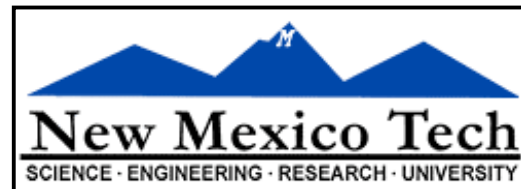


ARRAY DESIGN AND SIMULATIONS



Craig Walker NRAO

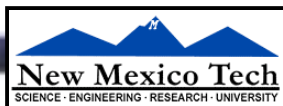
Based in part on 2008 lecture by Aaron Cohen



TALK OUTLINE

STEPS TO DESIGN AN ARRAY

- Clarify the science case
 - Determine the technical requirements for the key science
- Specify the resolution, field of view, sensitivity, frequency range
- Specify the antenna type, size, and performance
- Choose site
- Design and optimize the configuration
- Also required, but not covered further
 - Find money
 - Hire the best engineers you can find!
 - Design feeds, receivers, LO/IF systems, data transmission
 - Design a correlator

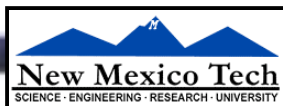


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SCIENCE REQUIREMENTS

- No one array can do everything. What is yours for?
- Extreme examples:
 - Epoch or reionization requires low resolution, low frequency
 - Star formation, black holes, accretion disks and jet launch require high resolution and high frequency
- Determine the technical requirements of each major element of the science case
- Generate specifications for the array based on the science drivers
- Don't be surprised when the actual science done differs from the Science case.
 - Make the array flexible.



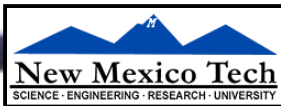
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CASE STUDY

SKA KEY SCIENCE DRIVERS

- SKA project identified 5 key science drivers
 1. Cradle of Life
 - Astrobiology, planet detection, SETI
 2. Probing the Dark Ages
 - Epoch of reionization, redshifted CO, first AGNs
 3. The origin and evolution of Cosmic Magnetism
 4. Strong field tests of gravity using pulsars and black holes
 5. Galaxy evolution, cosmology and dark ages
 6. (Exploration of the Unknown)



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TECHNICAL REQUIREMENTS OF SKA KEY SCIENCE PROJECTS

- A very big array with very broad capabilities is required to do everything!
- Cost in billions of dollars.

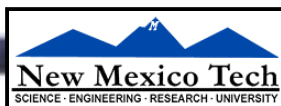
Table 4. Desired specifications for the SKA

KSP ID	KSP Description	Frequency Range GHz						FoV	Sensitivity	Survey Speed	Resn.	Base-line	Dyn. Range	Polarisation Driver
		0.1	0.3	1.0	3.0	10	30							
								deg ²	m ² /K	deg ² m ² K ⁻²	mas	Km		
1	The Dark Ages													
1a [†]	EoR	—								$>3 \times 10^3$		1	*	**
1b	First Metals					—		0.003	15,000		50	125		
1c	First Galaxies & BHs			—					20,000		10	4500	*	**
2	Galaxy Evolution, Cosmology & Dark Energy													
2a [†]	Dark Energy			—						6×10^8		5		
2b [†]	Galaxy Evolution		—						20,000	1×10^8		10		
2c	Local Cosmic Web			—						2×10^7		0.5		
3	Cosmic Magnetism													
3a [†]	Rotation Measure Sky			—						2×10^8		10-30		**
3b	Cosmic Web	—								1×10^8		5		**
4	GR using Pulsars & Black Holes													
	Search		—							1×10^8		< 1		
4a [†]	Gravitational Waves		—		—			*	$> 15,000$		1	200		**
4b	BH Spin		—		—			†	10,000			—		**
4c [†]	Theories of Gravity		—		—				$> 15,000$		1	200		**
5	Cradle of Life													
5a [†]	Proto-planetary Disks					—		0.003	10,000		2	1000		
5b	Prebiotic Molecules			—	—			0.5-1	10,000		100	60		
5c	SETI			—	—			†						
6	Exploration of the Unknown	—	—	—	—	—	—	Large	Large	Large				

[†] Headline science, see Section 3.2

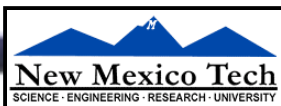
* See Section 5.1.8 for explanation of Dynamic Range drivers

** See Section 5.1.6 for explanation of Polarisation Purity drivers



RESOLUTION

- Resolution = λ/B_{max}
- High resolution is used to study hot or non-thermal sources and for astrometry
 - Requires high frequencies and long baselines
 - Radio arrays can use unlimited baseline lengths
 - VLBI commonly uses baselines up to near an Earth diameter
 - Longer baselines possible with spacecraft (HALCA)
- Low resolution is required to see low brightness sources
 - Brightness temperature $S = 2kT_B\Omega / \lambda^2$
 - Ω is set by the smaller of the beam and the source
 - To detect low T_B sources, need large Ω (short baselines)
 - Cannot detect low brightness, compact sources - too weak
- A general purpose instrument will need a wide range of resolutions



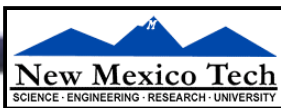
EXTREME BASELINE EXAMPLES



- ALMA compact configuration
- Good for large, diffuse sources



- VLBA - Continental or more in scale
- Good for very high brightness sources and astrometry.

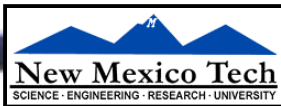


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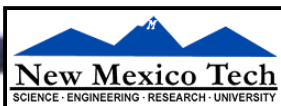
SENSITIVITY AND SURVEY SPEED

- The sensitivity and survey speed requirements will determine the scale and cost of the array
- Sensitivity depends on collecting area, system temperature and bandwidth $(N_{\text{ant}} D^2 / T_s) \Delta\nu^{0.5}$
 - This is what matters for sources smaller than a beam
- For observations over many beam areas, the “survey speed” matters
 - Field of view times sensitivity squared
 - $N_{\text{beams}} \lambda^2 (N_{\text{ant}} D / T_s)^2 \Delta\nu$
 - N_{beams} is the number of independent primary beams
 - Maximize for surveys
 - Maximize for sources that are large - big mosaics
 - Favor small antennas and multiple beams
 - Might choose to sacrifice some sensitivity (eg high T_s)



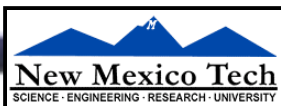
FIELD SIZE

- Reasons for large fields of view:
 - Surveys - want to cover lots of sky
 - Large sources (galactic clouds, nearby galaxies etc)
- Reasons for small fields of view:
 - Less trouble with confusion
 - Fewer baselines required, easier processing
 - Can afford more sensitive receivers, wider bandwidth etc.
- For wide fields:
 - Small antennas with large beams - but need many
 - Multiple beam receiving systems - lots of electronics
- For small fields can use large individual antennas
 - But cost scales faster than area, so don't go too big



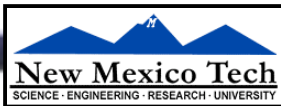
FIELD SIZE EXAMPLES

- EVLA: 25m antennas - primary beam 30' at 1.4 GHz.
 - Good for sensitivity and wide frequency coverage
 - Slow for surveys
- ALMA: 50 X 12m antennas + 12 X 7m antennas (+ 4 X 12m for total power)
 - Compromise between sensitivity for extragalactic sources vs ability to observe large galactic objects
 - The 7m antennas and total power antennas were added by Japan to do large sources
- VLBA: 10 X 25m antennas, but individual fields limited by delay and rate smearing to a few arcseconds. Not for blind surveys!
- LWA, MWA, LOFAR: Fixed aperture arrays. In principle, with enough electronics, could observe the whole sky.
- WSRT, ASKAP: Feed arrays for multiple beaming



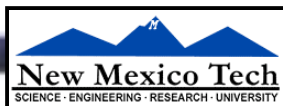
COST VS ANTENNA DIAMETER

- Traditional antenna cost scales as $D^{2.7}$
- Number of antennas scales as D^{-2} for constant area
- Total cost for all antennas scales as $D^{0.7}$ Favors smaller antennas.
- But many items scale with N_{ant} and N_{beams}
 - Receiver electronics, LO/IF, data transmission, station sections of correlator
- Baseline sections of correlator scale with N_{beams} and N_{ant}^2
- Optimum has a broad minimum favoring 10 to 20 m antennas.



ANTENNA DESIGN: FREQUENCY RANGE

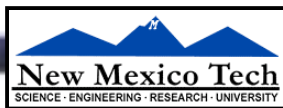
- The frequency range strongly influences the type and cost of the antennas and receivers
 - Low frequencies (< 3 GHz very roughly)
 - Less demanding for accuracy
 - Can get large collecting area at low cost
 - Can use aperture arrays of fixed elements
 - Limited by ionosphere at low end
 - High frequencies (> 3 GHz very roughly)
 - Almost certainly will use dishes and cryogenic receivers
 - Higher frequencies require more accurate surfaces
 - High demands on pointing accuracy
 - Complicated choice - still not clear for SKA



ANTENNA TECHNOLOGIES



- MWA 80-300 MHz. Steered by phasing fixed elements
- MeerKAT prototype 15m composite antenna (South Africa)

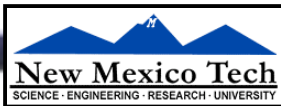


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LOCATION

- Location is an important decision with large performance, operations, financial, and political considerations
- At high frequencies, want high altitude and dry climate (ALMA)
- At low frequencies, want protection from RFI (SKA)
- At low frequencies, avoid regions with worst ionosphere (SKA etc)
- Site must be large enough to accommodate the array
- Need reasonable access and place to live for staff and their families
 - Not everyone can work remotely
- Need power, communications. Expensive if need to provide own, especially to outer stations.

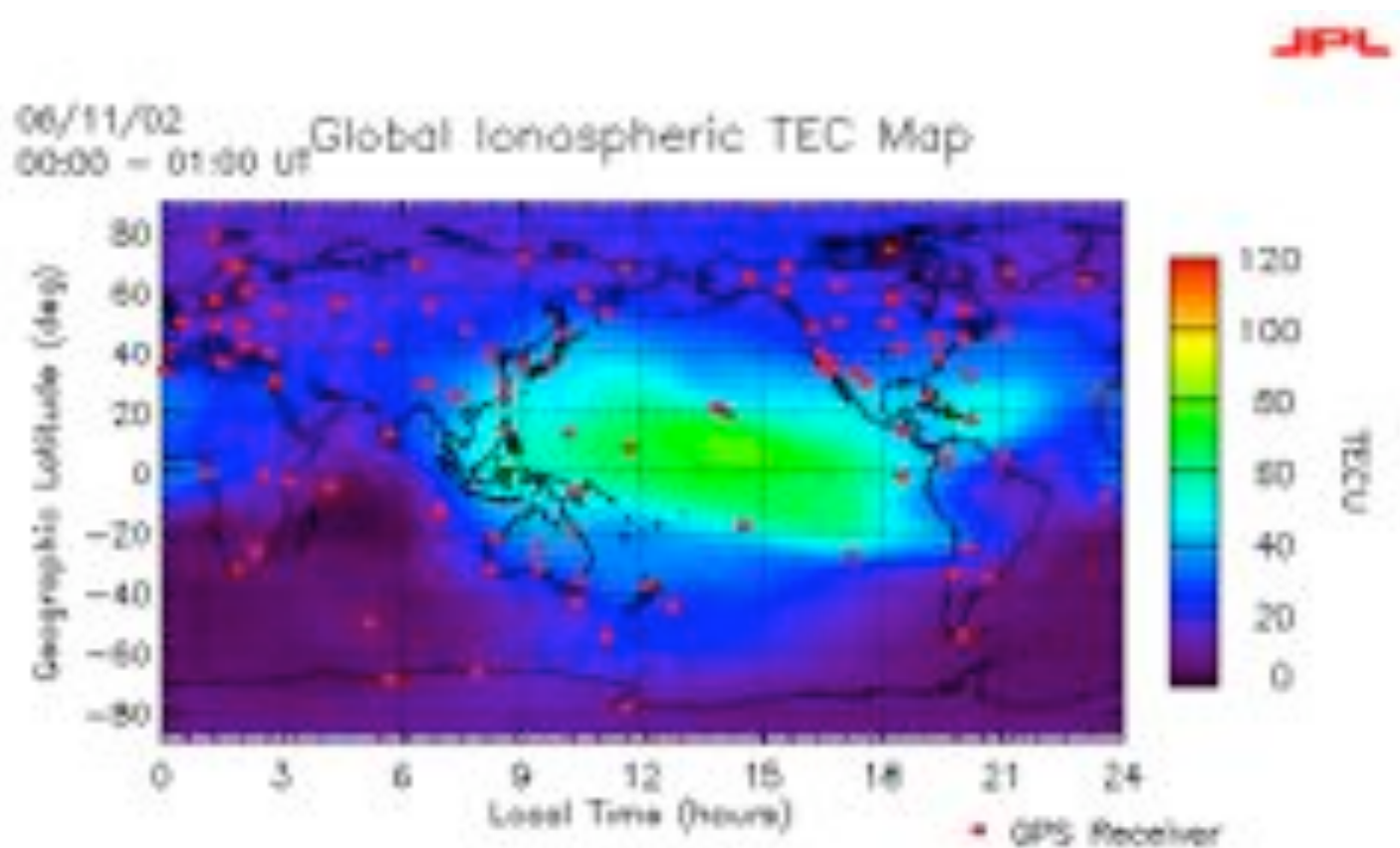


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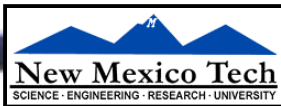
IONOSPHERE

- Can seriously complicate the calibration of low frequency data
- Concentrated near the subsolar point but on the geomagnetic equator



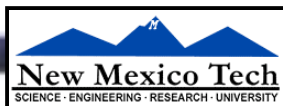
TROPOSPHERE

- At high frequencies, the troposphere is the main problem for calibration
- The tropospheric delay is dominated by the dry atmosphere
 - But that is fairly stable
- Water vapor is highly variable, so limits phase stability
 - For a high frequency array, chose a site with low water vapor
 - Want an arid location at high altitude
 - EVLA at 2114 m
 - ALMA at 5000 m in the Atacama Desert
 - Want phase stability
 - Usually, but not always correlates with opacity



RADIO FREQUENCY INTERFERENCE

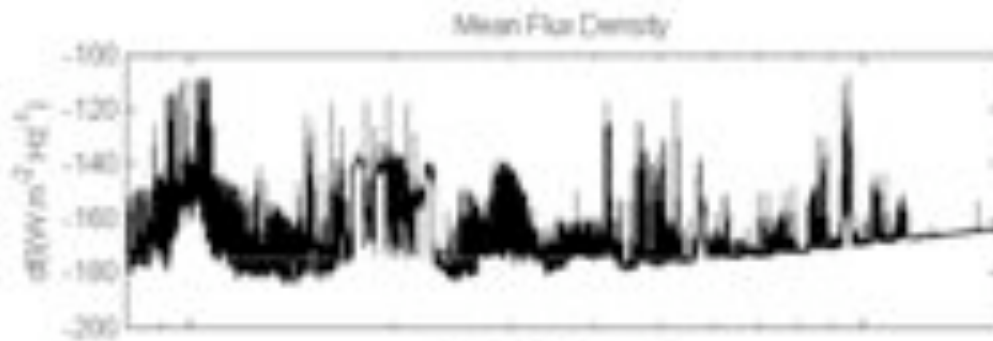
- RFI is a big problem especially on short baselines at low frequencies.
 - Non-closing corruption of data
 - Time variable
 - Corruption of spectra
- It is becoming more of a problem at high frequencies
- Want isolation from civilization
- Want terrain shielding (surrounding mountains good)
 - Can't hide from satellites
- Problem is reduced for long baselines
 - Sources different at each antenna - don't correlate
 - Attenuated by high fringe rates (differential Doppler shifts)
 - But can saturate receivers



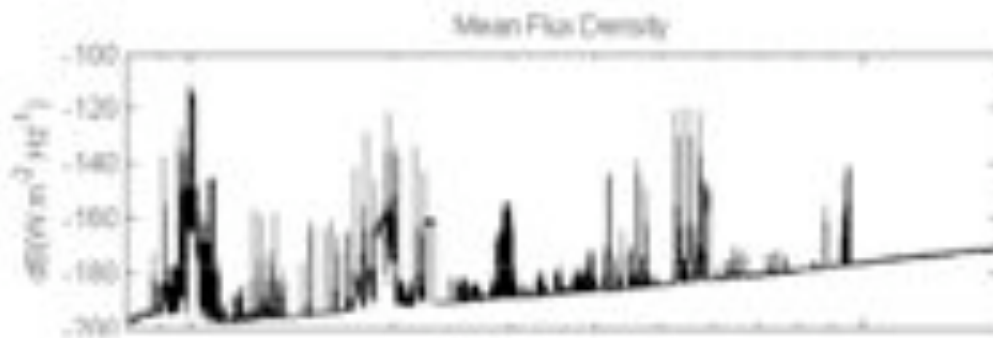
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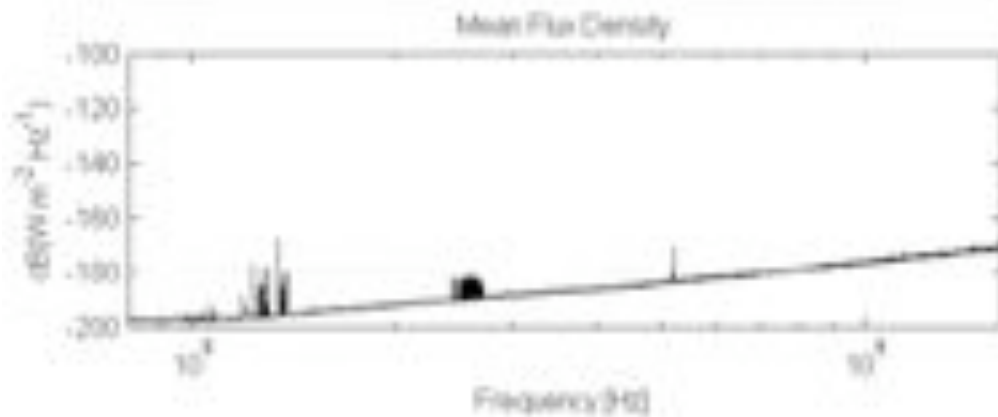
RFI EXAMPLES



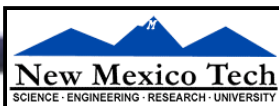
Large city
population: several million



Town
population: several thousand



Candidate SKA core site
population: a few

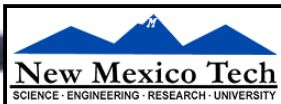


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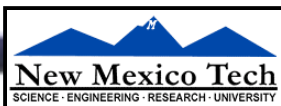
SITE CONSTRAINTS

- Sites for all antennas need to be chosen together for good UV coverage
- Site issues vary on different scales
 - For short baselines (10s of km), want large flat area
 - Full freedom to position antennas as desired
 - For 10s to 100s of km, will need individual sites
 - Need to conform to power, communication, road access
 - Need to avoid cities, wilderness areas, military areas
 - The sites will need to be within a few km of the desired position for the configuration, but many configurations work
 - For long baselines, site position not critical to 10s or 100s of km
 - Usually can find some place that works
 - Main constraints are major geographic features like oceans



NUMBER OF ANTENNAS AND SITES

- Sensitivity issues
 - Required sensitivity
 - Required field of view or survey speed
 - Cost optimization - N vs D
- Imaging issues
 - Required baseline range and UV coverage
 - Types and complexity of target sources
 - Impact of confusion
- Each antenna separate or clusters?
 - May depend on distance from center
 - May be cost and correlator size driven

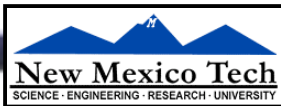


RECONFIGURE?

- Allows wide baseline range with fewer antennas
 - EVLA 1km to 35km arrays - 27 antennas but 72 pads
- Constrains observing to certain times by resolution
- Requires some sort of transporter
- SKA not planned to reconfigure
- “Configurations” (EVLA) vs continuous zoom (ALMA)



ALMA transporter

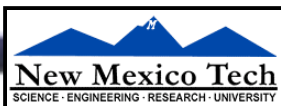


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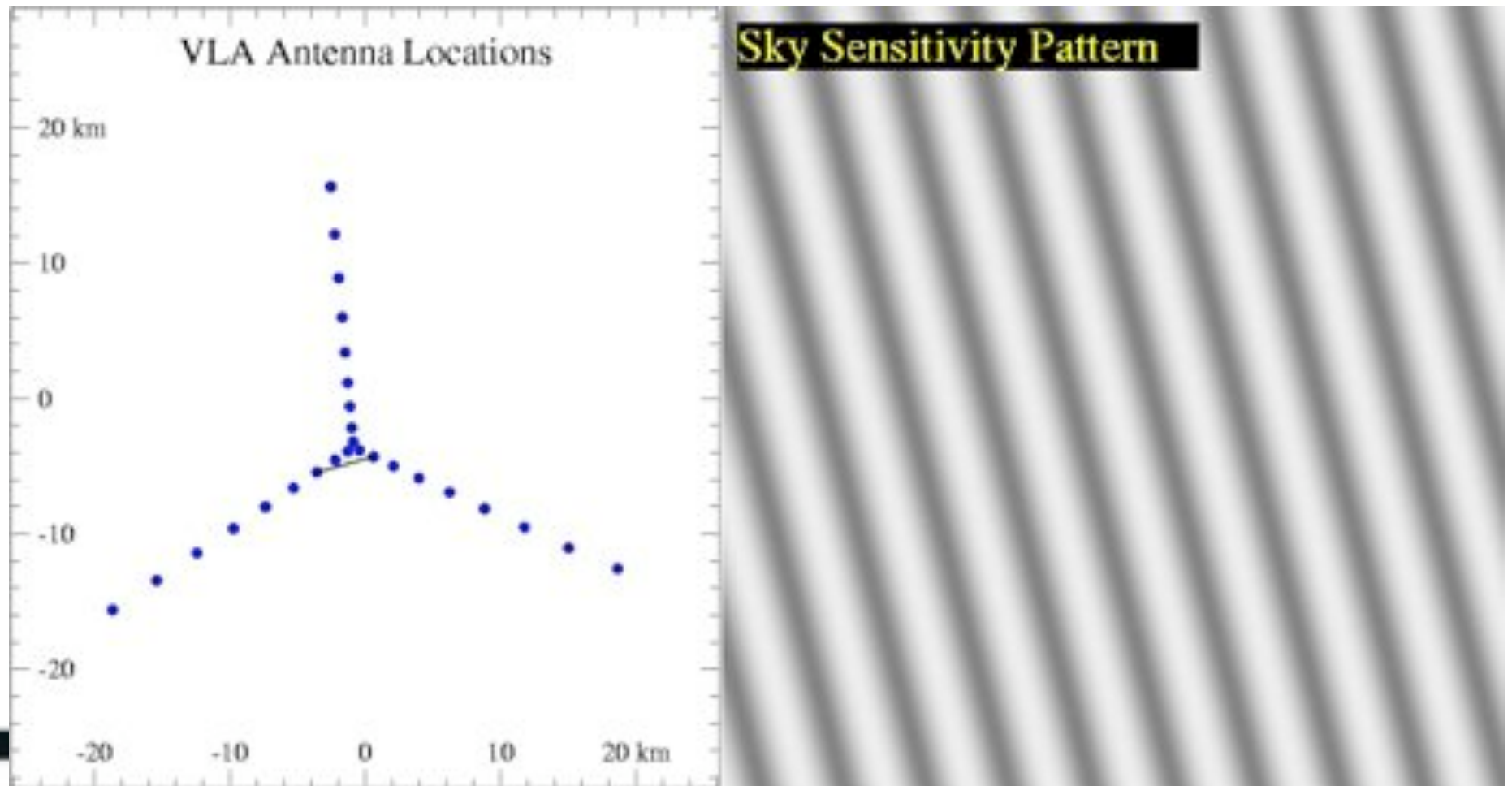
CONFIGURATION

- Must determine where to put the antennas
- Goals
 - Obtain adequate UV coverage to meet the scientific goals
 - Minimize cost - probably means minimize separate stations
- Constraints
 - Available geography
 - Available infrastructure (power, communication, roads)
- What are the required properties and capabilities?
 - Snapshot coverage or only full tracks
 - Implies baseline range
 - Brightness sensitivity and resolution range
 - Centrally condensed or more uniform distribution
 - Reconfigurable?
- Once configuration is chosen, can't freely move individual antennas
 - Optimizing baselines



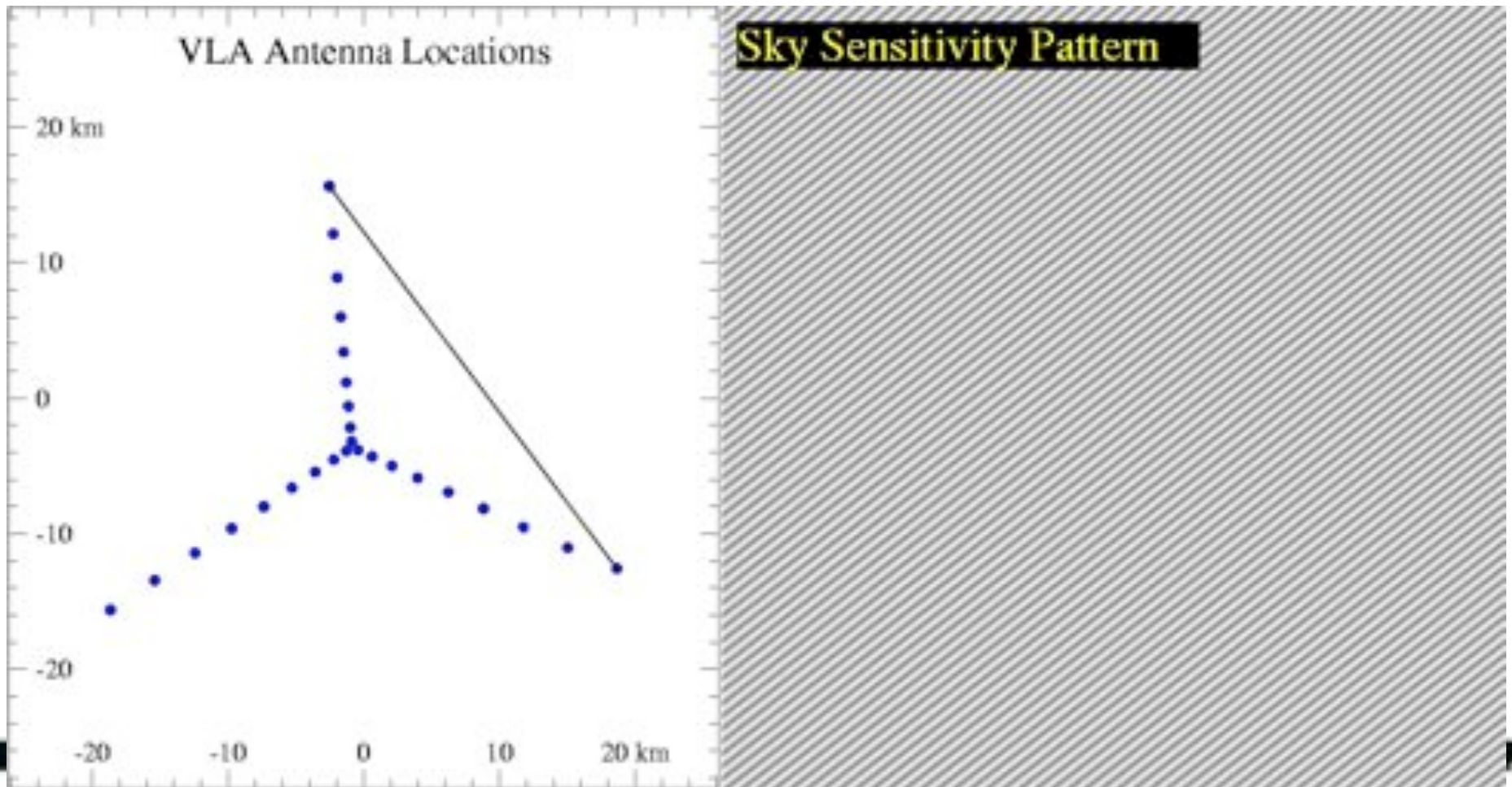
UV COVERAGE: SINGLE SHORT BASELINE

A single baseline has a sinusoidal sensitivity pattern across the sky, oscillating between constructive and destructive interference.



UV COVERAGE: SINGLE LONG BASELINE

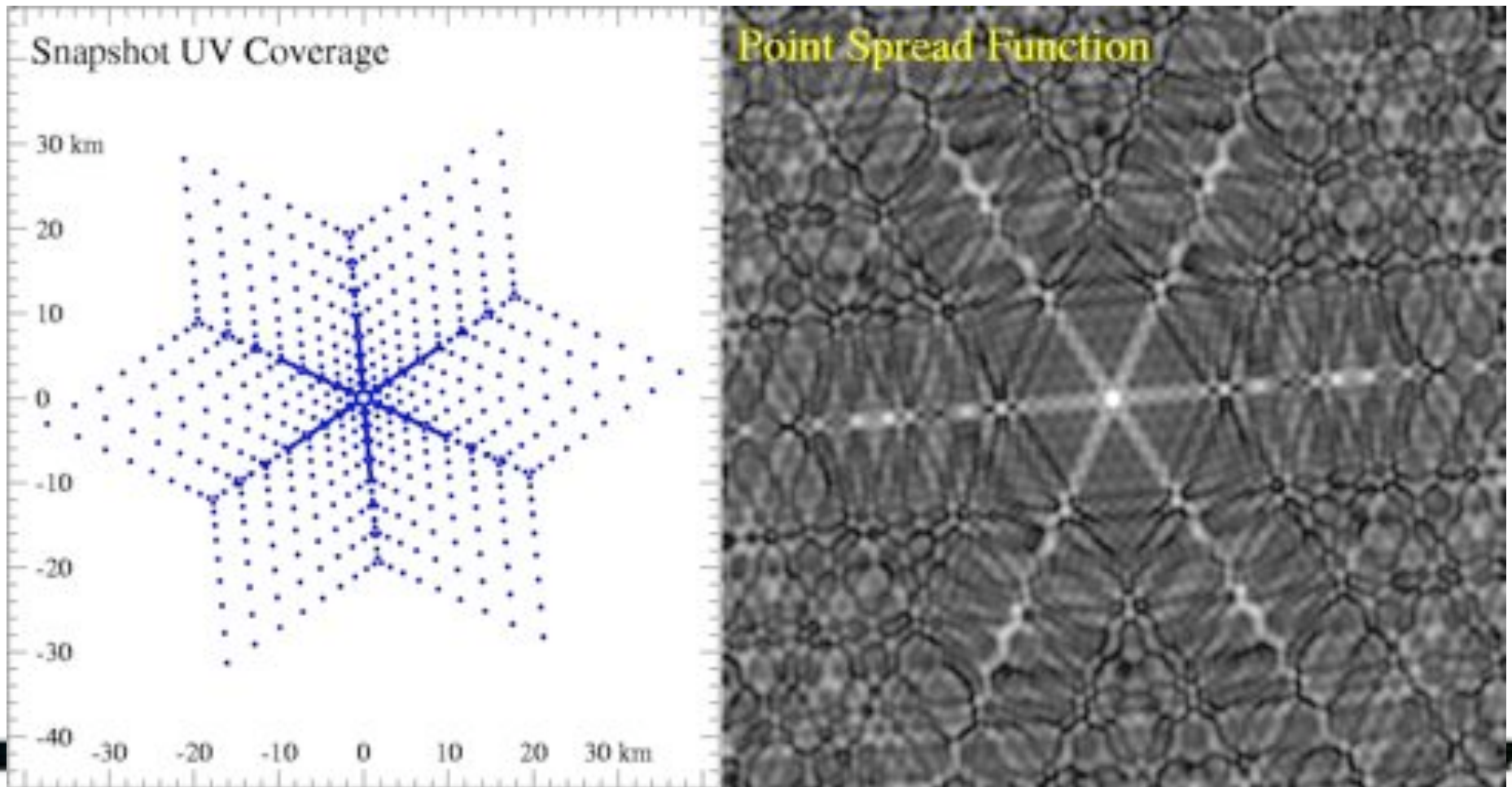
The oscillations in the sensitivity pattern have the same direction as the baseline, with a period determined by the baseline length in wavelengths



UV COVERAGE: SNAPSHOT

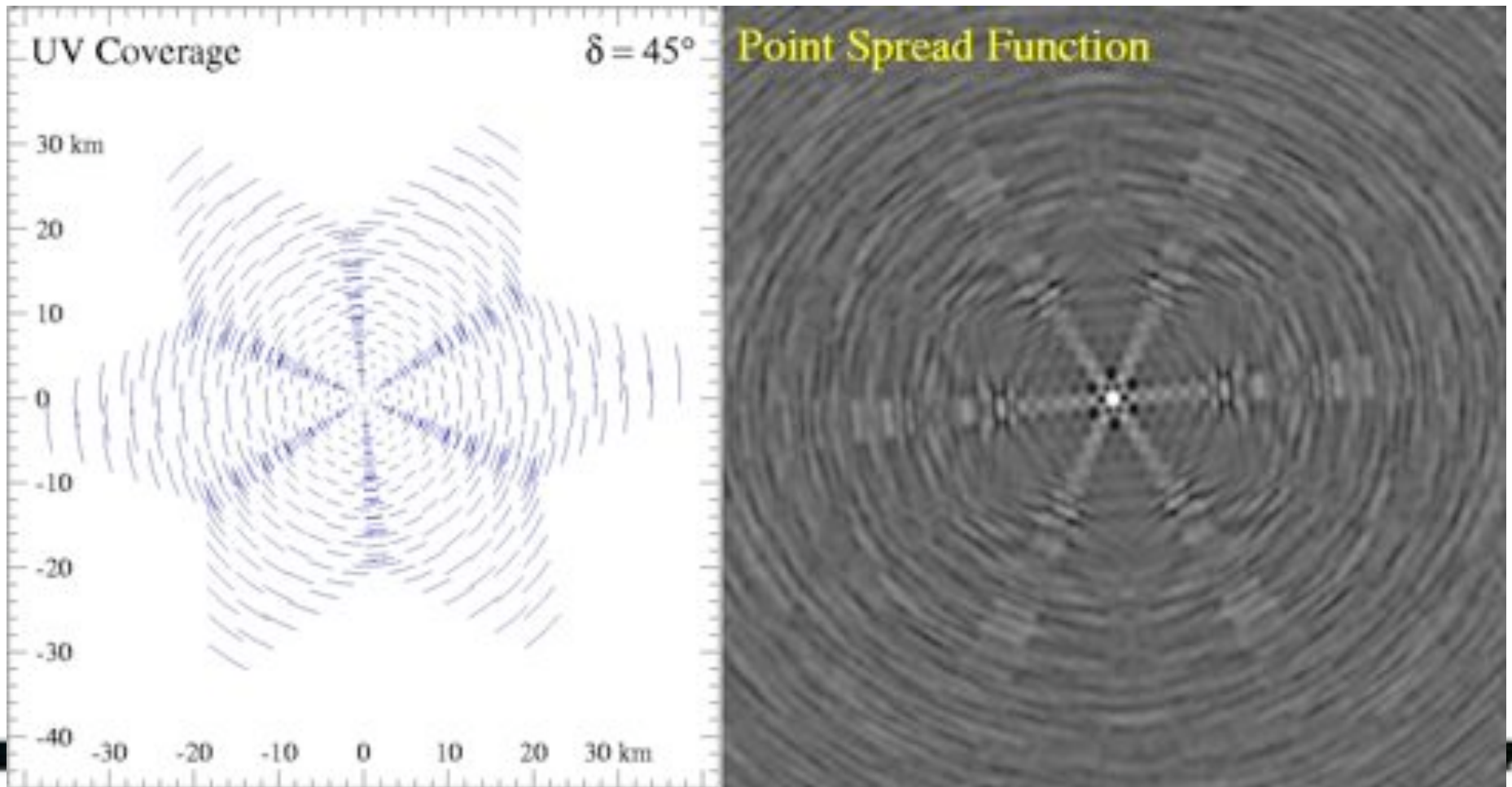
The uv-coverage is the set of all baseline vectors.

The synthesized beam (PSF) is the sensitivity pattern of all baselines.



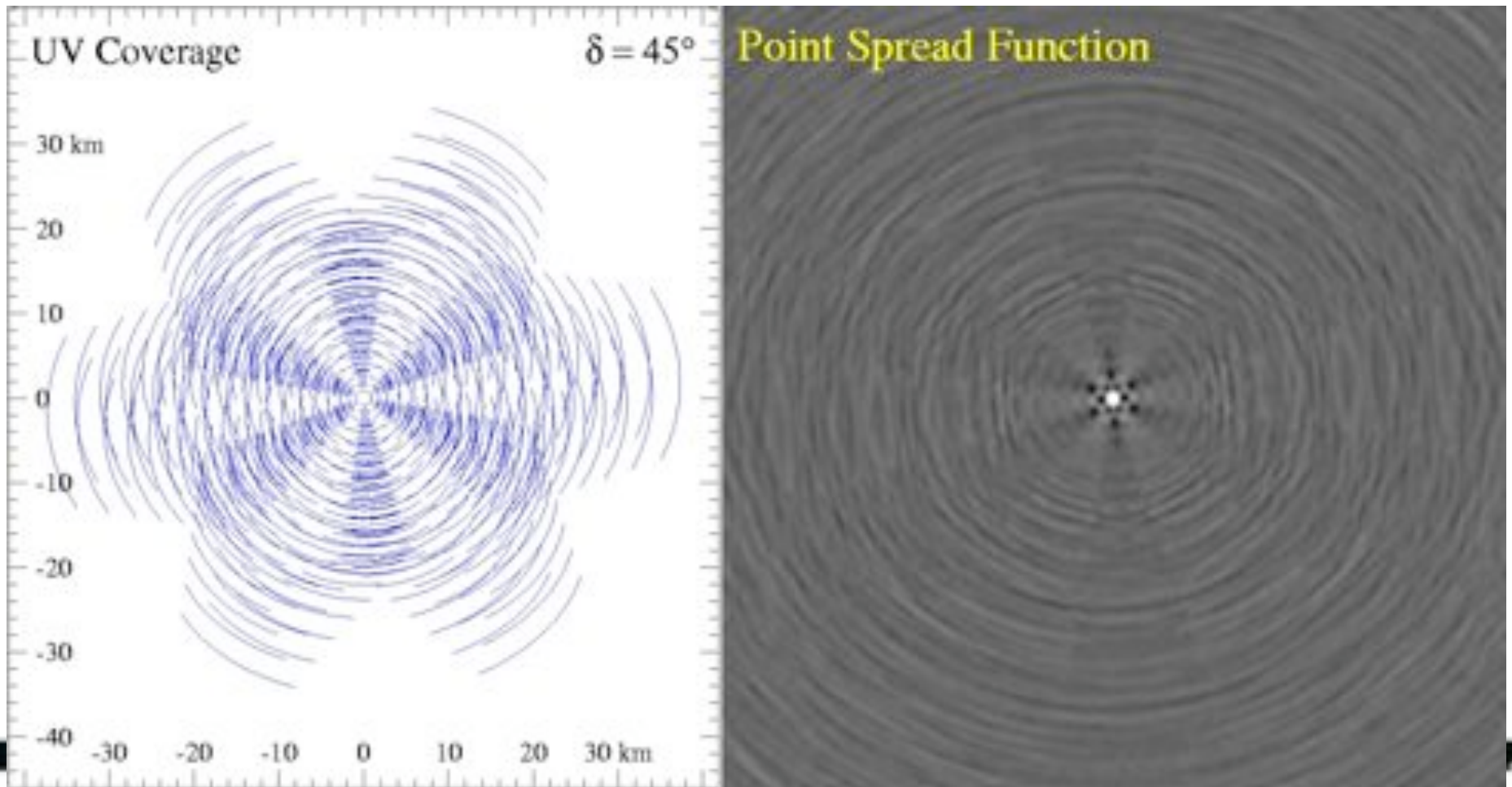
UV COVERAGE: SHORT TRACK

1 Hour Synthesis Observation



UV COVERAGE: MEDIUM TRACK

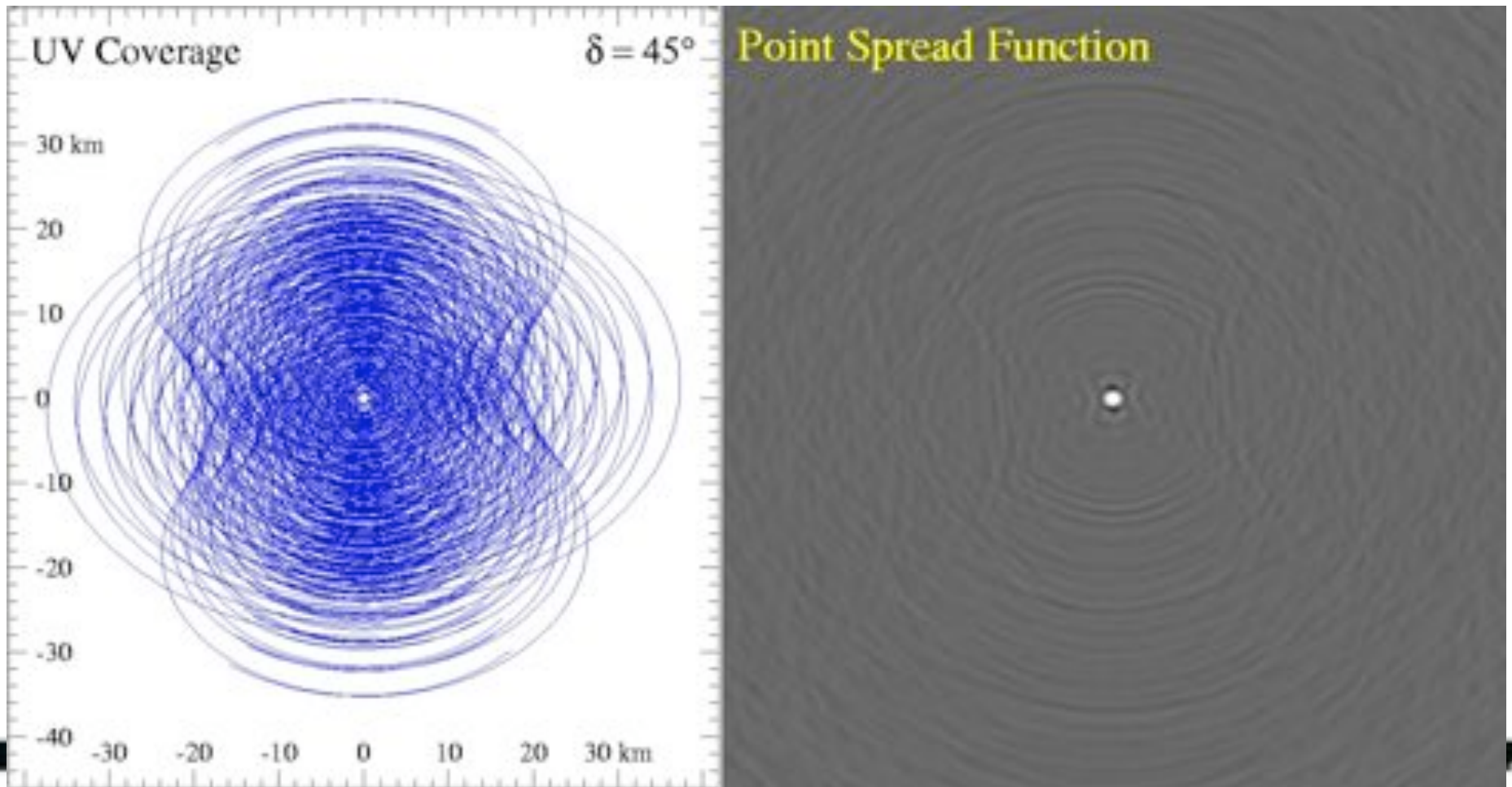
3 Hour Synthesis Observation



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UV COVERAGE: FULL TRACK

12 Hour Synthesis Observation



EXAMPLES: Westerbork Synthesis Radio Telescope (WSRT)

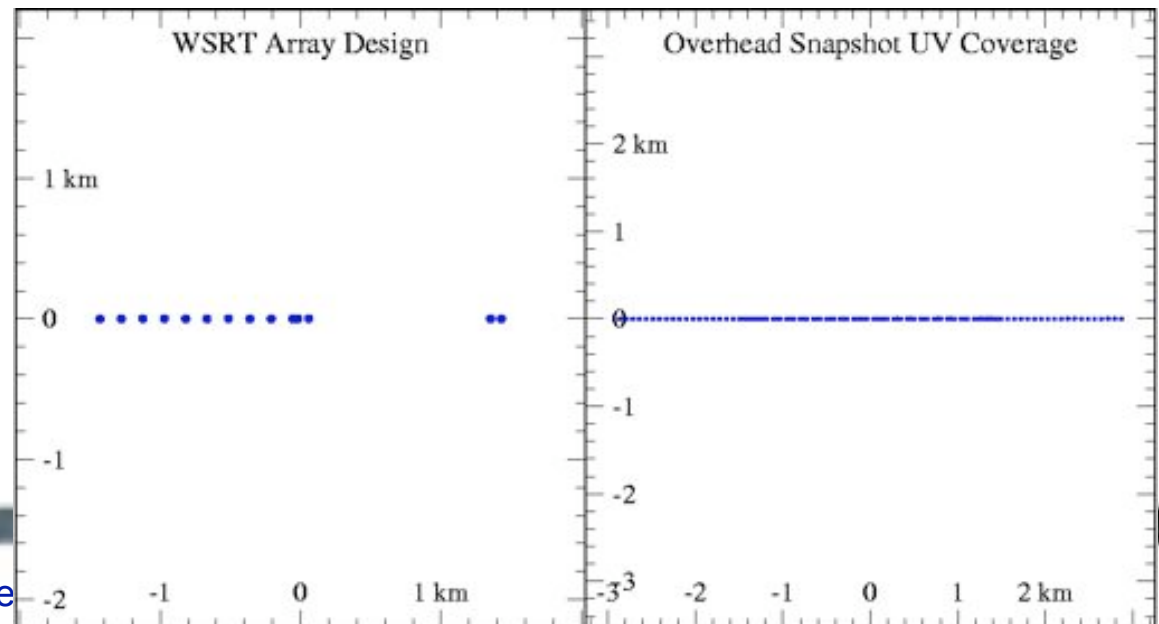


Has 14 antennas, 25m diameter

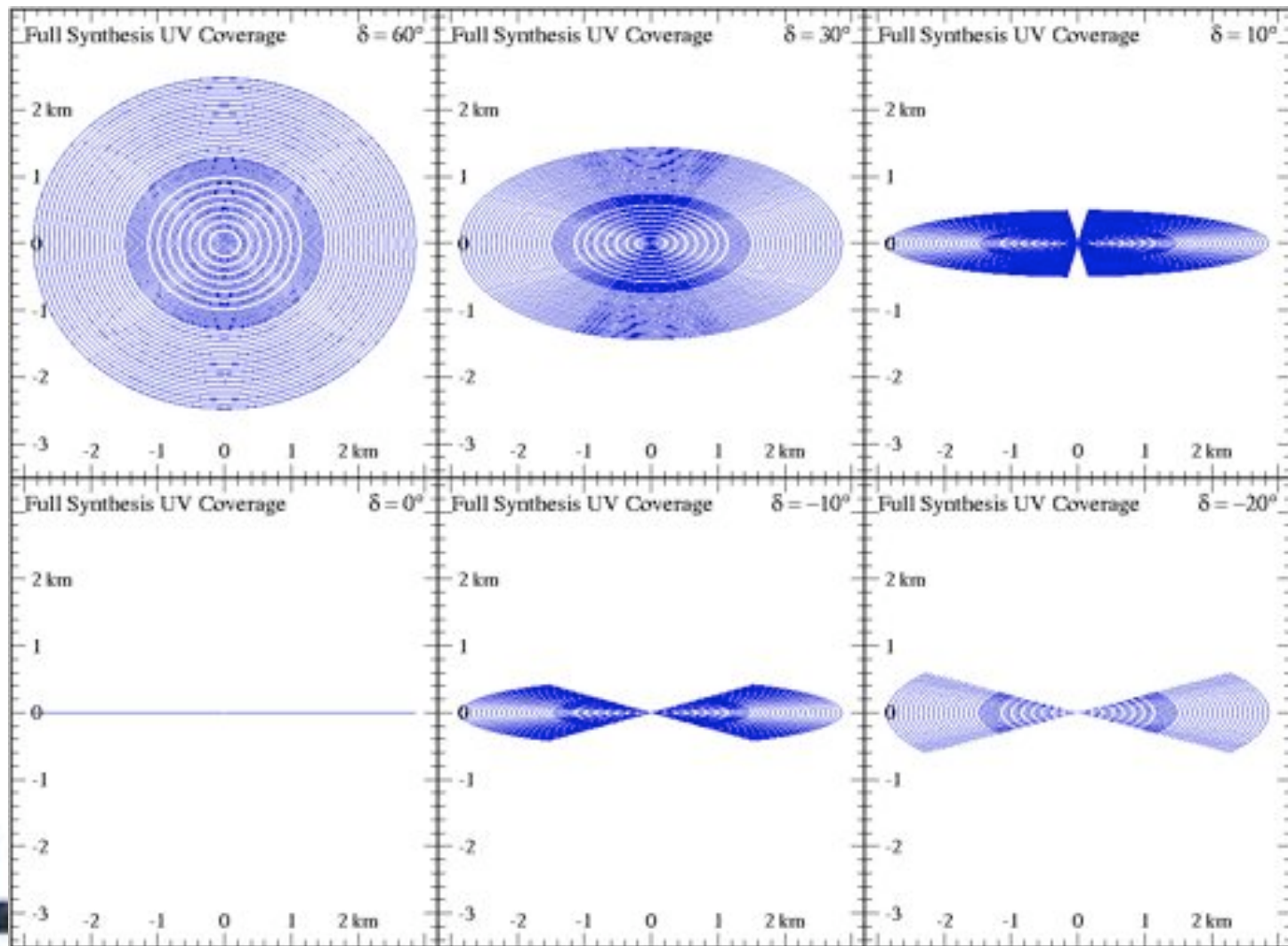
East-West Array

Requires Earth Rotation Synthesis for all imaging

Dedicated in 1970: one of the earliest major interferometric arrays



EXAMPLES: WSRT

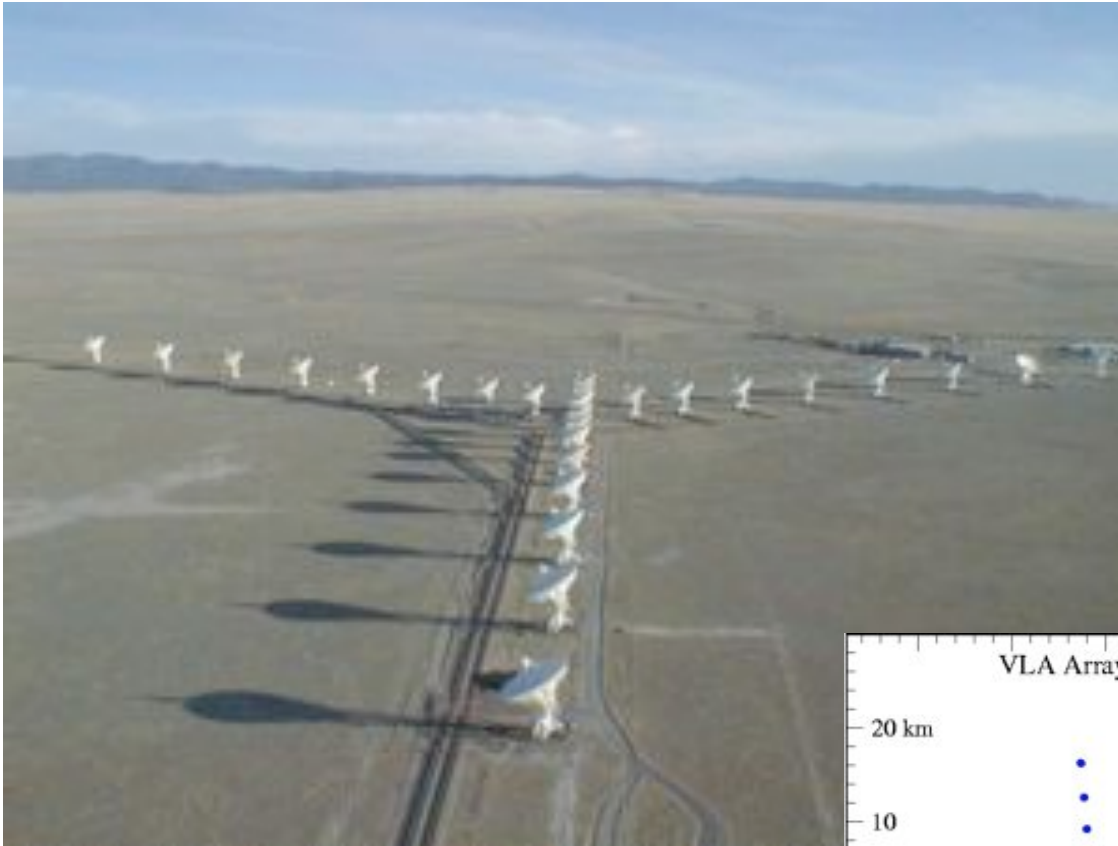


Tracks: elevation > 10 degrees

... Full Synthesis Imaging ...

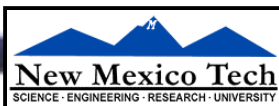
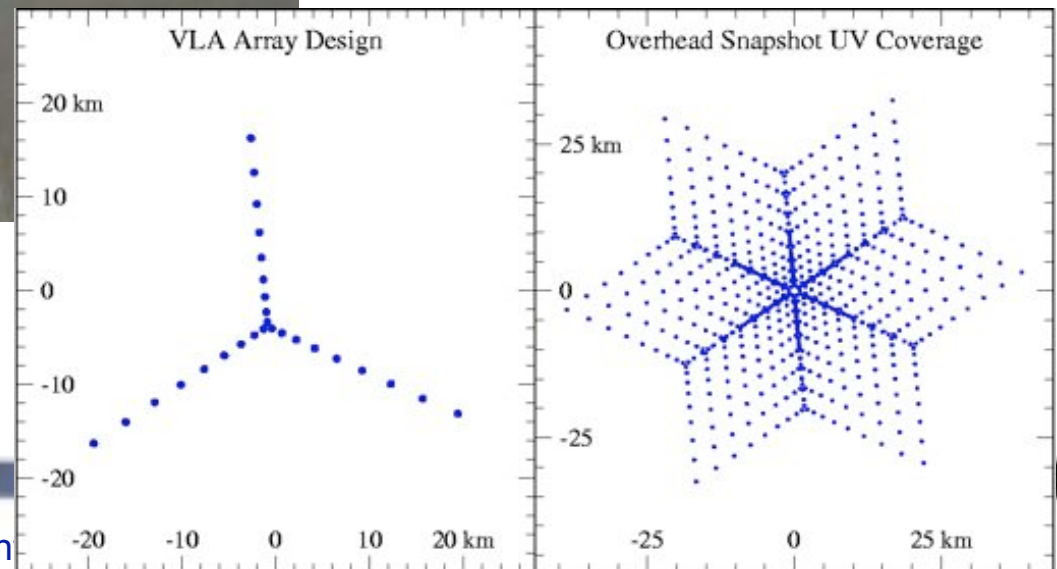


EXAMPLES: Very Large Array (VLA)



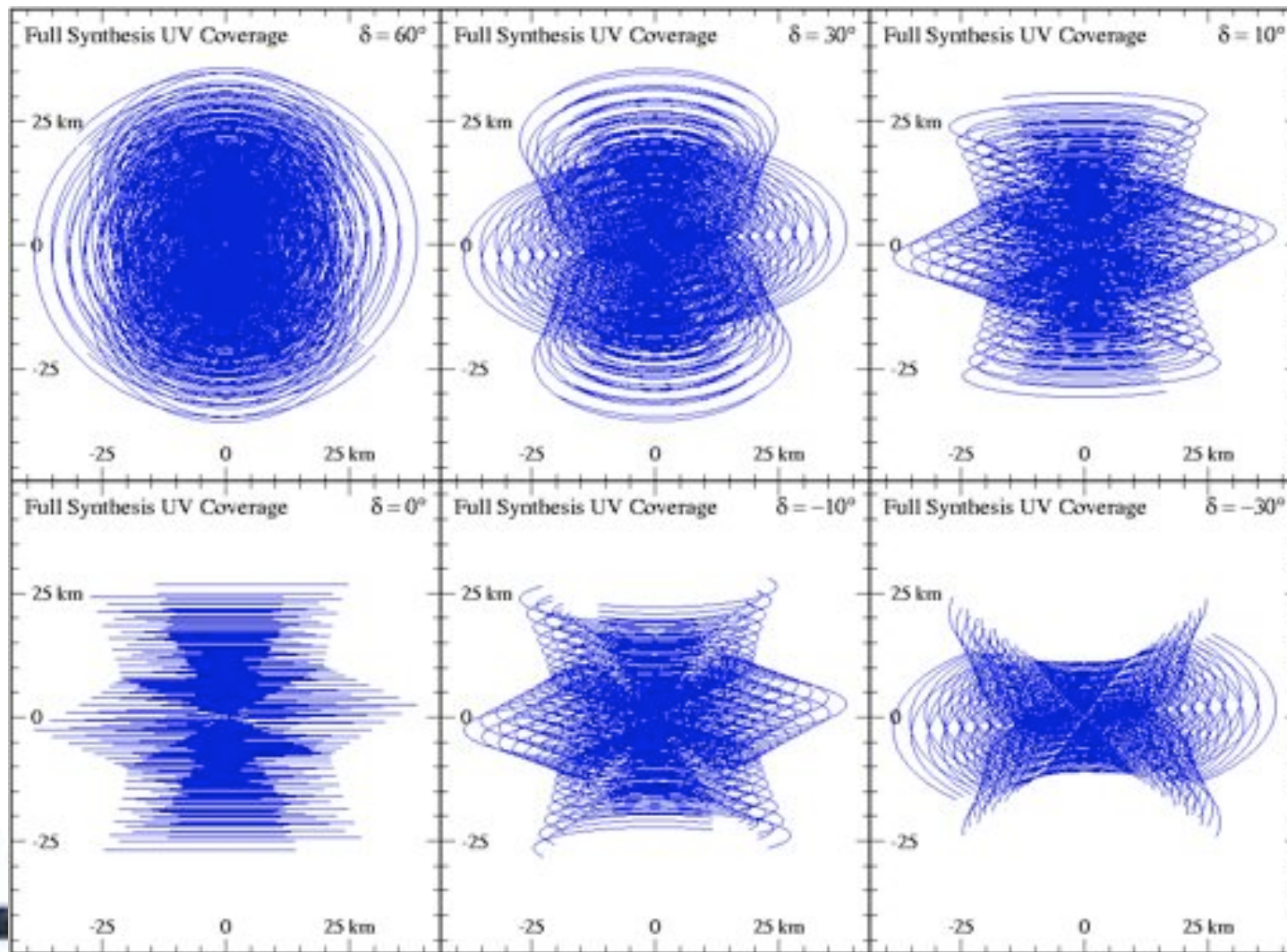
Y-shaped Array
Re-configurable

Config.	B_{\max} (km)	B_{\min} (km)
A	36	0.68
B	11	0.24
C	3.4	0.045
D	1.0	0.035



EXAMPLES: VLA LONG TRACK

VLA uv-coverage at various declinations



Tracks: elevation > 10 degrees

EXAMPLES: Very Long Baseline Array (VLBA)



Ten 25m antennas

US Territory, Hawaii to St. Croix

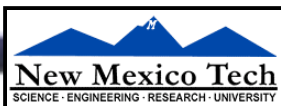
Baselines 200 to 8,600 km

Elements not connected

Separate clocks

Data recorded

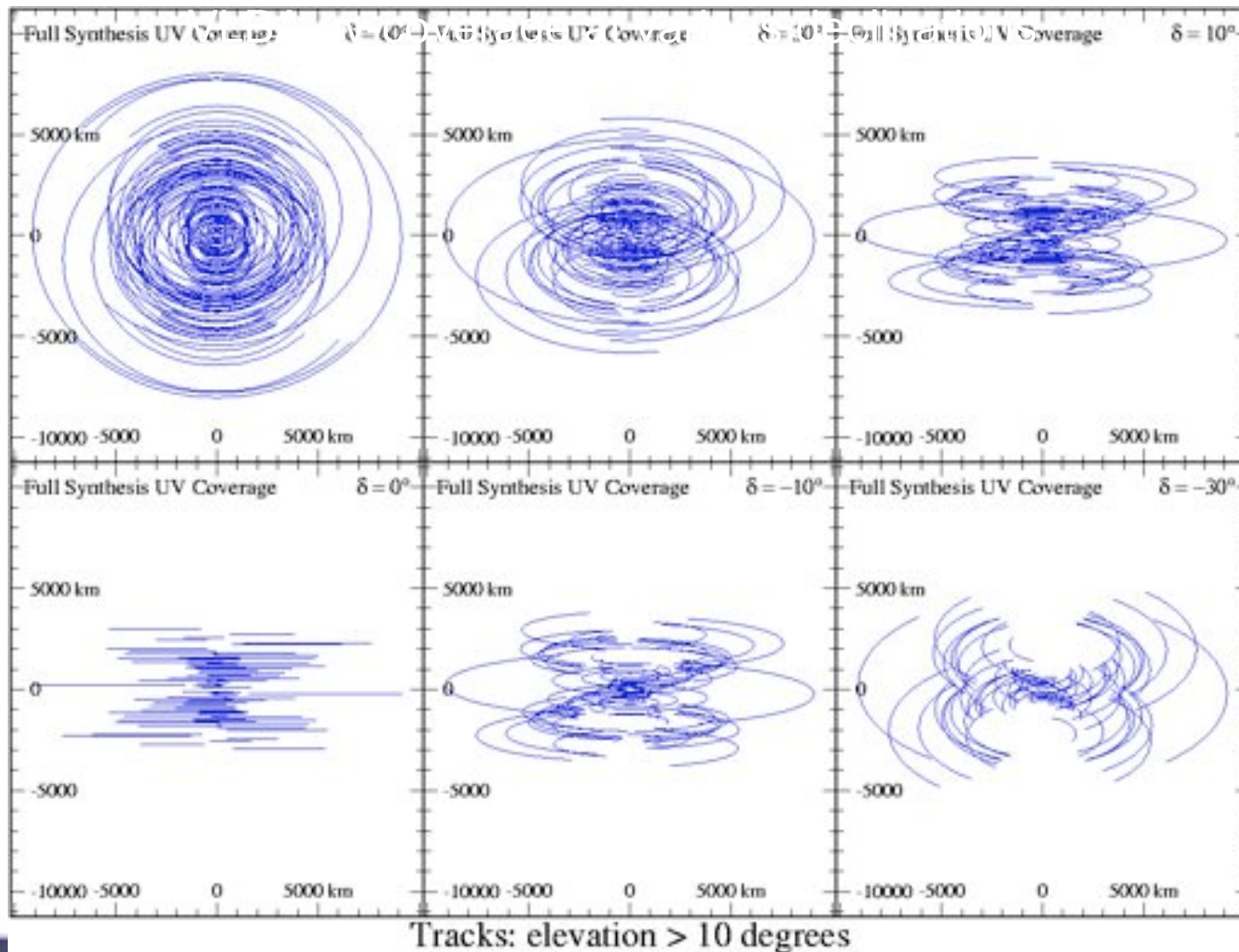
Resolution of milli-arcseconds



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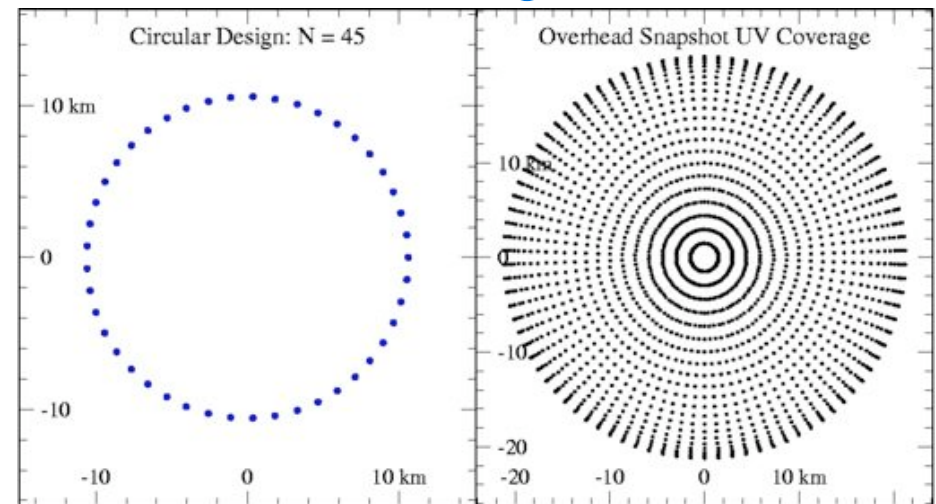
EXAMPLES: VLBA



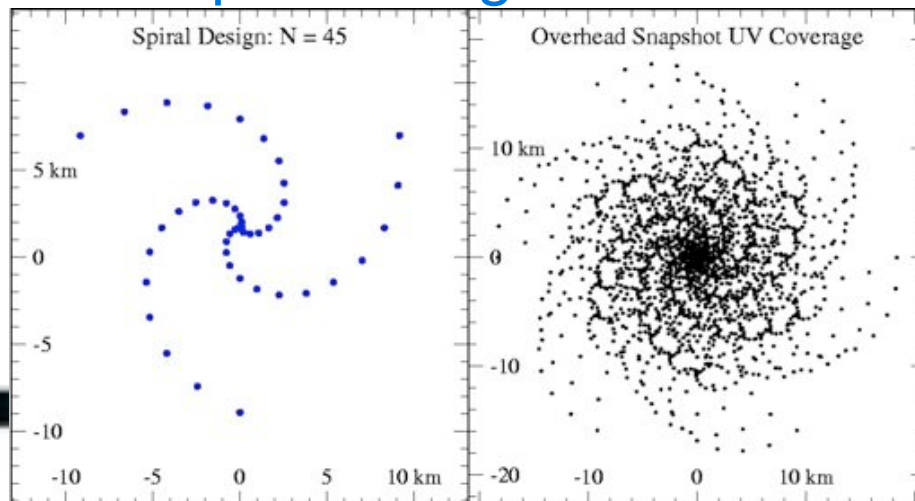
VARIOUS “IDEAL” ARRAY DESIGNS

- Circular
 - maximizes number of long baselines
- Spiral
 - has more short baselines
- Random
 - has little redundancy or patterns

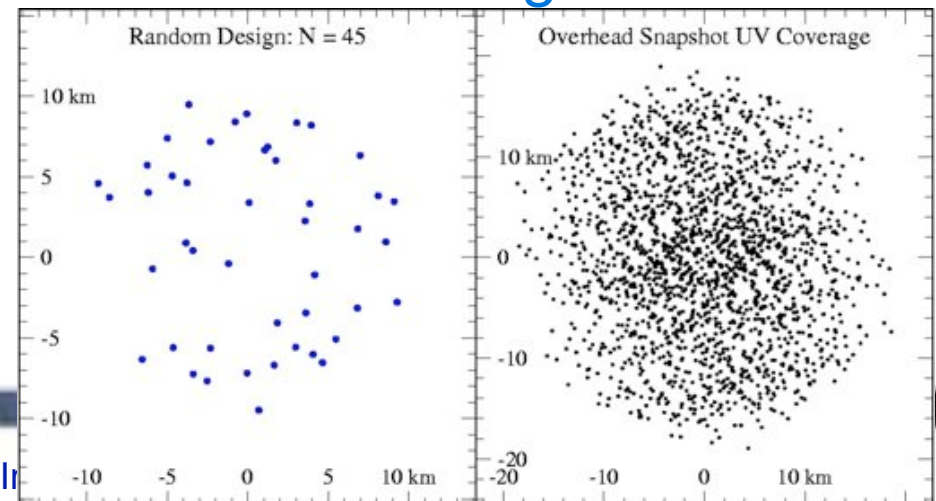
Circular Design: $N = 45$



Spiral Design: $N = 45$

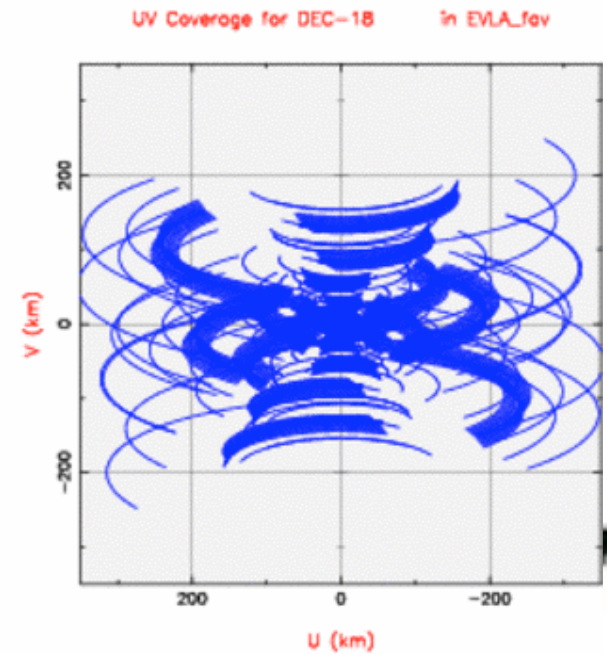
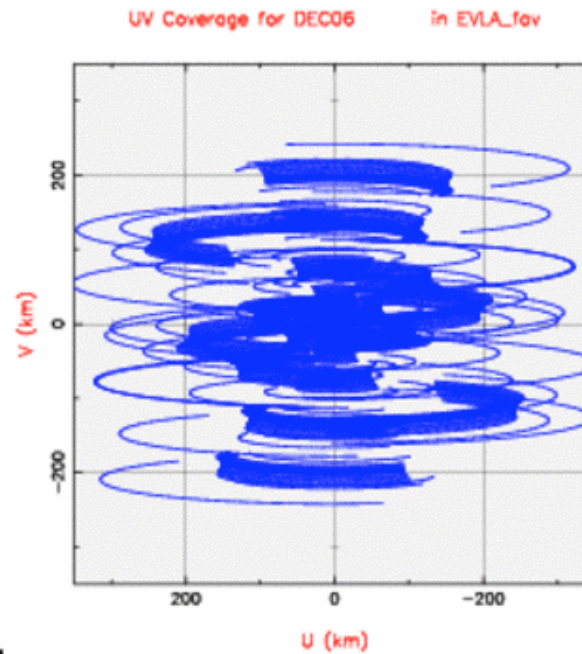
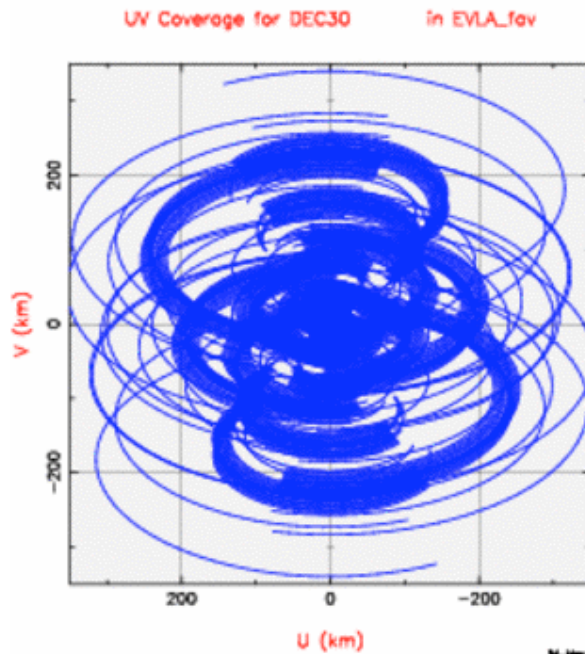
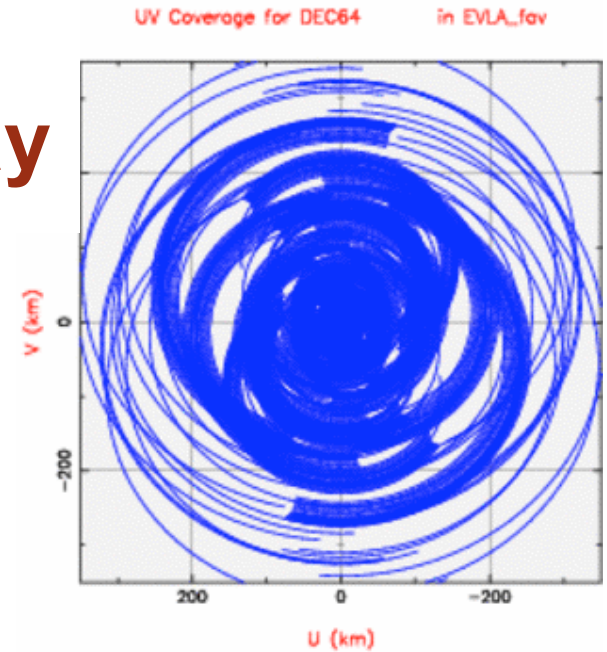
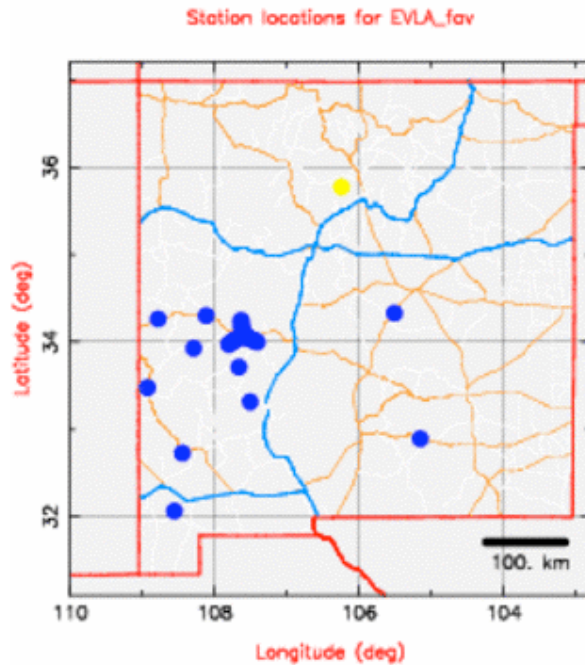


Random Design: $N = 45$



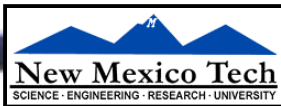
Centrally Condensed Array

- Plots for EVLA2 (NMA)
 - VLA + 10, to 300km
- Mainly baselines from outer stations to core count
- SKA will be centrally condensed
- Hard to get full resolution and full sensitivity together



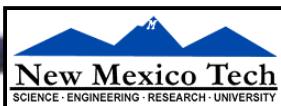
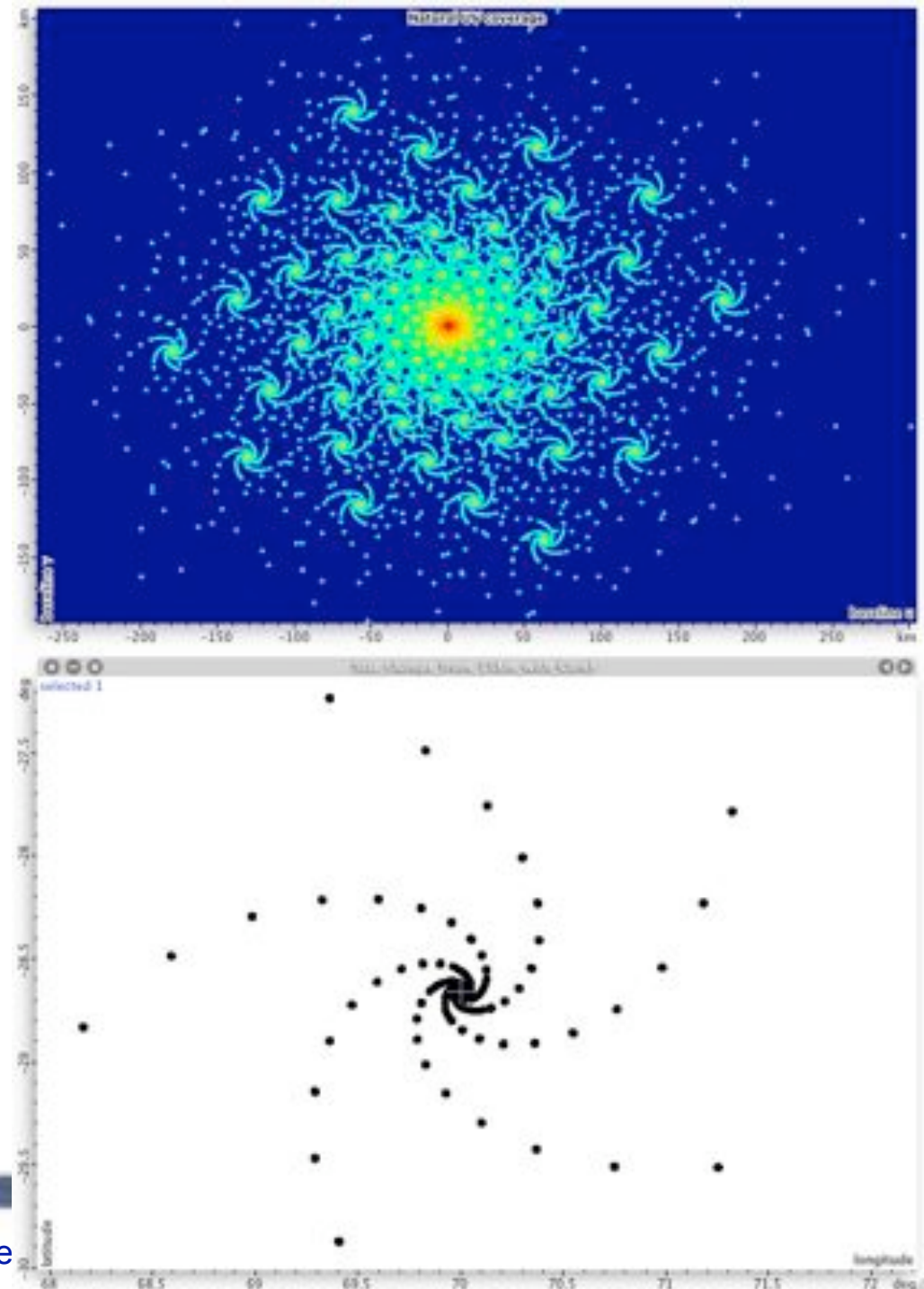
LARGE-N / SMALL-D CONCEPT

- N = Number of antennas in array
- D = Diameter of an antenna
- Collecting area ($N D^2$) kept constant
- UV Coverage drastically improved keeping sensitivity constant
 - Number of baselines scales with N^2
- Field of view large - better for survey speed
- Antennas relatively inexpensive - cost effective way to get area
- But the electronics are more complicated and expensive
 - Many more receivers, LOs, data lines etc
 - Correlator scales with N^2
- ATA is exploring the concept
- SKA will likely use it with several thousand antennas



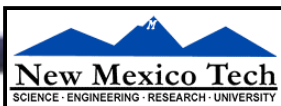
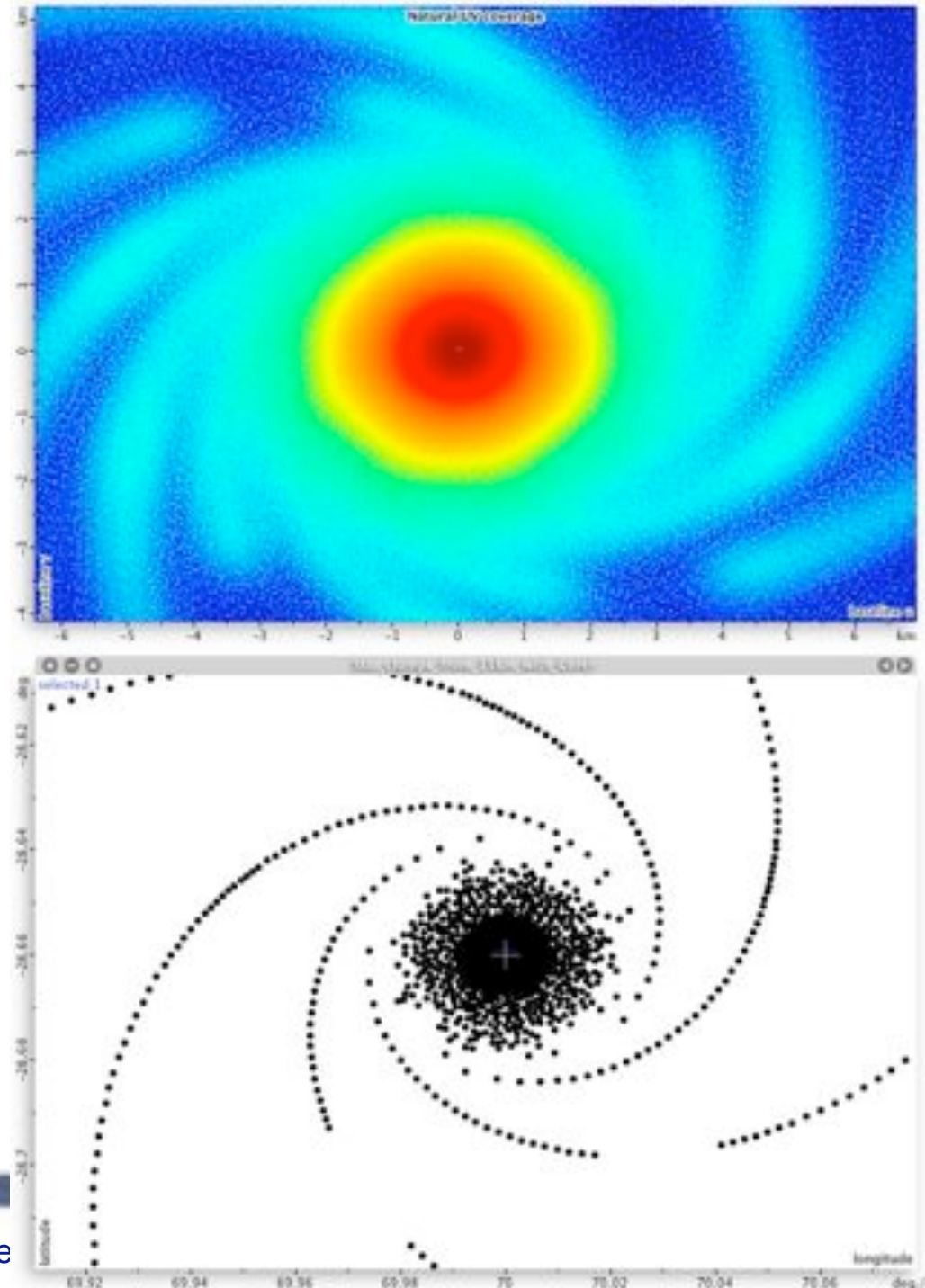
SKA CONCEPTUAL CONFIGURATION

- About 3000 antennas
- Core of 5 km diameter
 - Dense array of 1500 individual antennas
- Skirt 2.5 to 15 km radius
 - Transition to spirals
 - 372 antennas
- Intermediate region 2.5-180 km
 - Skirt is inner part
 - 528 antennas in clumps of 11 beyond skirt
- Remote region 180-3000+ km
 - 600 antennas in clumps of 24
- Displays from AntConfig - program being used to derive SKA configuration



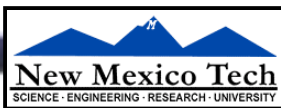
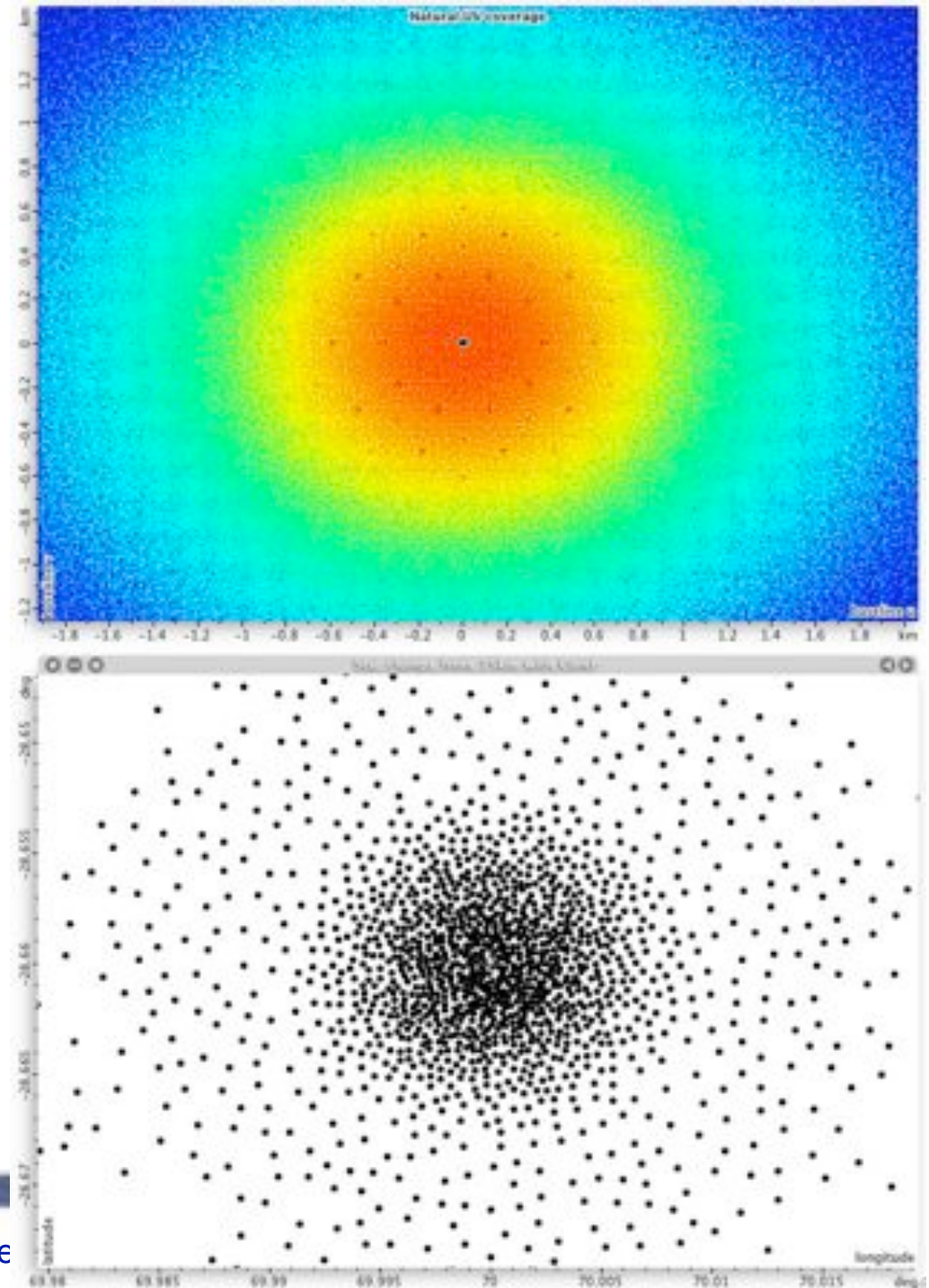
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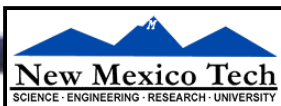
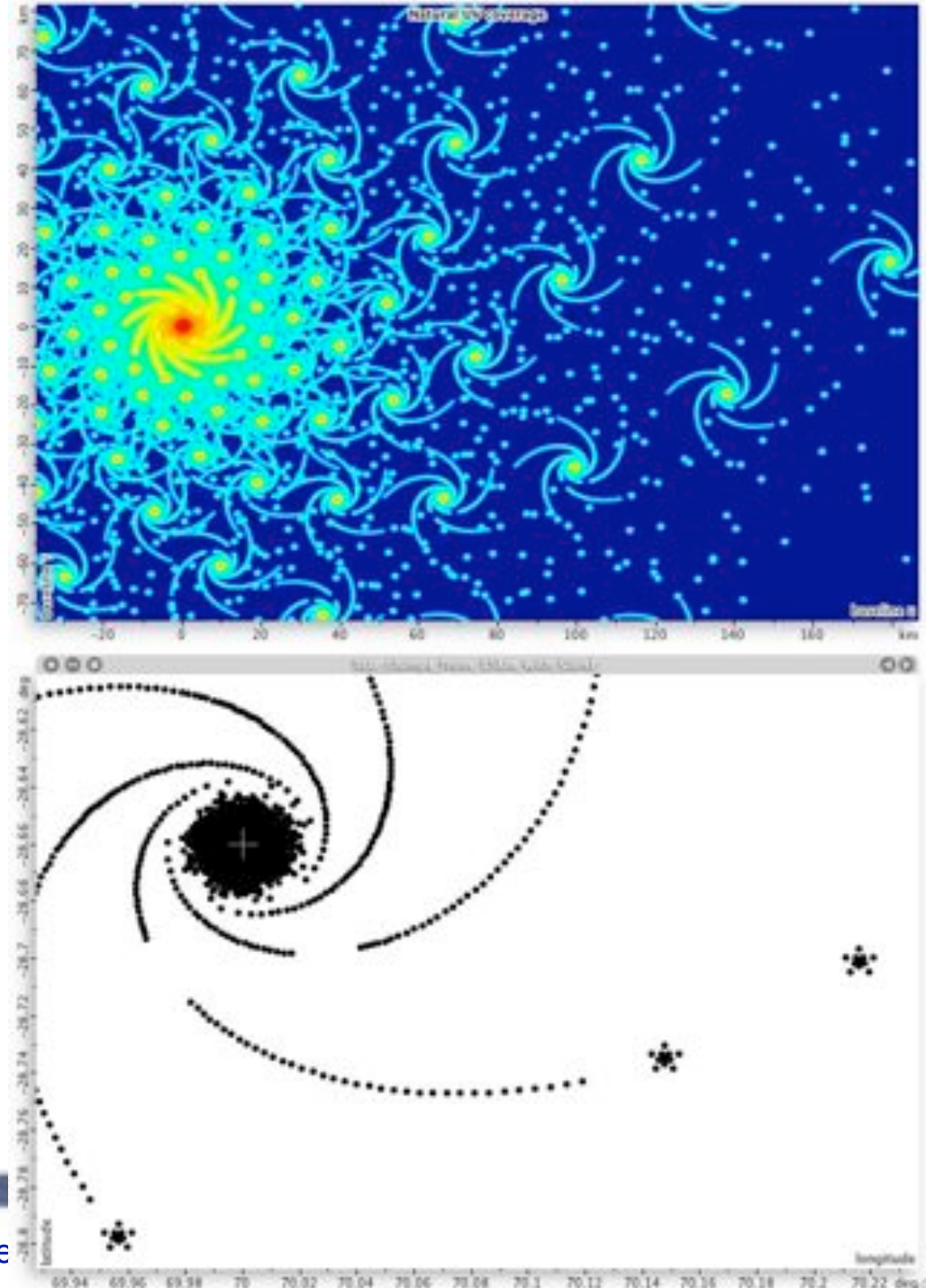
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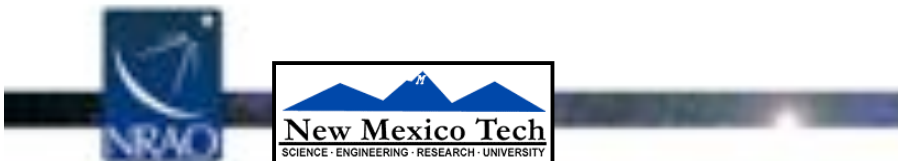
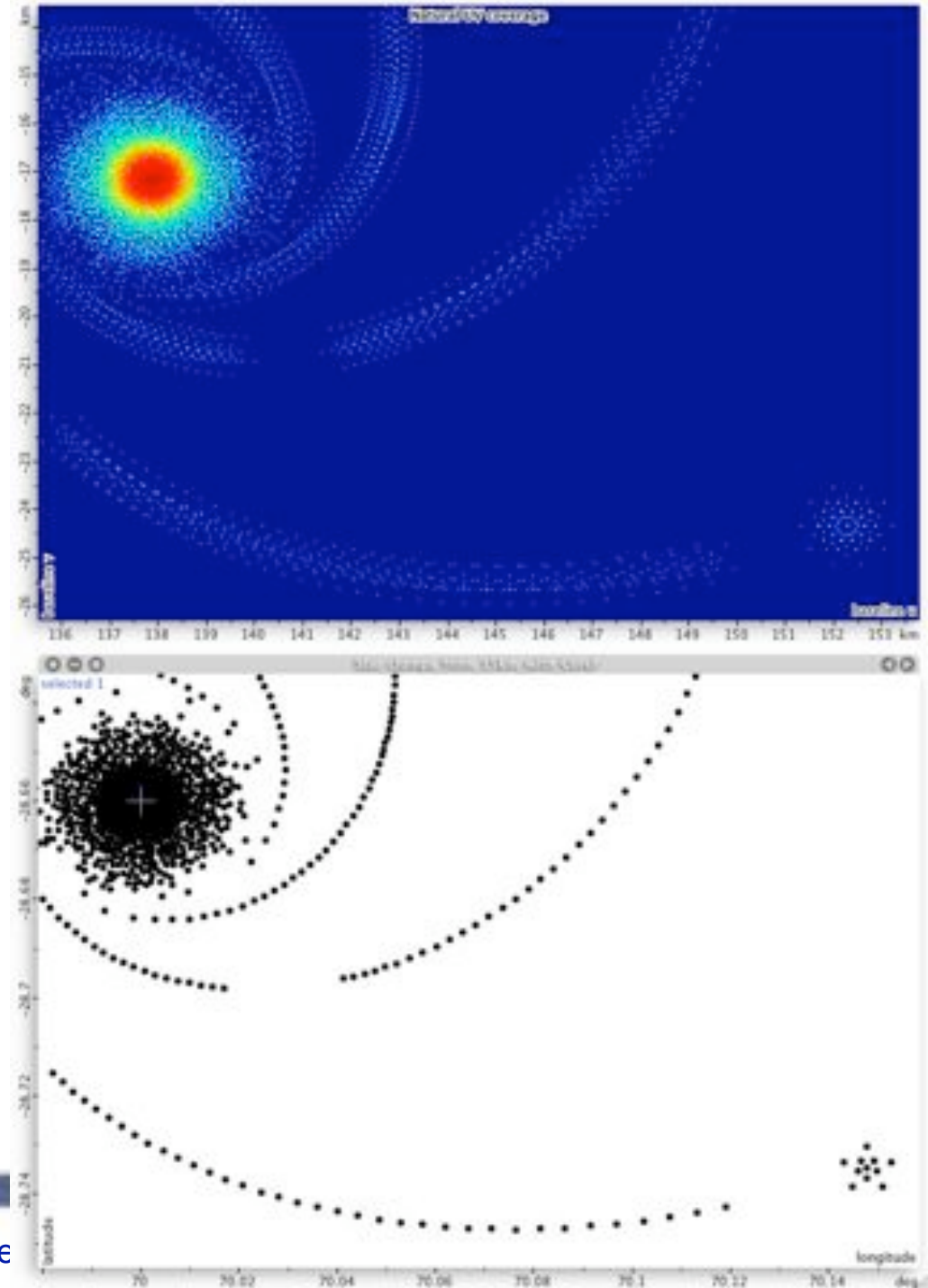
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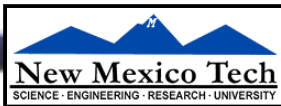
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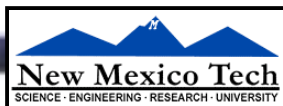
ARRAY OPTIMIZATION

- Trial and Error
 - devise configurations and calculate metrics (works OK for small N)
- Random Distribution
 - Lack of geometric pattern reduces redundancy
 - Works surprisingly well for large N
- Simulated Annealing (Cornwell)
 - Define uv 'energy' function to minimize – log of mean uv distance
- UV-Density & pressure (Boone)
 - Steepest descent gradient search to minimize uv density differences with ideal uv density (e.g., Gaussian)
- Genetic algorithm (e.g., Cohan et al., 2004)
 - Pick start configurations, breed new generation using crossover and mutation, select, repeat
- PSF optimization (L. Kogan)
 - Minimize biggest sidelobe using derivatives of beam with respect to antenna locations (iterative process)



METRICS FOR OPTIMIZATION

- Side-lobe levels
 - Useful for image dynamic range
- Range of baseline lengths
 - Useful for large complex sources
 - Useful for ability to support a wide variety of science
- Largest gaps in uv-coverage
 - Image fidelity
- Match to desired baseline length distribution
 - So that UV-weighting, which reduces sensitivity, is not needed

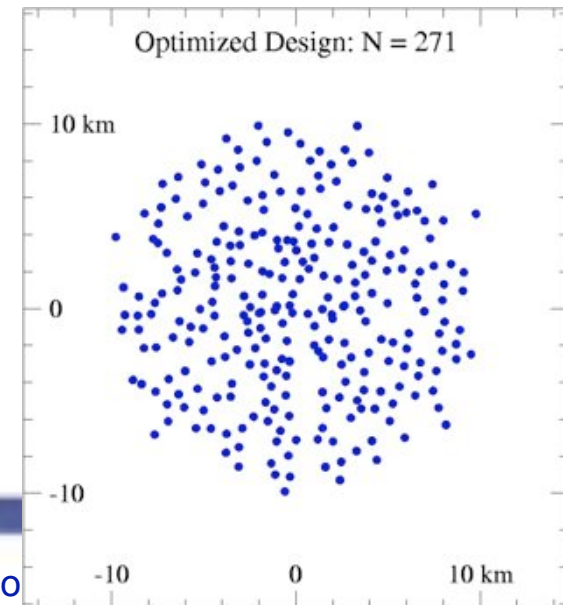
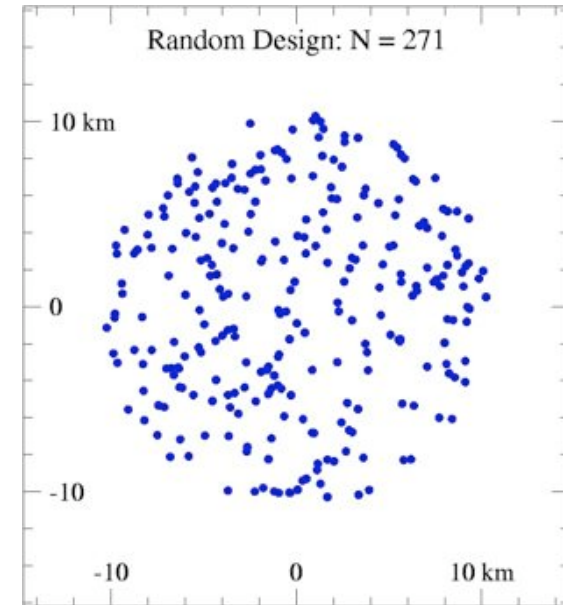
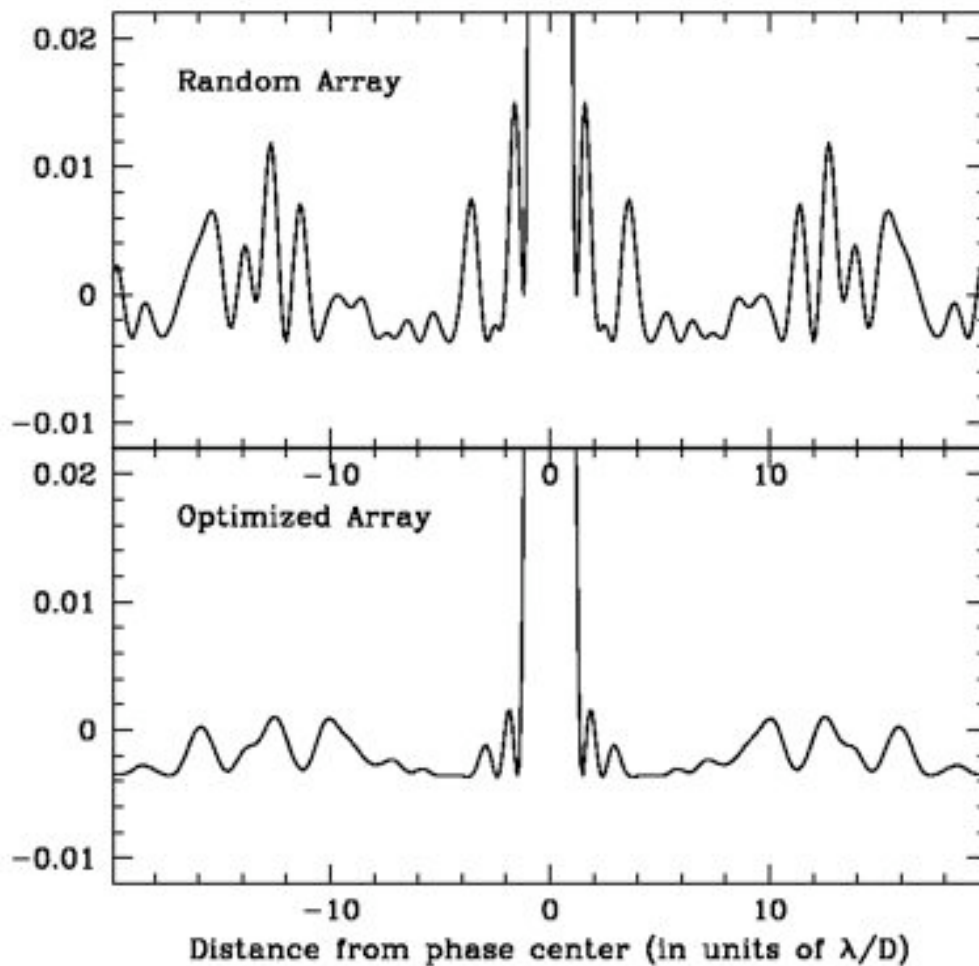


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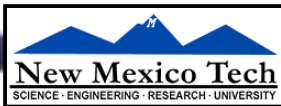
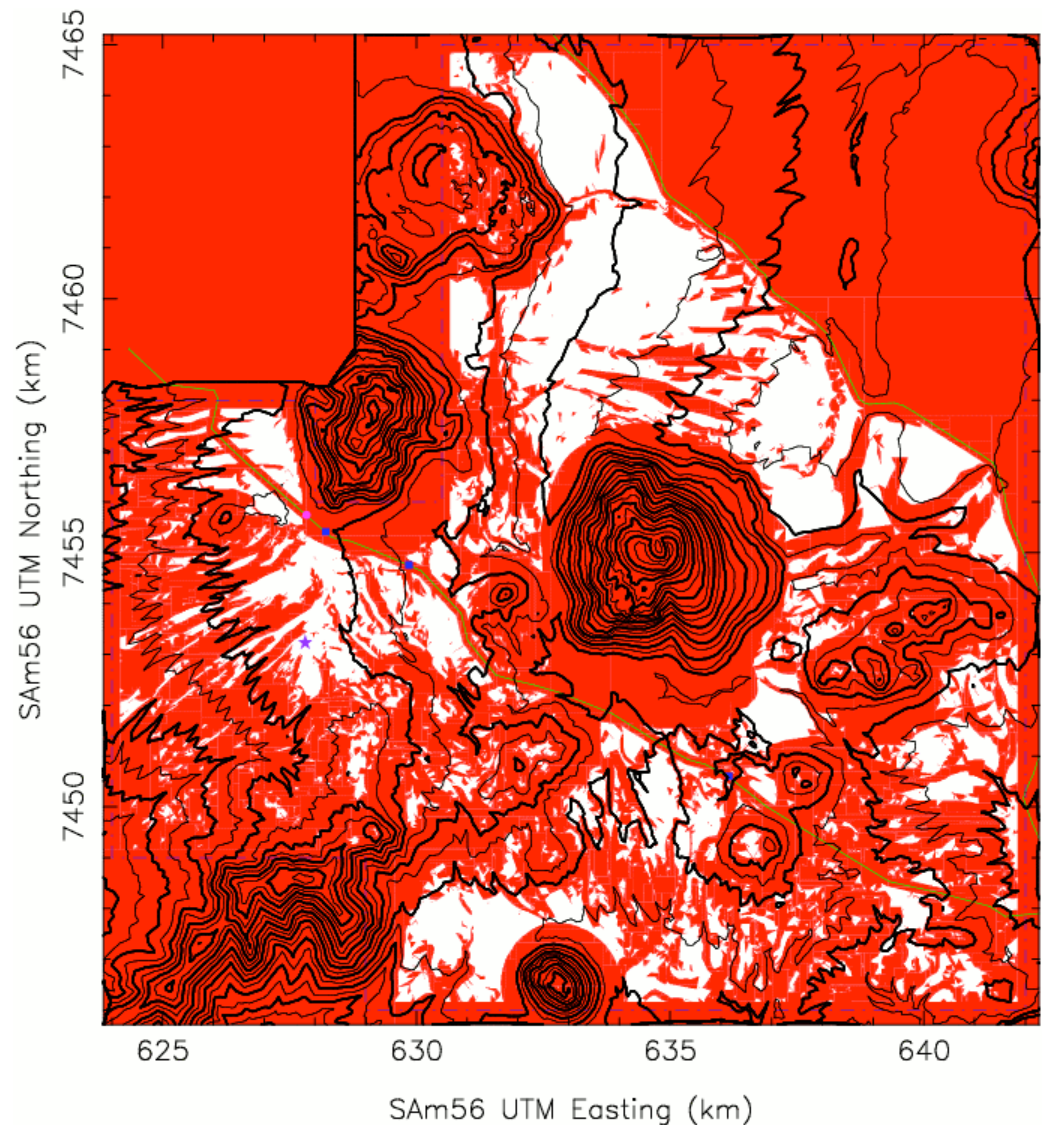
Iterative Minimization of Sidelobes: Kogan Method

Comparing random versus optimized
arrays for $N = 271$



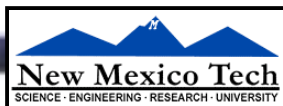
MASK

- In the optimization, a mask can be used to define acceptable places to put antennas
- Example is for ALMA
 - Pads can go in the white areas
- Preparation of a mask is an important step
 - Time consuming to get all the required data

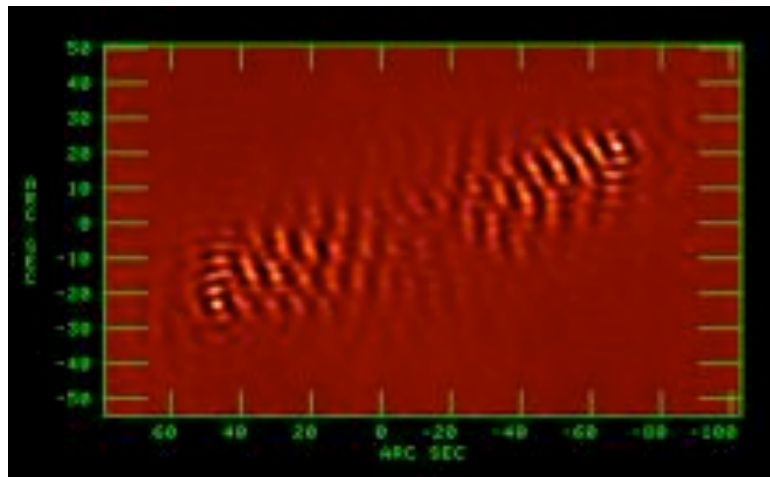
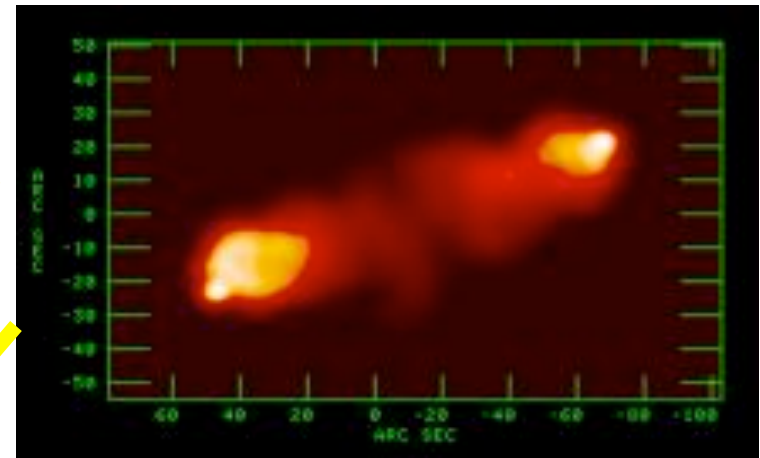
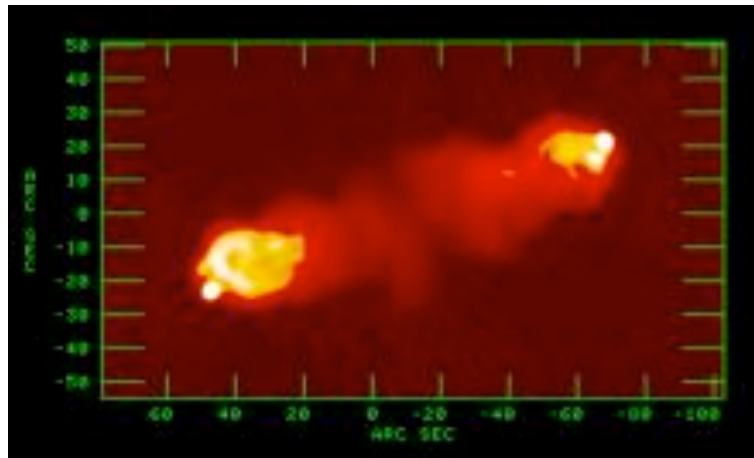


SIMULATIONS

- Simulations provide a good test and demonstration of an array design
 - Show how well the UV-coverage performs in practice
 - Can explore “fidelity” since the “true” image is known
 - Provide material to help sell the array
- Steps for a simulation:
 - Generate realistic models of sky
 - Simulate data, adding in increasing levels of reality
 - Atmosphere, pointing errors, dish surface rms etc.
 - Process simulated data & compare final images for different designs and configurations – relative comparison
 - Compare final images with input model
 - Tests image fidelity which cannot be done with real data
 - Compare with specifications for DR and fidelity
- Be careful that you are not just testing imaging methods rather than array design - imaging is a complicated process



Simulating the Long Wavelength Array (LWA)

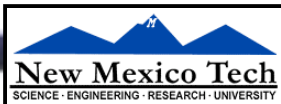


- Simulating Image Fidelity
 - Project model image to simulated uv-coverage and image in normal way
 - Subtract model to examine residual image errors
 - Can define: Fidelity Index = $(\text{peak intensity})/(\text{residual rms})$



SIMULATION SOFTWARE

- Most analysis packages have basic simulation capabilities
- AIPS - Basic fake data creation with full imaging and analysis
- CASA - simdata and sm
 - Can simulate many arrays. including ALMA, EVLA, CARMA, SMA, ATCA, PdB
- MeqTrees - Implements measurement equations
 - Used especially for LOFAR
- ASKAPSoft - includes support for multi-beam systems
- IRAM/GILDAS ALMA simulator
- Many more



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THE END

