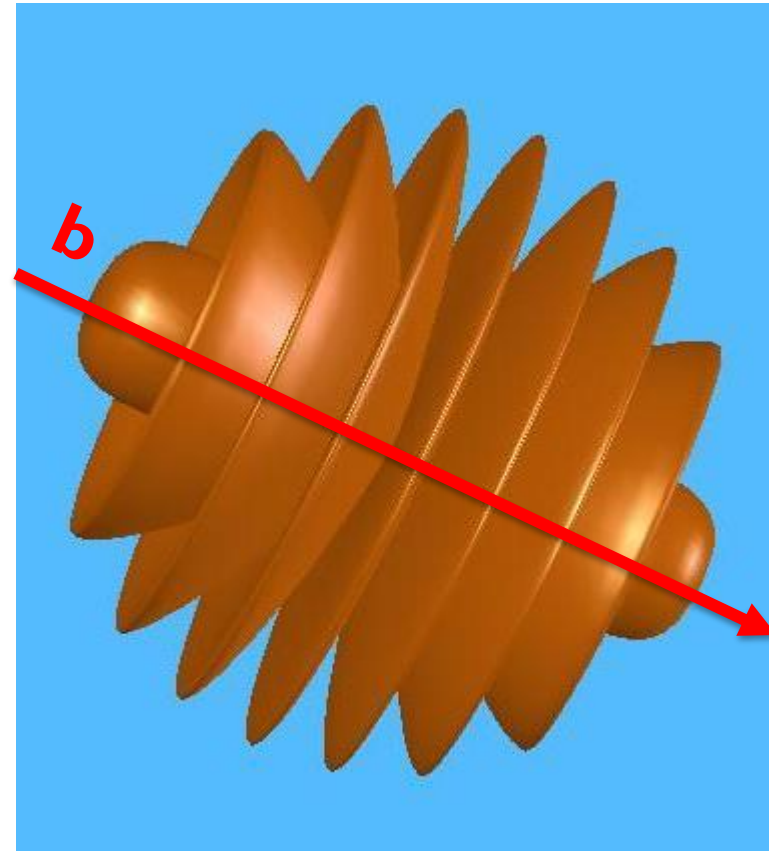
Angular separation between lobes (of the same sign) is

$$\delta\theta \sim 1/u = \lambda/b \text{ radians.}$$



Full Sky Pattern

- The preceding plot is a meridional cut through the hemisphere, oriented along the baseline vector **b**.
- In the three-dimensional space, the fringe pattern consists of a series of coaxial cones, oriented along the baseline vector.
- The figure is a two-dimensional representation when $u = 4$.
- As viewed along the baseline vector, the fringes show a 'bull's-eye' pattern – concentric circles.



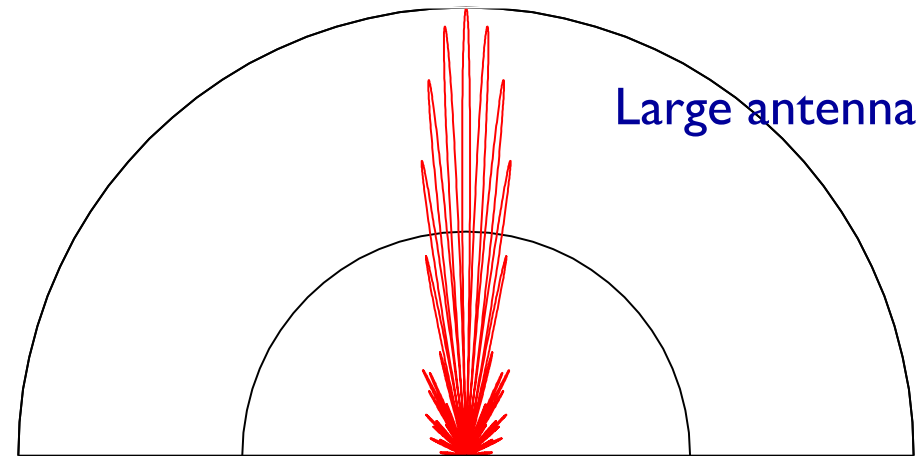
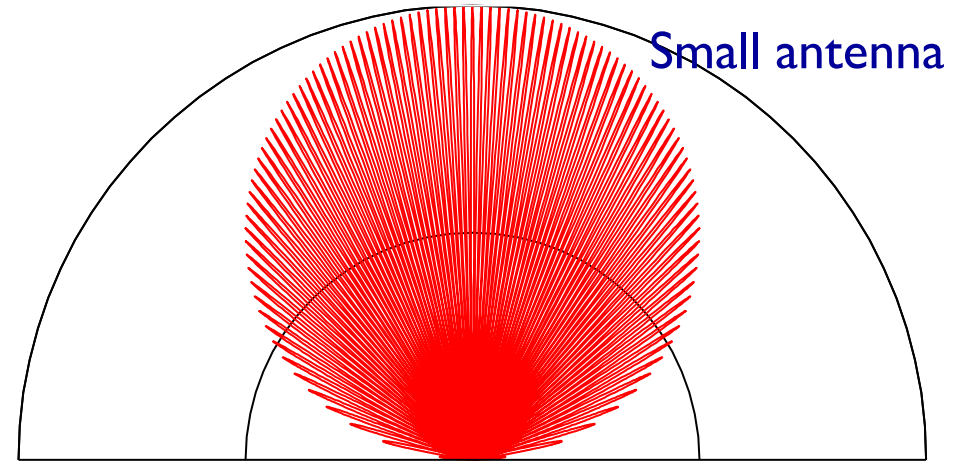
The Effect of the Sensor (aka Antenna)

- The patterns shown presume the sensor has isotropic response.
- This is a convenient assumption, but doesn't represent reality.
- Real sensors impose their own patterns, which modulate the amplitude and phase of the interferometer response.
- Large sensors have good angular resolution and high gain
 - very useful for some applications like imaging individual objects.
- Small sensors have poor angular resolution and low gain
 - useful for wide-angle surveys.
- Emphasis: The fringe pattern is a function of the baseline length (in wavelengths) and orientation, and is not affected by the antenna patterns.



The Effect of Sensor Patterns

- Sensors (or antennas) are not isotropic and have their own responses – both amplitude and phase.
- **Top Panel:** The interferometer pattern with a $\cos(\theta)$ -like sensor response.
- **Bottom Panel:** A multiple-wavelength aperture antenna has a narrow beam, but also sidelobes.
- **Emphasis:** The fringe pattern is a function of the array geometry. The angular modulation is from the sensor.



From Point Sources to Extended Emission

- Everything I stated earlier holds for ‘point sources’. What are these?
- Point Source: Emission from an object whose angular extent is much, much smaller than the interferometer fringe scale.
- That is:
$$\theta_{rad} \ll \lambda / B$$
where θ = angular size, λ = wavelength, B = baseline
- What happens when the source angular size is comparable to, or larger than, the fringe scale?
- Short answer: Under nearly all conditions, you just ‘add up’ the individual responses from the components of the extended source.



The Response from an Extended Source

- For an extended source, the voltage output from a single antenna is the spatial integration of the E-field emission over the primary beam: $V = \iint E(\mathbf{s})d\Omega$
- So the correlator response becomes $R_C = \left\langle \iint E_1(\mathbf{s})d\Omega_1 \times \iint E_2(\mathbf{s})d\Omega_2 \right\rangle$
- The averaging and integrals can be interchanged and, **providing the emission is spatially incoherent**, we get

$$R_C = \iint I_\nu(\mathbf{s}) \cos(2\pi\nu \mathbf{b} \cdot \mathbf{s}/c) d\Omega$$

- The response is the sum of the spatial integration of the brightness I_ν modulated by the cosinusoidal interferometer pattern.
- This expression links what we want: the brightness on the sky, $I_\nu(\mathbf{s})$, to something we can measure - R_C , the interferometer response.

Can we recover $I_\nu(\mathbf{s})$ from observations of R_C ?

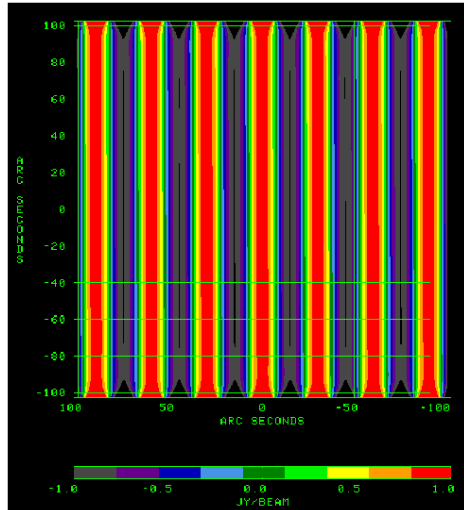


A picture is worth 1000 words ...

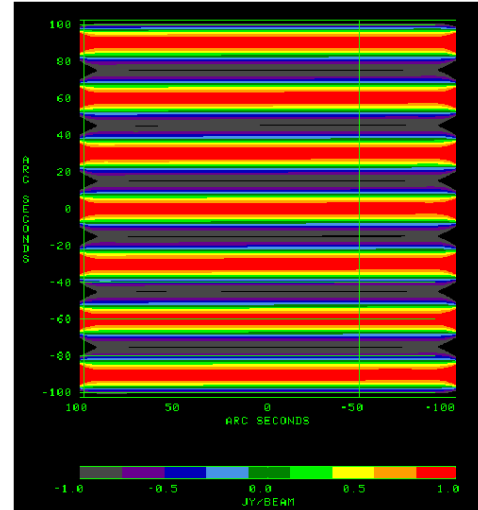
- As stated earlier, these concepts are not difficult but are unfamiliar. We need to think in new ways, to get a deeper understanding of how all this works.
- To aid, I have generated images of interferometer fringes, of various baseline lengths and orientations.
- I then ‘observe’ a real source (Cygnus A, of course), to show what the interferometer actually measures.
- For all these, the ‘observations’ are made at 2052 MHz. The Cygnus A image is taken from real VLA data.
- To keep things simple, all simulations are done at meridian transit.

'Real' Fringes ... 1Km Baseline at 2052 MHz

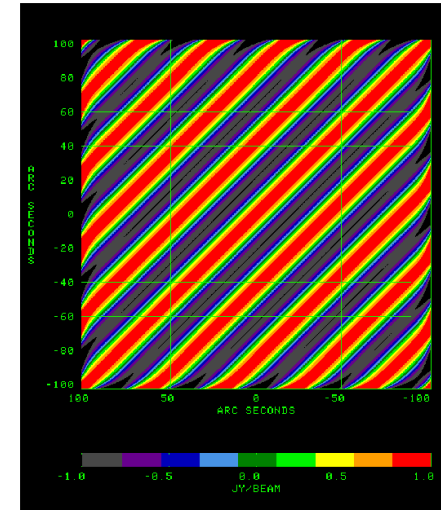
- The fringe separation given by baseline length in wavelengths, the orientation given by the orientation of the baseline.



East-West baseline
makes vertical fringes



North-South baseline
makes horizontal fringes



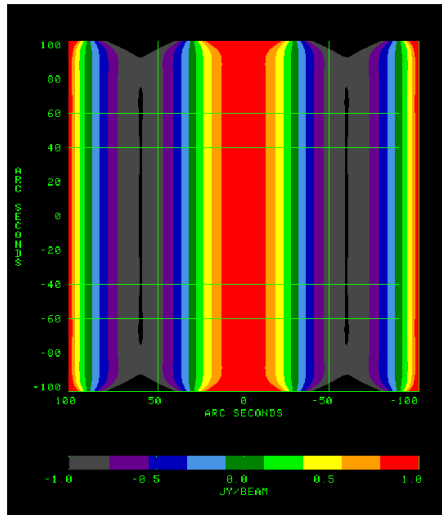
Rotated baseline makes
rotated fringes

- Red = positive maximum. Black = negative maximum. Green = zero
- Fringe angular spacing given by baseline length in wavelengths:

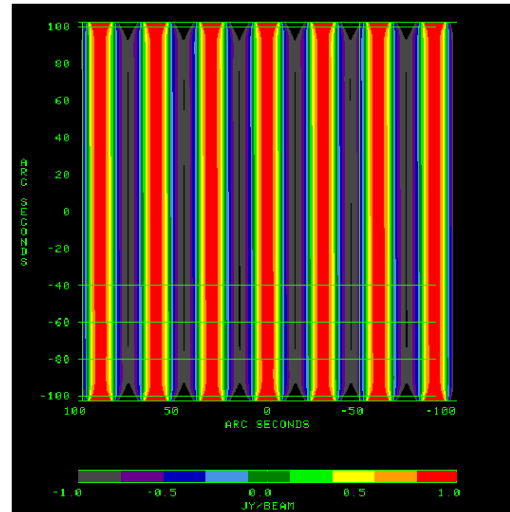
$$\Delta\theta = \lambda / B = 30.2''$$

Longer Baselines => Smaller Fringe Spacing

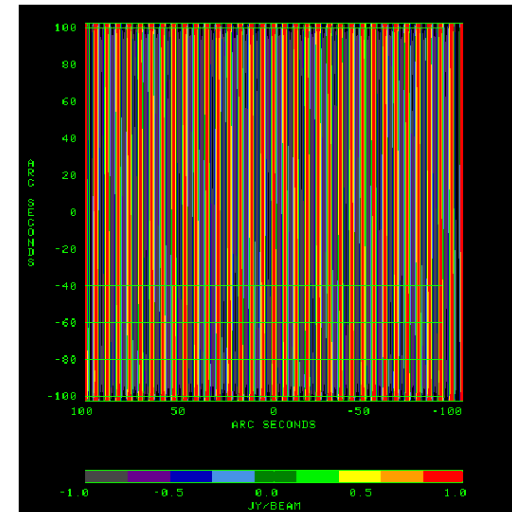
- Longer baselines make finer fringes, shorter baselines make larger fringes:



250 meter baseline
120 arcsecond fringe



1000 meter baseline
30 arcsecond fringe

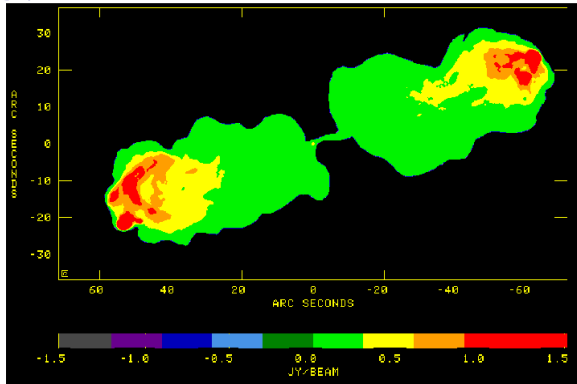


5000 meter baseline
6 arcsecond fringe

- What the interferometer measures is the integral (sum) of the product of this pattern with the actual brightness.

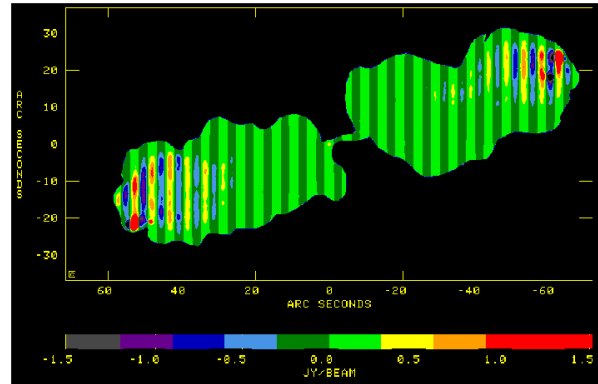
For a Real Source (Cygnus A = 3C405)

- Cygnus A is a powerful, nearby radio galaxy.
- The left panel shows the color-coded brightness at 2052 MHz. (2'' resⁿ)
- The other two panels show how 6.9 km EW and NS interferometers 'see' the source.



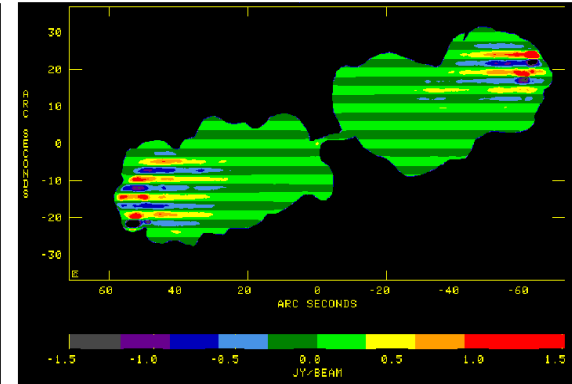
Zero-spacing Image

Sum = 1029 Jy



6.3 km EW spacing

Sum = 70 Jy



6.3 km NS spacing

Sum = -19 Jy

- Dark green, blue, and purples => Negative correlation
- Light green, yellow, and reds => Positive correlation
- Don't be alarmed by the 'negative flux' in the third panel.

So ... What Next?

- The interferometer casts a sinusoidal pattern on the sky, with the result that we obtain a response which is some function of the source brightness and the fringe separation and orientation.
- By definition, 'Cosine' fringes have a peak passing through the central position of the source ('phase center').
- But in fact, something is missing. 'Cosine' fringes are not sufficient to allow recovery of the sky brightness.
- To answer why ...
- Time for some mathematics.... Starting with a seeming digression about odd and even functions.
- (All will be clear shortly...)

A Short Mathematics Digression – Odd and Even Functions

- Any real function, $I(x,y)$, can be expressed as the sum of two real functions which have specific symmetries:

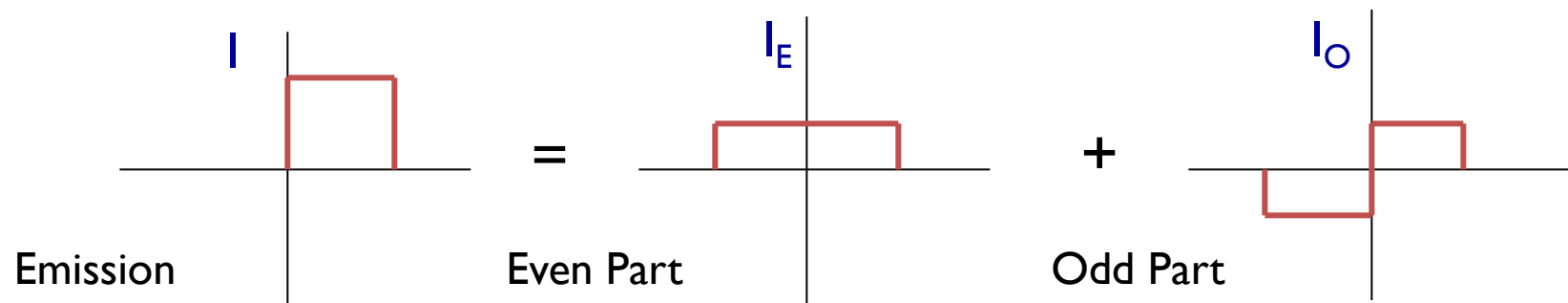
$$I(x, y) = I_E(x, y) + I_O(x, y)$$

An even part:

$$I_E(x, y) = \frac{I(x, y) + I(-x, -y)}{2} = I_E(-x, -y)$$

An odd part:

$$I_O(x, y) = \frac{I(x, y) - I(-x, -y)}{2} = -I_O(-x, -y)$$



The Cosine Correlator is Blind to Odd Structure

- Suppose that the source of emission has a component with odd symmetry, for which

$$I_o(\mathbf{x}) = -I_o(-\mathbf{x})$$

- Since the cosine fringe pattern is even, the response of our interferometer to the odd brightness distribution is 0!

$$R_c = \iint I_o(\mathbf{s}) \cos(2\pi\nu \mathbf{b} \cdot \mathbf{s}/c) d\Omega = 0$$

- Thus, the cosine correlator response R_c :

$$R_c = \iint (I(\mathbf{s})) \cos(2\pi\nu \mathbf{b} \cdot \mathbf{s}/c) d\Omega = \iint (I_E(\mathbf{s})) \cos(2\pi\nu \mathbf{b} \cdot \mathbf{s}/c) d\Omega$$

is sensitive to only the even component of the source structure.

Hence, we need more information if we are to completely recover the source brightness.



Thus: More Information is Needed

- The integration of the cosine response, R_C , over the source brightness is sensitive to only the even part of the brightness:

$$R_C = \iint I(\mathbf{s}) \cos(2\pi\nu\mathbf{b} \cdot \mathbf{s}/c) d\Omega = \iint I_E(\mathbf{s}) \cos(2\pi\nu\mathbf{b} \cdot \mathbf{s}/c) d\Omega$$

since the integral of an odd function (I_O) with an even function ($\cos x$) is zero.

- To recover the 'odd' part of the brightness, I_O , we need an 'odd' fringe pattern.
- Let us replace the 'cos' with 'sin' in the integral, to get

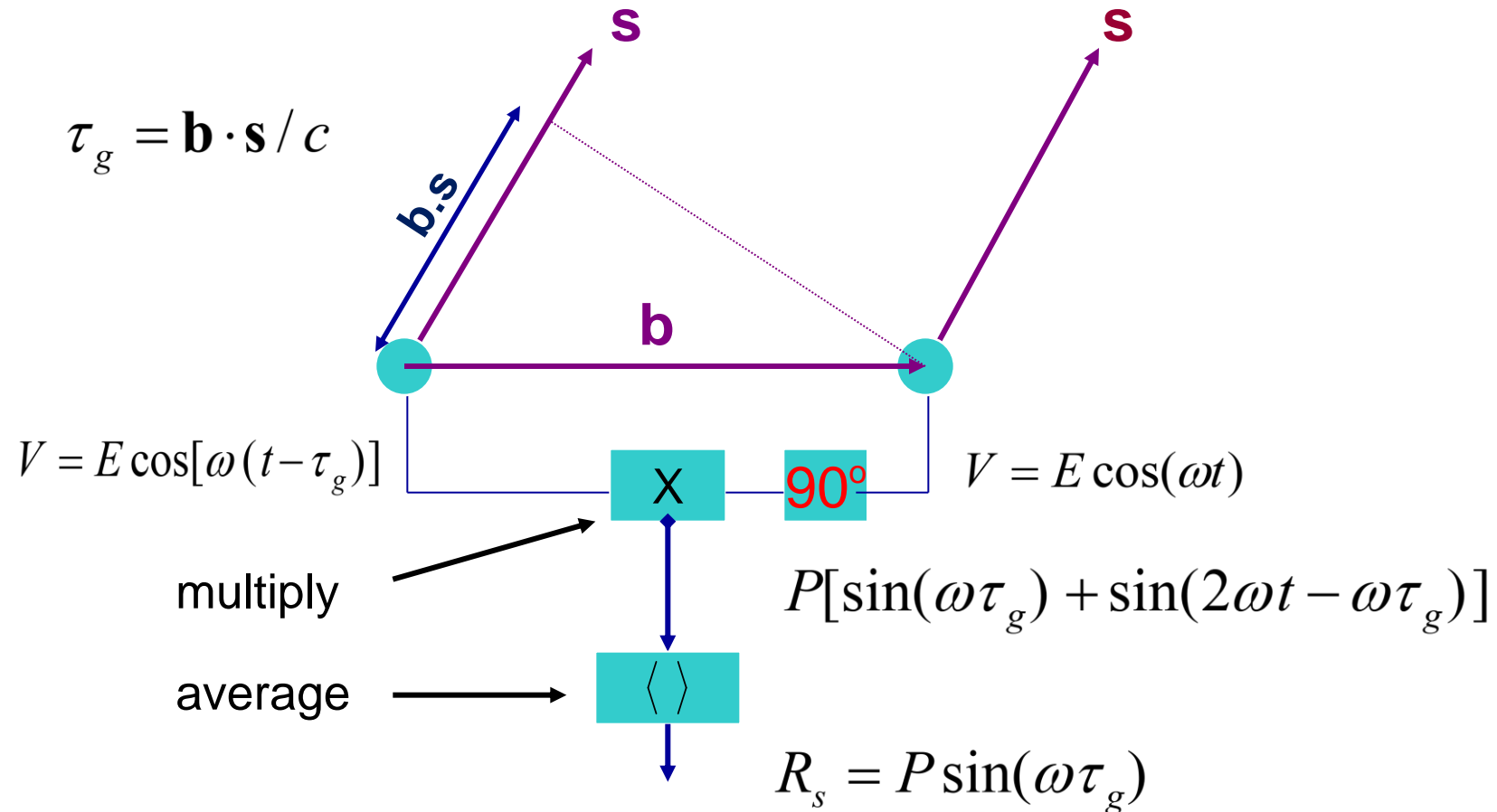
$$R_S = \iint I(\mathbf{s}) \sin(2\pi\nu\mathbf{b} \cdot \mathbf{s}/c) d\Omega = \iint I_O(\mathbf{s}) \sin(2\pi\nu\mathbf{b} \cdot \mathbf{s}/c) d\Omega$$

since the integral of an even times an odd function is zero.

- These 'sine' fringes see only the 'odd' component.
- To obtain this necessary component, we must make a 'sine' pattern.

Making a SIN Correlator

- We generate the 'sine' pattern by inserting a 90 degree phase shift in one of the signal paths.



Define the Complex Visibility

- We now DEFINE a complex function, the complex visibility, V , from the two independent (real) correlator outputs R_C and R_S :

$$V = R_C - iR_S = Ae^{-i\phi}$$

where

$$A = \sqrt{R_C^2 + R_S^2}$$

$$\phi = \tan^{-1}\left(\frac{R_S}{R_C}\right)$$

- This gives us a beautiful and useful relationship between the source brightness, and the response of an interferometer:

$$V_v(\mathbf{b}) = R_C - iR_S = \iint I_v(\mathbf{s}) e^{-2\pi i v \mathbf{b} \cdot \mathbf{s} / c} d\Omega$$

- Under some circumstances, this is a 2-D Fourier transform, giving us a well established way to recover $I(\mathbf{s})$ from $V(\mathbf{b})$.



The Complex Correlator and Complex Notation

- A correlator which produces both ‘Real’ and ‘Imaginary’ parts – or the Cosine and Sine fringes, is called a ‘Complex Correlator’
 - For a complex correlator, think of two independent sets of projected sinusoids, separated by 1/4 fringe spacing.
 - In our scenario, both components are necessary, because we have assumed there is no motion – the ‘fringes’ are fixed on the source emission, which is itself stationary.
- The complex output of the complex correlator also means we can use complex analysis throughout: Let:

$$V_1 = A \cos(\omega t) \rightarrow A e^{-i\omega t}$$

$$V_2 = A \cos[\omega(t - \mathbf{b} \cdot \mathbf{s} / c)] \rightarrow A e^{-i\omega(t - \mathbf{b} \cdot \mathbf{s} / c)}$$

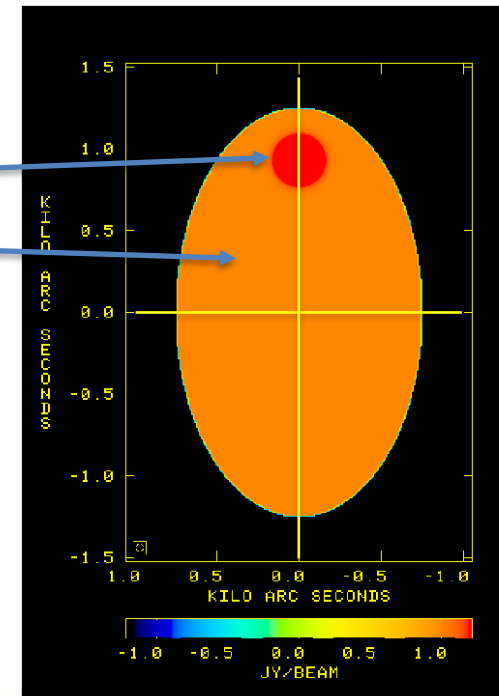
- Then:

$$P_{corr} = \langle V_1 V_2^* \rangle = A^2 e^{-i\omega \mathbf{b} \cdot \mathbf{s} / c}$$



Visualizing Visibilities

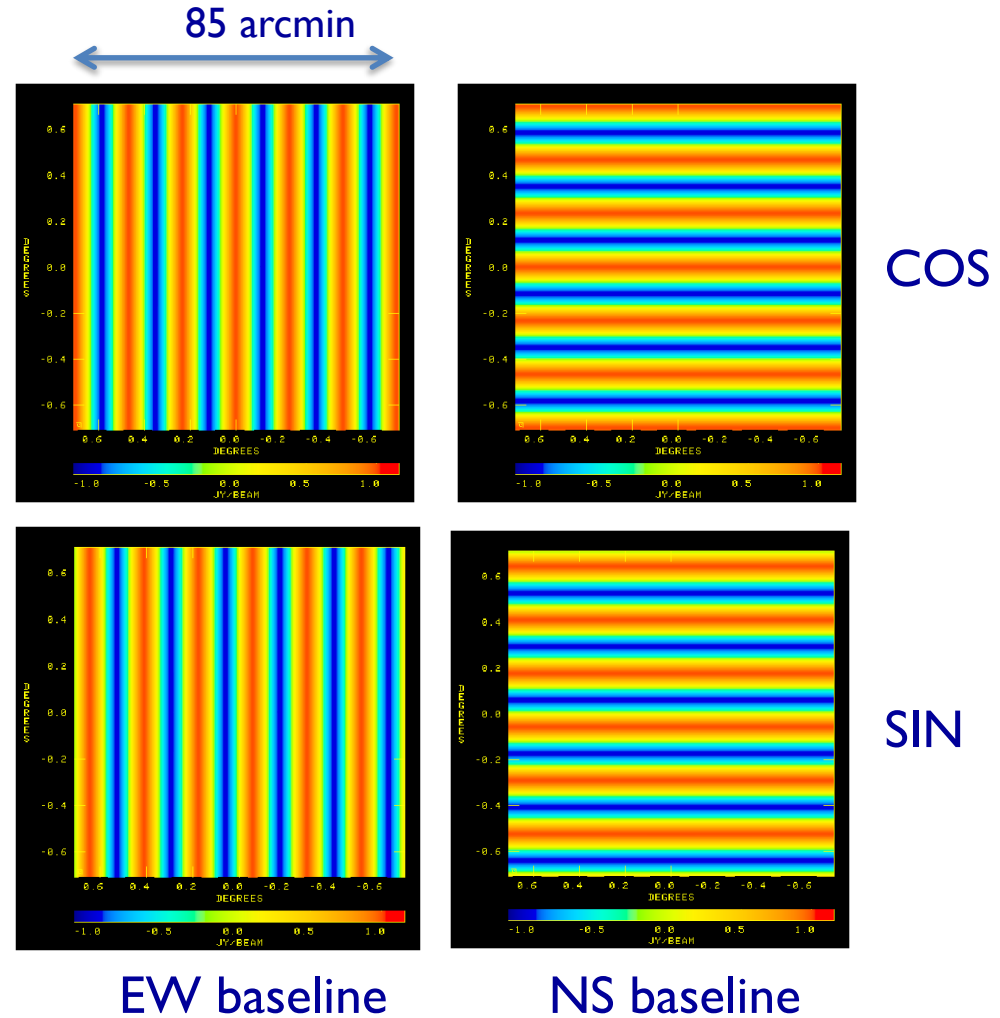
- An intimate familiarity with interferometer visibilities is essential in understanding how interferometers work.
- Fortunately, the concepts can be easily grasped through pictures.
- To illustrate, I have generated a mock source, consisting of a flat elliptical disk, (1500'' x 2500'') and a bright, circular gaussian 'spot' of width 150'' near one end.
 - Flux of disk: 1283 Jy.
 - Peak brightness of hotspot: 6 Jy/beam
 - Brightness of disk: 1 Jy/beam
 - Flux of hotspot: 56 Jy
 - Beamsize = 45 arcseconds
 - The odd color wedge is chosen to illustrate the main points
 - Color wedge runs from -1.25 Jy/beam (black) to +1.25 Jy/beam (red).



Our Mock Interferometer Response

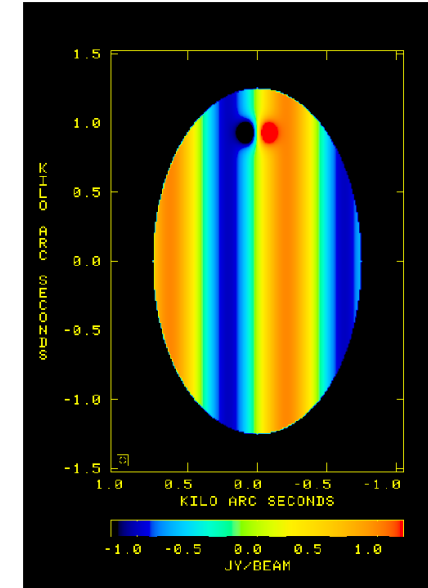
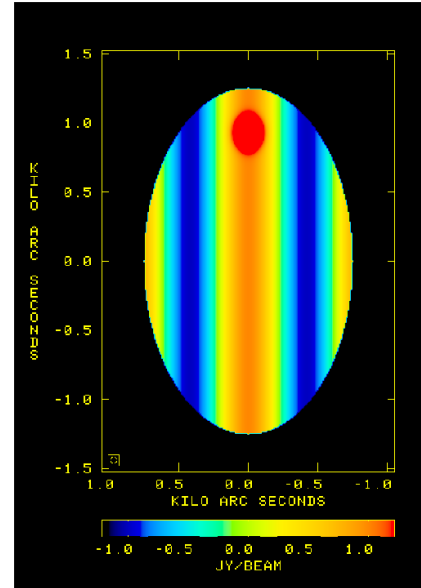
- We now `observe' this source with an interferometer, with seven baselines running from 12 through 525 meters, at a frequency of 1471 MHz.
 - These numbers are appropriate for the MeerKAT interferometer, but can be scaled to any other.
- The mock interferometer has only EW and NS spacings.
- Shown here are the two fringe patterns (Cos and Sin) for the two 50-meter baselines.
- Fringe spacing = $841''$

$$= 300 * 206265 / (1471 * 50)$$



What does the interferometer 'do'? E-W baseline

- Recall that the interferometer multiplies the actual brightness by the fringe pattern (both COS and SIN), and integrates (adds) over the field of view.
- The complex visibility is made from these products as:
 - COS => Real Part
 - SIN => Imaginary Part
- Shown are the COS and SIN products for the 50-m EW baseline.



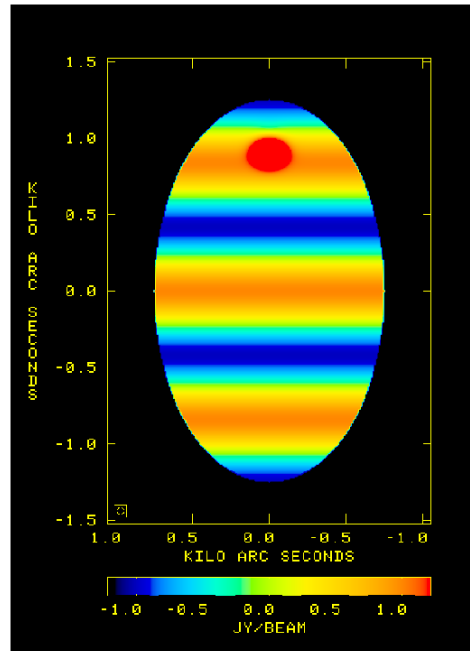
$$\text{Cos } \Sigma = -104 \text{ Jy} \quad \text{Sin } \Sigma = -0.14 \text{ Jy}$$

$$\text{Thus: } A = 104 \text{ Jy}, \quad \phi = 180 \text{ degrees.}$$

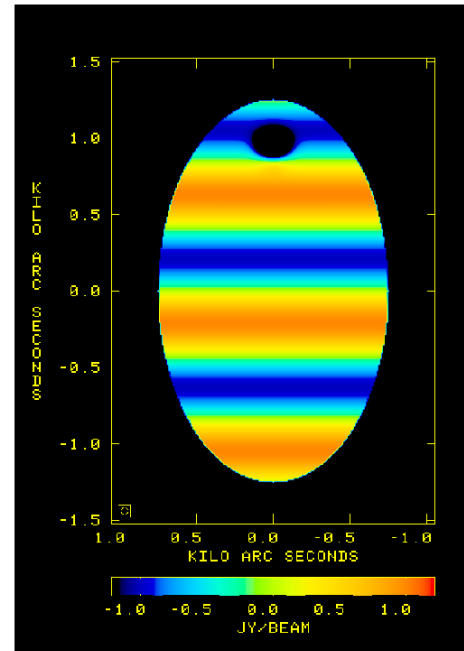
NB: The EW even symmetry requires the SIN integral = 0, so the phase must be either 0 or 180.

While for the NS baseline...

- The N-S asymmetry of the model (due to the `hotspot') means the NS baselines `see' a wider range in the SIN (imaginary) component:



$$\text{Cos } \Sigma = 91.9 \text{ Jy}$$



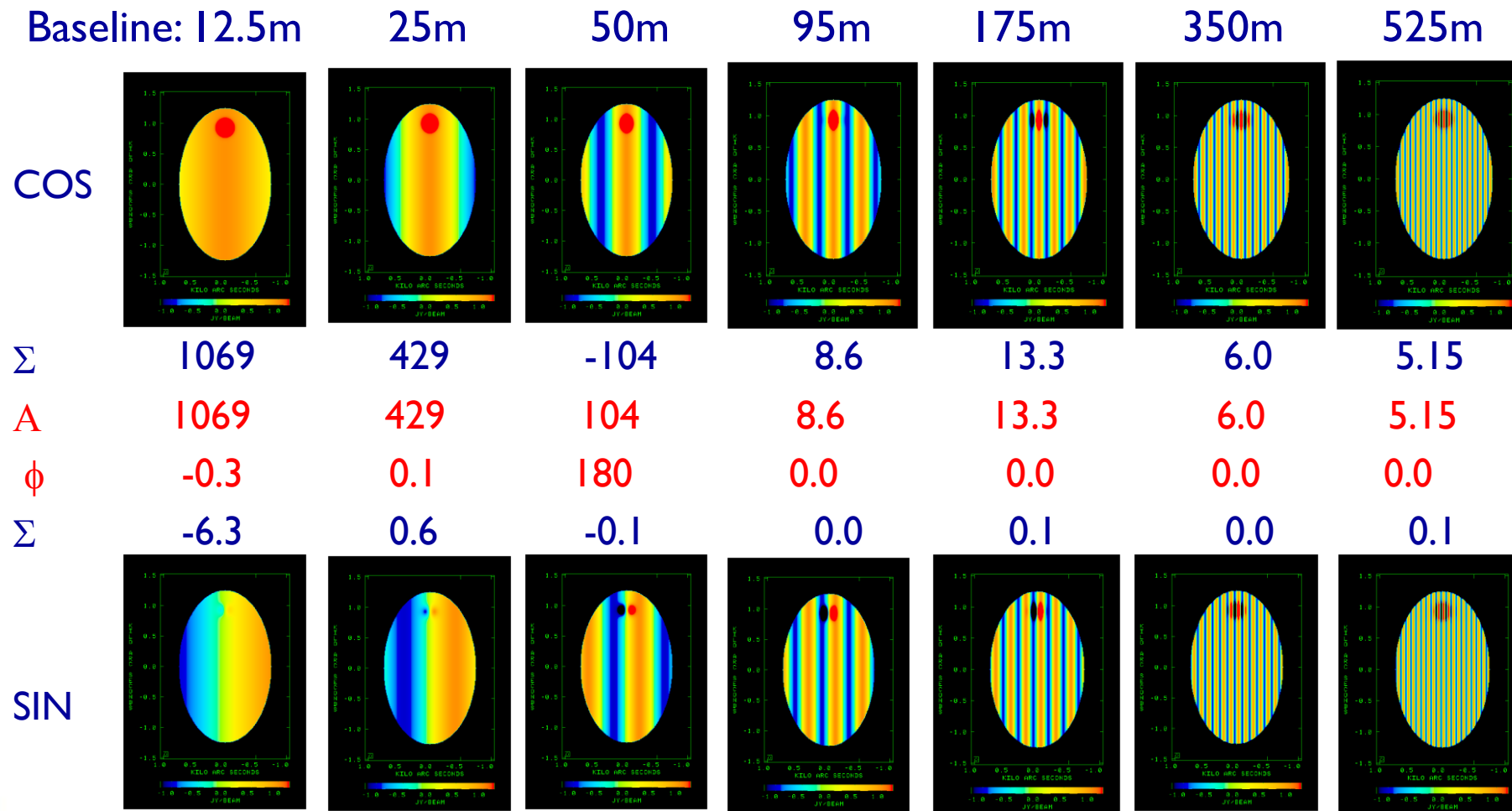
$$\text{Sin } \Sigma = -30.6 \text{ Jy}$$

Thus: $A = 96.9 \text{ Jy}$, $\phi = -18.4 \text{ degrees}$.

NB: There are no symmetries here, so phases can be any value.

Visibilities as a function of baseline length

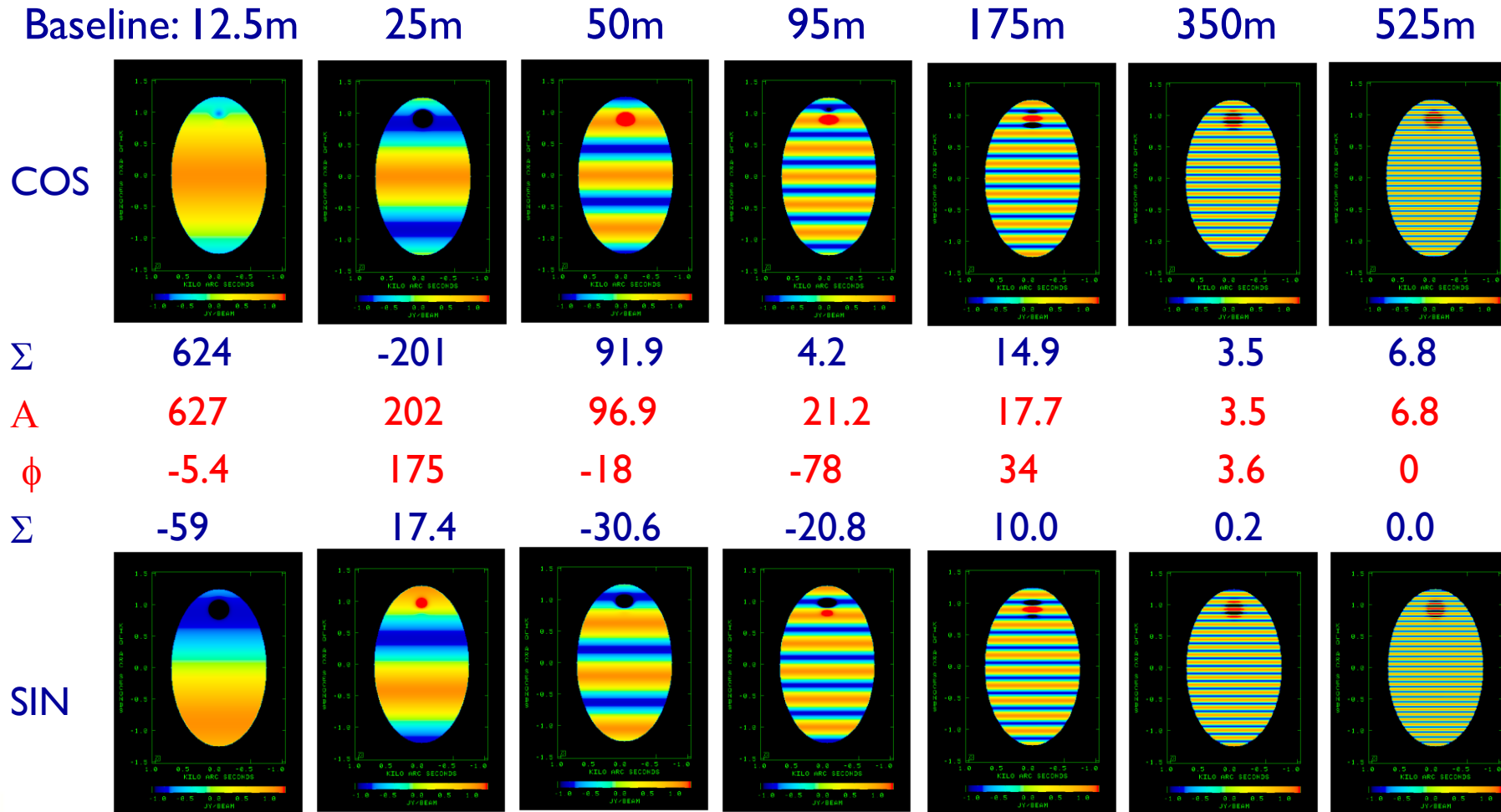
- Showing a sequence as the E-W baselines gets longer:



- Note that the 'SIN' fluxes are all very low, so the visibility phases are ~zero or 180 degrees.

As a function of N-S baseline length...

- Showing a sequence as the baseline gets longer:



- Note that the 'SIN' fluxes are now much larger, and the visibility phases far from zero or 180.

Some Take-Aways...

- In general, as the baseline gets longer, the visibility amplitude declines.
- The decline need not be smooth – complicated emission will often have an oscillating, and decaying, visibility function.
- The visibility from a ‘zero-spacing’ interferometer (aka ‘a single dish’) equals the total flux density of the source.
 - For Stokes ‘I’, this cannot be less than all visibilities at longer spacings.
- The visibilities for a source with even symmetry about some axis must be real (phase 0 or 180) for fringes parallel to that axis.
 - An extreme case of this is a smooth circular source: The emission is even about all axes (through the center), so all visibilities are real.
- The visibilities for a source with odd symmetry about some axis must be imaginary (phase 90 or -90) for fringes parallel to that axis.

This is not possible for Stokes ‘I’, but is possible for Q, U, or V.



Some Thoughts to Ponder

- The complex visibility **amplitude** is independent of the source location*, and linearly related to source flux density.
- The complex visibility **phase** is a function of source location, and independent of source flux density.
- These two statements, restated, are:
 - 1) Doubling the source brightness doubles the visibility amplitude, but doesn't change the visibility phase
 - 2) Shifting the source position changes the phase, but does not change the visibility amplitude.*
- Reversing the elements of an interferometer negates the phase of the complex visibility, and leaves the amplitude unchanged.
- For those of you familiar with Fourier transforms, the equivalent statement is that:
 - 'As the source brightness is a real function, its Fourier transform is Hermitian'.

* Ignoring any attenuation due to the primary beam...



Visibilities Lead to Images ...

- The Visibility is a unique function of the source brightness.
- The two functions are related through a Fourier transform.

$$V_v(u, v) \Leftrightarrow I(l, m)$$

- How we go from visibilities to images is the subject of a later lecture.
- An interferometer, at any one time, makes one measure of the visibility, at baseline coordinate (u,v).
- 'A sufficient number of measures' of the visibility function (as derived from an interferometer) will provide us a 'reasonable estimate' of the source brightness.
- How many is 'sufficient', and how good is 'reasonable'?
- These simple questions do not have easy answers...



Final Comments ...

- The formalism presented here presumes much ... including that there is no motion between source and interferometer.
- Real interferometers:
 - Are on a rotating platform
 - Utilize real sensors (antennas)
 - Use wide bandwidths
 - Average data over time
 - Employ frequency downconversion
 - Have to deal with corruptions due to many causes...
- How we manage these issues are the subjects of my next lecture, and by following lectures.

