

Mosaicking and Data Combination

Adele Plunkett

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Talk outline

I. Setting the stageII. MosaickingIII. Image combinationVI. Summary and resources



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Wide field imaging (Preshanth Jagannathan)



Narrow band mosaicking and data combination (Adele Plunkett)



Wide band imaging (Joshua Marvil)





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Talk outline



There was a glut of information presented inthe lectures.



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About me, briefly







Photo: S. Radford, 1995 May.

I. Setting the Stage

What to expect with interferometric imaging in practice, and why you might need to "think outside of the box" (primary beam)



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Now consider several more complex

scenarios ...





1501





Astronomical examples that cover a "large", FOV area of the sky





Cheng et al. (2020)



Astronomical examples that cover a "large" , FOV area of the sky









I. Setting the stage: Scales

It's important to know what (angular) scales your observations will be sensitive to detect and discern.



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Equations

Primary Beam (∝ Field of View):

$$\theta_{PB} = (1.03 \rightarrow 1.2) \times \frac{\lambda}{D}$$

~ the diameter of the area imaged by one pointing of the interferometer (instantaneous FOV defined at first null of PB)

Maximum Recoverable Scale (MRS):



The "Spatial Period" of the **largest angular scale** Fourier component of the sky brightness measured by the interferometer.

In practice, \mathcal{L} represents what you can measure **well**. Quoted pre-factors vary, e.g. depending on uv-coverage; you can motivate $\mathcal{L} = 1/2$ with a simple toy model (Wilner & Welch 1994). ALMA uses $\theta_{MRS} = \frac{0.983\lambda}{L_5}$.

 b_{min} should be taken to be the shortest spacing at which there is **good** uv-coverage. ALMA uses L_5 .



Equations

Primary Beam (∝ Field of View):

$$\theta_{PB} = (1.03 \rightarrow 1.2) \times \frac{\lambda}{L}$$

 \sim the diameter of the area imaged by one pointing of the interferometer (instantaneous field of view)

Maximum Recoverable Scale (MRS):



The "Spatial Period" of the **largest angular scale** Fourier component of the sky brightness measured by the interferometer

Largest possible scale reliably recovered by an interferometer with antennas of diameter D



Takeaway messages

Primary Beam (∝ Field of View):

If your region of interest is larger than the FOV, you need to mosaic together many interferometer pointings.

Maximum Recoverable Scale (MRS):

If the Largest Angular Scale (LAS) of structures you are interested in are larger than this, you likely will need to get data from a more compact configuration of the interferometer, and/or single dish.

Angular Resolution:

Smallest scale structure you can distinguish.

A side note on MRS versus LAS: • ALMA documentation distinguishes MRS as a property of the observations, and LAS as a property of the observed source. • VLA documentation refers only to LAS, which applies to either case.



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Implications of (*u*,*v*) plane sampling, visually



Samples of V(u,v) are limited by the array, and Earth-sky geometry.

Outer boundary (longest baselines):

- Information only DOWN TO a certain small scale
- Resolution limit (θ_{HPBW})

Inner boundary (shortest baselines):

- Information only UP TO a certain recoverable scale (MRS)
- Extended sources are invisible

Irregular coverage:

- Sampling theorem violated
- Information missing

Recall talk by J. Marvil (Thursday), adapted from slide by D. Wilner



Implications of	Array	λ	PB	MRS	$ heta_{HPBW}$				
(<i>u,v</i>) plane	VLA	21 cm (L Band)	15'	36-970"	1-46"				
sampling,		3.6 cm (X Band)	3'	5-145"	0.2-7"				
numerically **		0.7 cm (Q Band)	40"	1-32"	0.04-1.5"				
	ALMA	1 mm (Band 6)	17.5″	0.2-12"	0.02-1.5"				
		0.4 mm (Band 9)	7"	0.08-4"	0.007-0.5"				
		Depends on:	Wavelength, antenna diameter	Wavelength, shortest baselines	Wavelength, longest baselines				

** Approximate reference values





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See talks by I. Heywood & P. Jagannathan for Radio Interferometer Measurement Equation









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The problem

- With each pointing of the interferometer, you measured only a single complex visibility $\left(\text{between } \frac{\lambda}{b+D} < \theta < \frac{\lambda}{b-D}\right)$
- SD observations have an equivalent problem...

Theory of Mosaicking







Theory of Mosaicking

See memo by Mason (2020) https://arxiv.org/pdf/2006.06549



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The problem

- With each pointing of the interferometer, you measured only a single complex visibility $\left(\text{between } \frac{\lambda}{b+D} < \theta < \frac{\lambda}{b-D}\right)$
- SD observations have an equivalent problem...

Solution

- Scan the telescope over the sky and measure the visibility V(u,v) function multiple times in different locations.
- Separate out the the Fourier modes contained in each measurement, increasing the mapped Fourier resolution & Maximum (useful) Recoverable Scale.

Theory of Mosaicking







See talk by P. Jagannathan for widefield imaging

II. Mosaicking

Several techniques for mapping a larger field of view (FOV)



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How to observe a larger FOV?

Option 1: Scan continuously, dumping correlations & antenna position information rapidly (scheme proposed by Ekers & Rots 1979)

- On-The-Fly Interferometry analogous to single dish "On-the-fly Mapping"
- Low observing overheads but high data rates
- Sometimes used today, especially for surveys at VLA (e.g. VLASS)







Option 2: Tile the sky with discrete pointings;

 Cornwell (1988) showed that this provides the full E&R (1979) information if the sampling is sufficiently dense

Hexagonal Grid





However, effects of more sparse sampling are modest, and often a viable option to increase survey speed, e.g. NVSS



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Making the mosaic image ("map")

Two widely-used methods for mosaic image reconstruction:

A.) Linear mosaic (AKA "stitching")

- Make dirty maps of each individual pointing
- Deconvolve individually
- Combine deconvolved maps with some PB correction

B.) Joint Mosaic Imaging

- Combine visibilities from all pointings in uv-space
- Generate single dirty map
- Deconvolve jointly



Making the mosaic image ("map"): A.) Linear mosaic





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Making the mosaic image ("map"): A.) Linear mosaic



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National Radio Astronomy Observatory Making the mosaic image ("map"): A.) Linear mosaic





Advantages

- Conceptually straightforward
- Each pointing can be calibrated and optimized individually: useful for *low frequency imaging* (high dynamic range, ionosphere)

Disadvantages

- Deconvolution is possible only to the depth of the individual pointings
- Not as effective at recovering shorter spacings (no Ekers & Rots information in the deconvolution)



Making the mosaic image ("map"): B.) Joint mosaic imaging



Advantages

- Uses all (u, v) info per overlap \rightarrow better beam, deeper clean
- All the (Ekers-Rots) information at every point in the sky utilized in deconvolution → more large-scale structure recovered
- Works well with on-the-fly interferometry data (many, many pointing centers)
- Naturally works well with heterogeneous arrays (antennas of different sizes)

Disadvantages

- You need to know your PB well
- Assumes a fairly stable PSF



Making the mosaic image ("map"): B.) Joint mosaic imaging

In practice... *

- Calibrate as you would do for a single pointing (e.g. pipeline)
- In tclean() use gridder='mosaic' for joint mosaic imaging
 - Uses Cotton-Schwab (major/minor cycle) algorithm
 - Specify the "deconvolver" parameter
 - *deconvolver='hogbom'* default, good for poor psf and compact sources
 - deconvolver='multiscale' for complex, extended emission.
 - deconvolver='clark' faster
 - gridder='mosaic' is necessary for any "heterogeneous array" imaging using tclean() in CASA (even single field!)
 - Fully supported for ALMA; possible for other telescopes if you use a little bit of care.
- Other recommended tclean() parameter choices: mosweight=True; and for cubes, perchanwtdensity=True + briggsbwtaper=True.





Deconvolution

** For "Widefield Imaging", see talk by P. Jagannathan Deconvolution of extended sources (a primary scenario for mosaicking) is tricky. **

Why? In general the "CLEAN model" is not your best estimate of the sky; the reconvolved CLEAN model+residuals is.

As a result...

- It may take a long time to clean a spectral line cube
- Multi-scale is often a good option tclean(deconvolver='multiscale') [Cornwell+ 2008]
- It helps to have good uv coverage, a judiciously chosen clean box, & careful monitoring (interactive)
- Automatic CLEAN masking can help a lot! tclean(mask='automultithresh') [Kepley+ 2020]
- You may need to clean deeply (e.g. 1.5σ) for extended emission.
- For self-cal using the CLEAN model for a mosaic, clean more conservatively.



III. Image Combination: Motivation

Some words (pictures) on why single dish is important for "synthesis imaging"



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Zero-spacing problem = missing information at short baselines (<Lmin)

Slide by Alvaro Hacar



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- Zero-spacing problem = missing information at short baselines (<Lmin)
- Solution: Fill up the gap combining config./arrays/telescopes

Slide by Alvaro Hacar







See memo by Mason (2020) https://arxiv.org/pdf/2006.06549



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III. Image Combination: In practice

"Short-spacing correction"



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Image combination: Antennas





Image combination: Configurations



Diagram credit: ALMA (ESO/NAOJ/NRAO)



But first... Image combination does not have to include antennas of different sizes.



See ALMA Technical Handbook, Section 7.8-7.9



But first... Image combination does not have to include antennas of different sizes.

	θ_{res} (arcsec)	θ_{LAS} (arcsec)	Array combination	1 ime ratios	1 Iotal 1 ime					
>	0.042	< 0.496	C43-10	1	$1.0 \times \Delta_{extended}$					
	0.042	> 0.496	-	-	-					
0	0.057	< 0.814	C43-9	1	$1.0 \times \Delta_{extended}$					
a)	0.057	0.814-4.11	C43-9 + C43-6	1: 0.21	$1.21 \times \Delta_{extended}$					
arr	0.057	> 4.11	-	-	-					
	0.096	< 1.42	C43-8	1	$1.0 \times \Delta_{extended}$					
2n	0.096	1.42-6.7	C43-8 + C43-5	1: 0.22	$1.22 \times \Delta_{extended}$					
H	0.096	> 6.7	-	-	-					
A1	0.211	< 2.58	C43-7	1	$1.0 \times \Delta_{extended}$					
2	0.211	2.58 - 11.2	C43-7 + C43-4	1: 0.23	$1.23 \times \Delta_{extended}$					
A	0.211	> 11.2	-	-	-					
	0.306	< 4.11	C43-6	1	$1.0 \times \Delta_{extended}$					
>	0.306	4.11-16.2	C43-6 + C43-3	1: 0.25	$1.25 \times \Delta_{extended}$					
	0.306	16.2-66.7	C43-6 + C43-3 + 7-m	1: 0.25: 0.6	$1.8 \times \Delta_{extended}$					
0	0.306	> 66.7	C43-6 + C43-3 + 7-m + TP	1: 0.25: 0.6: 1.0	$2.3 \times \Delta_{extended}$					
3	0.545	< 6.7	C43-5	1	$1.0 \times \Delta_{extended}$					
7	0.545	6.7-22.6	C43-5 + C43-2	1: 0.26	$1.26 \times \Delta_{extended}$					
μ	0.545	22.6-66.7	C43-5 + C43-2 + 7-m	1: 0.26: 1.21	$2.5 \times \Delta_{extended}$					
2r	0.545	> 66.7	C43-5 + C43-2 + 7-m + TP	1: 0.26: 1.21: 2.1	$3.3 \times \Delta_{extended}$					
(1	0.918	< 11.2	C43-4	1	$1.0 \times \Delta_{extended}$					
	0.918	11.2-28.5	C43-4 + C43-1	1: 0.34	$1.3 \times \Delta_{extended}$					
	0.918	28.5-66.7	C43-4 + C43-1 + 7-m	1: 0.34: 2.4	$3.7 \times \Delta_{extended}$					
	0.918	> 66.7	C43-4 + C43-1 + 7-m + TP	1: 0.34: 2.4: 4.0	$5.3 \times \Delta_{extended}$					
	1.42	< 16.2	C43-3	1	$1.0 \times \Delta_{extended}$					
	1.42	16.2-66.7	C43-3 + 7-m	1: 2.4	$3.4 \times \Delta_{extended}$					
	1.42	> 66.7	C43-3 + 7-m + TP	1: 2.4: 4.1	$5.1 \times \Delta_{extended}$					
	2.3	< 22.6	C43-2	1	$1.0 \times \Delta_{extended}$					
	2.3	22.6-66.7	C43-2 + 7-m	1:4.7	$5.7 \times \Delta_{extended}$					
	2.3	> 66.7	C43-2 + 7-m + TP	1:4.7:7.9	$8.9 \times \Delta_{extended}$					
	3.38	< 28.5	C43-1	1	$1.0 \times \Delta_{extended}$					
	3.38	28.5-66.7	C43-1 + 7-m	1:7	$8.0 \times \Delta_{extended}$					
	3.38	> 66.7	C43-1 + 7-m + TP	1:7:11.9	$12.9 \times \Delta_{extended}$					
	12.5	< 66.7	7-m	1	$1.0 \times \Delta_{extended}$					
	12.5	> 66.7	7-m + TP	1:1.7	$2.7 \times \Delta_{extended}$					

 $\mathbf{T} \rightarrow \mathbf{1} \mathbf{T}$

Δ

ALMA interferometry

Total

Includes

Power (TP)

See: ALMA Technical Handbook, Table 7.5 (for 100 GHz) For VLA: https://science.nrao.edu/facilities/vla/pro posing/configpropdeadlines

Configuration changes at VLA and ALMA





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So many combination options...





Photo credits: ALMA: A. Plunkett; VLA: NRAO/AUI/NSF;
 IRAM 30m: © IRAM,K.Zacher; FCRAO: https://www.umass.edu/; SMA: SMA; ACA: A. Plunkett;
 LMT: http://lmtgtm.org/; NRO: NAOJ; GBT : Jay Young; CARMA: A. Plunkett; NOEMA: IRAM



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Data Combination methods







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Methods: We tested and evaluated 5 methods

Methodology ^a	Domain ^b	Method	Task Name	I	Input				
				Interferometry	SD				
Before	F/I	SDINT	sdintimaging	Vis.	Image	Image			
	F	TP2VIS	tp2vis [°] tclean	Vis. Vis.	SD image Pseudovisibilities	Pseudovisibilities Image			
During	$\mathbf{F} + \mathbf{I}$	MACF	tclean feather	Vis. Image	Image as model Image	Image Image			
After	F	Feather	feather	Image	Image	Image			
Aner	I	FSSC	(script)	Image	Image	Image			

Table 1 Summary of Data Combination Methods

Notes.

^a Indicates combination before, during, or after image deconvolution.
^b Fourier ("F") or image ("T") domain in which the method operates.

^c Only available in CASA after importation of the TP2VIS package.

See Plunkett et al. (2023)



Results (qualitative)



See Plunkett et al. (2023)



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Results (qualitative)

We'll focus here on Feather and Sdintimaging (two methods in CASA)

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See Plunkett et al. (2023)





III. Image Combination: Feather

"The term "feathering" is likely derived from the similarity with birds' feathers, which are dense at the center and very light at the edge." Cotton (2017)



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		189	172	169	152	149	132	129	112	109	92	89	72	69	52	49	32	29	12	9			-		
	-	188	173	168	153	• 148	133	128	113	108	93	88	73	68	53	48	33	. 28	13	8			-		
2	- ,	187	174	167	154	147	134	127	114	107	. 94	87	74	67	54	47	34	27	14	7			-		0.05
	-	186	175	166	155	146	135	126	115	106	95	86	75	66	55	46	35	88	15	6		•	1		
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1	- ' *	184	177	164	157	144	137	124	• 117	104	97	84	77	64	57	44	37	24	17	4	•			-	-
		183	178	163	158	143	138	123	118	103	98	• 83	78	63	58	43	38	23	18	3			-	-	-
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0.1

GLON (degrees)

GLAT (degrees)

Feather: A basic schema





MACF: Model Assisted CLEAN with Feather: A basic schema







The newest combination technique in CASA



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sdintimaging An over-simplified schematic...



Learn more: https://casadocs.readthedocs.io/en/stable/api/tt/casatasks.imagi ng.sdintimaging.html



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Image analysis [[some definitions]]



See Plunkett et al. (2023), Sec. 5.2: Accuracy Parameter and Fidelity: Assessing Flux Recovery





A few results on data combination testing





Image combination considerations

- ALMA Observing Tool helps the user set up the observations on multiple configurations; VLA users should independently indicate which configurations are needed
- Sensitivities should be comparable among the images that are being combined, therefore integrations times should scale accordingly.
- There are a few scale factors (sdfactor in feather, sdgain in sdintimaging) that can be tested.
- The greater the overlap in baselines/ SD diameter, the better.
- If you know that there is extended emission beyond your FOV, you should consider image combination with SD (even if you only care about smaller scales).
- Make the SD map extend beyond the interferometry map.



Summary

- Consider FOV, PB, MRS, LAS, and HPBW *
- If your region of interest is larger than the FOV, you need to **MOSAIC** together many interferometer pointings.
- For "large" structures, you likely will need to **COMBINE** data from a more compact configuration of the interferometer, and/or single dish.
 - Feather and sdintimaging are two techniques

* Abbreviations?! Next slide.



Abbreviations

- HPBW: Half-power beam width (like FWHM)
- FOV: Field of view
- PB: Primary Beam
- MRS: Maximum Recoverable Scale
- LAS: Largest Angular Scale
- **PSF**: Point spread function



Resources

- Essentials of Radio Astronomy (<u>link</u>), especially section 3.7
- Ekers & Rots (1979) (<u>link</u>)
- Mason (2020) "Imaging Spatially Extended Objects with Interferometers: Mosaicking and the Short Spacing Correction" (<u>link</u>)
- Cotton (2017) on Feather (<u>link</u>)
- Rau et al. (2019) on Sdintimaging (link)
- Plunkett et al. (2023) (<u>link</u>)
 - Try out Data Combination using scripts at DataComb Github.
- ALMA Technical Handbook (<u>Cycle 10 link</u>)
- VLA configurations and mosaicking guide
 - VLA interactive configuration visualizations



Getting started

- 1. Check your interferometry and SD images.
- 2. Run FEATHER
 - a. **INPUTS**: interferometry image; SD image
 - b. Advantage: It's fast!
 - *c. Disadvantage*: If your interferometry image isn't great, the negatives might remain.
- 3. Run SDINTIMAGING
 - **a. INPUTS**: interferometry calibrated measurement set; SD image
 - *b.* Advantage: It's making the interferometry image as you go.
 - *c. Disadvantage*: It will take more time than feather, because you're "CLEANing" again.
- 4. Test out MACF
 - a. INPUTS (TCLEAN): calibrated measurement set as "vis", SD image as "startmodel"
 - b. Then run FEATHER (see #1)
 - c. Advantage/disadvantage: Does a better clean because it starts out with a model, but sometimes this still isn't enough to make a good interferometry image.



FEATHER, a few notes

https://casaguides.nrao.edu/index.php?title=M100 Band3 Combine 6.5.4

- Inputs should be "*.image" (casa images) format
 - importfits and exportfits
- In Tclean step: Combined 12m+7m image, or any interferometry image, should have restoration=True, restoringbeam='common'
 - Otherwise
- To make a quick assessment of the images, smooth to a common beamsize (the larger beam size).
 - Use imsmooth for the two input images and the output image of Feather
 - Then plot the spectra
- Check units of input Single Dish image (mJy/beam, Jy/beam, Jy/pixel, mK, K?)
 - When making any comparisons, make sure the units are the same.

SDINTIMAGING, a few notes

<u>https://casadocs.readthedocs.io/en/latest/notebooks/image_combination.h</u> <u>tml</u>

- SD image needs "per channel beams"
- *If imaging a cube:* SD image must be a cube with the same spectral grid as the one you are trying to create.
- Units of SD image should (*probably?*) be Jy/beam
- SDINTIMAGING uses many parameters common to TCLEAN (check weblog to see what TCLEAN parameters were used)
 - Possibly, masking can be less specific (i.e. a pb-based mask at the 0.3 gain level)
- There was once an issue with CASA '6.2.0' and MFS mode. *Not sure if that was resolved...*