









Polarization in Interferometry

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Polarization in interferometry

- Astrophysics of Polarization
- Physics of Polarization
- Antenna Response to Polarization
- Interferometer Response to Polarization
- Polarization Calibration & Observational Strategies
- Polarization Data & Image Analysis





DON'T PANIC!

- There are lots of equations and concepts. Hang in there.
- I will illustrate the concepts with figures and 'handwaving'.
- Many good references:
 - Synthesis Imaging II: Lecture 6, also parts of 1, 3, 5, 32
 - Born and Wolf: Principle of Optics, Chapters 1 and 10
 - Rolfs and Wilson: Tools of Radio Astronomy, Chapter 2
 - Thompson, Moran and Swenson: Interferometry and Synthesis in Radio Astronomy, Chapter 4
 - Tinbergen: Astronomical Polarimetry. All Chapters.
 - J.P. Hamaker et al., A&A, 117, 137 (1996) and series of papers
- Great care must be taken in studying these references conventions vary between them.





Polarization Astrophysics





Why Measure Polarization?

- Electromagnetic waves are intrinsically polarized
 - monochromatic waves are fully polarized
- Polarization state of radiation can tell us about:
 - the origin of the radiation
 - intrinsic polarization, orientation of generating B-field
 - the medium through which it traverses
 - propagation and scattering effects
 - unfortunately, also about the purity of our optics
 - you may be forced to observe polarization even if you do not want to!







Astrophysical Polarization

- Examples:
 - Processes which generate polarized radiation:
 - Synchrotron emission: Up to ~80% linearly polarized, with no circular polarization. Measurement provides information on strength and orientation of magnetic fields, level of turbulence.
 - Zeeman line splitting: Presence of B-field splits RCP and LCP components of spectral lines by by 2.8 Hz/μG. Measurement provides direct measure of B-field.
 - Processes which modify polarization state:
 - Free electron scattering: Induces a linear polarization which can indicate the origin of the scattered radiation.
 - Faraday rotation: Magnetoionic region rotates plane of linear polarization. Measurement of rotation gives B-field estimate.
 - Faraday conversion: Particles in magnetic fields can cause the polarization ellipticity to change, turning a fraction of the linear polarization into circular (possibly seen in cores of AGN)





Example: Radio Galaxy 3C31

- VLA @ 8.4 GHz
 - Laing (1996)
- Synchrotron radiation
 - relativistic plasma
 - jet from central "engine"
 - from pc to kpc scales
 - feeding >10kpc "lobes"
- E-vectors
 - along core of jet
 - radial to jet at edge







Example: Radio Galaxy Cygnus A

• VLA @ 8.5 GHz B-vectors Perley & Carilli (1996)









Example: Faraday rotation of CygA

 See review of "Cluster Magnetic Fields" by Carilli & Taylor 2002 (ARAA)





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Example: Zeeman effect



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Example: the ISM of M51

- Trace magnetic field structure in galaxies
 - follow spiral structure
 - origin?
 - amplified in dynamo?



M51 2.8CM 'B'-VECTORS

1.8mJy/Beam





Scattering

- Anisotropic Scattering induces Linear Polarization
 - electron scattering (e.g. in Cosmic Microwave Background)
 - dust scattering (e.g. in the millimeter-wave spectrum)





Animations from Wayne Hu



Polarization Fundamentals





The Polarization Ellipse

- From Maxwell's equations E•B=0 (E and B perpendicular)
 - By convention, we consider the time behavior of the E-field in a fixed perpendicular plane, from the point of view of the

receiver.

Mexico Tec

NRAC



transverse wave

• For a monochromatic wave of frequency v, we write

 $E_x = A_x \cos(2\pi v t + \phi_x)$

 $E_{y} = A_{y} \cos(2\pi v t + \phi_{y})$

These two equations describe an ellipse in the (x-y) plane.

• The ellipse is described fully by three parameters:

- A_{χ} , A_{γ} , and the phase difference, $\delta = \phi_{\gamma} - \phi_{\chi}$.





Elliptically Polarized Monochromatic Wave

The simplest description of wave polarization is in a Cartesian coordinate frame.

In general, three parameters are needed to describe the ellipse.

If the E-vector is rotating: -clockwise, wave is 'Left Elliptically Polarized', -counterclockwise, is 'Right Elliptically Polarized'.

The angle α = atan(A_Y/A_X) is used later



equivalent to 2 independent E_x and E_y





oscillators



Polarization Ellipse Ellipticity and P.A.

- A more natural description is in a frame (ξ,η), rotated so the ξaxis lies along the major axis of the ellipse.
- The three parameters of the ellipse are then:

 \textbf{A}_{η} : the major axis length

 $\tan \chi = A_{\xi}/A_{\eta}$: the axial ratio Ψ : the major axis p.a. $\tan 2\Psi = \tan 2\alpha \cos \delta$ $\sin 2\chi = \sin 2\alpha \sin \delta$

• The ellipticity χ is signed: $\chi > 0 \rightarrow REP$ $\chi < 0 \rightarrow LEP$



 $\chi = 0,90^{\circ} \rightarrow \text{Linear} (\delta=0^{\circ},180^{\circ})$ $\chi = \pm 45^{\circ} \rightarrow \text{Circular} (\delta=\pm 90^{\circ})$





Circular Basis

 We can decompose the E-field into a circular basis, rather than a (linear) Cartesian one:

$\mathbf{E} = A_R \hat{e}_R + A_L \hat{e}_L$

- where A_R and A_L are the amplitudes of two counter-rotating unit vectors, e_R (rotating counter-clockwise), and e_L (clockwise)
- NOTE: R,L are obtained from X,Y by δ =±90° phase shift
- It is straightforward to show that:

$$A_{R} = \frac{1}{2} \sqrt{A_{X}^{2} + A_{Y}^{2} - 2A_{X}A_{Y}} \sin \delta_{XY}$$
$$A_{L} = \frac{1}{2} \sqrt{A_{X}^{2} + A_{Y}^{2} + 2A_{X}A_{Y}} \sin \delta_{XY}$$





Circular Basis Example

- The black ellipse can be decomposed into an xcomponent of amplitude 2, and a y-component of amplitude 1 which lags by ¼ turn.
- It can alternatively be decomposed into a counterclockwise rotating vector of length 1.5 (red), and a clockwise rotating vector of length 0.5 (blue).







The Poincare Sphere

• Treat 2ψ and 2χ as longitude and latitude on sphere of radius $A=E^2$







Stokes parameters

- Spherical coordinates: radius I, axes Q, U, V
 - $-1 = E_x^2 + E_y^2 = E_R^2 + E_L^2$
 - Q = I cos 2χ cos 2ψ = E_x² E_y² = 2 E_R E_L cos δ_R
 - $U = I \cos 2\chi \sin 2\psi = 2 E_X E_Y \cos \delta_{X'} = 2 E_R E_L \sin \delta_R$
 - $V = I \sin 2\chi$ = 2 E_X E_Y sin δ_{XY} = E_R² E_L²
- Only 3 independent parameters:
 - wave polarization confined to surface of Poincare sphere
 - $|^2 = Q^2 + U^2 + V^2$
- Stokes parameters I,Q,U,V
 - defined by George Stokes (1852)
 - form complete description of wave polarization
 - NOTE: above true for 100% polarized monochromatic wave!





Linear Polarization

- Linearly Polarized Radiation: V = 0
 - Linearly polarized flux:



 $\tan 2\psi = U/Q$

Q and U define the linear polarization position angle:









Simple Examples

- If V = 0, the wave is linearly polarized. Then,
 - If U = 0, and Q positive, then the wave is vertically polarized, Ψ =0°

- If U = 0, and Q negative, the wave is horizontally polarized, Ψ =90°

- If Q = 0, and U positive, the wave is polarized at Ψ = 45°

- If Q = 0, and U negative, the wave is polarized at Ψ = -45°.







Illustrative Example: Non-thermal Emission from Jupiter

- Apr 1999 VLA 5 GHz data
- D-config resolution is 14"
- Jupiter emits thermal radiation from atmosphere, plus polarized synchrotron radiation from particles in its magnetic field
- Shown is the I image (intensity) with polarization vectors rotated by 90° (to show B-vectors) and polarized intensity (blue contours)
- The polarization vectors trace Jupiter's dipole
- Polarized intensity linked to the lo plasma torus







Why Use Stokes Parameters?

- Tradition
- They are scalar quantities, independent of basis XY, RL
- They have units of power (flux density when calibrated)
- They are simply related to actual antenna measurements.
- They easily accommodate the notion of partial polarization of non-monochromatic signals.
- We can (as I will show) make images of the I, Q, U, and V intensities directly from measurements made from an interferometer.
- These I,Q,U, and V images can then be combined to make images of the linear, circular, or elliptical characteristics of the radiation.



Partial Polarization

- Monochromatic radiation is a myth.
- No such entity can exist (although it can be closely approximated).
- In real life, radiation has a finite bandwidth.
- Real astronomical emission processes arise from randomly placed, independently oscillating emitters (electrons).
- We observe the summed electric field, using instruments of finite bandwidth.
- Despite the chaos, polarization still exists, but is not complete – partial polarization is the rule.





Stokes Parameters for Partial Polarization

Stokes parameters defined in terms of mean quantities: $Q = \langle E_r^2 - \langle E_r^2 = 2 \langle E_r E_l \cos \delta_r \rangle$ $U = 2\langle E_r E_v \cos \delta_r = 2\langle E_r E_l \sin \delta_r \rangle$ $V = 2\langle E_{x}E_{y}\sin\delta_{xy} = \langle E_{r}^{2} - \langle E_{l}^{2} \rangle$ Note that now, unlike monochromatic radiation, the radiation is not necessarily 100% polarized.

 $I^2 \ge Q^2 + U^2 + V^2$





Summary – Fundamentals

- Monochromatic waves are polarized
- Expressible as 2 orthogonal independent transverse waves

 - 3 independent parameters
 - choice of basis, e.g. linear or circular
- Poincare sphere convenient representation
 - Stokes parameters I, Q, U, V
 - I intensity; Q,U linear polarization, V circular polarization
- Quasi-monochromatic "waves" in reality
 - can be partially polarized
 - still represented by Stokes parameters





Antenna Polarization





Measuring Polarization on the sky

- Coordinate system dependence:
 - I independent
 - V depends on choice of "handedness"
 - V > 0 for RCP
 - Q,U depend on choice of "North" (plus handedness)
 - Q "points" North, U 45 toward East
- Polarization Angle Ψ

$\Psi = \frac{1}{2} \tan^{-1} (U/Q)$ (North through East)

- also called the "electric vector position angle" (EVPA)
- by convention, traces E-field vector (e.g. for synchrotron)
- B-vector is perpendicular to this





Optics – Cassegrain radio telescope

• Paraboloid illuminated by feedhorn:



Feeds arranged in <u>focal plane (off-axis)</u>





Optics – telescope response

- Reflections
 - − turn RCP ⇔ LCP
 - E-field (currents) allowed only in plane of surface
- "Field distribution" on aperture for E and B planes:







Example – simulated VLA patterns

 EVLA Memo 58 "Using Grasp8 to Study the VLA Beam" W. Brisken





Linear Polarization

Circular Polarization cuts in R & L





Example – measured VLA patterns

 AIPS Memo 86 "Widefield Polarization Correction of VLA Snapshot Images at 1.4 GHz" W. Cotton (1994)



Circular Polarization

Linear Polarization





Polarization Reciever Outputs

- To do polarimetry (measure the polarization state of the EM wave), the antenna must have two outputs which respond differently to the incoming elliptically polarized wave.
- It would be most convenient if these two outputs are proportional to either:
 - The two linear orthogonal Cartesian components, (E_{χ} , E_{γ}) as in ATCA and ALMA
 - The two circular orthogonal components, (E_R, E_L) as in VLA
- Sadly, this is not the case in general.
 - In general, each port is elliptically polarized, with its own polarization ellipse, with its p.a. and ellipticity.
- However, as long as these are different, polarimetry can be done.





Polarizers: Quadrature Hybrids

- We've discussed the two bases commonly used to describe polarization.
- It is quite easy to transform signals from one to the other, through a real device known as a 'quadrature hybrid'.



- To transform correctly, the phase shifts must be exactly 0 and 90 for all frequencies, and the amplitudes balanced.
- Real hybrids are imperfect generate errors (mixing/leaking)
- Other polarizers (e.g. waveguide septum, grids) equivalent





Polarization Interferometry





Four Complex Correlations per Pair

- Two antennas, each with two differently polarized outputs, produce four complex correlations.
- From these four outputs, we want to make four Stokes Images.







Outputs: Polarization Vectors

- Each telescope receiver has two outputs
 - should be orthogonal, close to X,Y or R,L
 - even if single pol output, convenient to consider both possible polarizations (e.g. for leakage)
 - put into vector

 $\vec{E}(t) = \begin{pmatrix} E_R(t) \\ E_L(t) \end{pmatrix} \quad \text{or} \quad \vec{E}(t) = \begin{pmatrix} E_X(t) \\ E_Y(t) \end{pmatrix}$





Correlation products: coherency vector

 Coherency vector: outer product of 2 antenna vectors as averaged by correlator

$$\vec{v}_{ij} = \left\langle \vec{E}_{i} \otimes \vec{E}_{j}^{*} \right\rangle = \left\langle \left(\begin{array}{c} E^{p} \\ E^{q} \end{array}\right)_{i} \otimes \left(\begin{array}{c} E^{p} \\ E^{q} \end{array}\right)_{j}^{*} \right\rangle = \left\langle \left\langle \begin{array}{c} E^{p} \\ E^{p} \\ E^{q} \end{array}\right\rangle_{j}^{*} \right\rangle = \left\langle \left\langle \begin{array}{c} E^{p} \\ E^{p} \\ E^{p} \\ E^{p} \\ E^{q} \\ E$$

- these are essentially the uncalibrated visibilities v

- circular products RR, RL, LR, LL
- linear products XX, XY, YX, YY
- need to include corruptions before and after correlation







Polarization Products: General Case

$$\begin{split} v^{pq} &= \frac{1}{2} G_{pq} \{ I[\cos(\Psi_p - \Psi_q)\cos(\chi_p - \chi_q) + i\sin(\Psi_p - \Psi_q)\sin(\chi_p + \chi_q)] \\ &+ Q[\cos(\Psi_p + \Psi_q)\cos(\chi_p + \chi_q) + i\sin(\Psi_p + \Psi_q)\sin(\chi_p - \chi_q)] \\ &- iU[\cos(\Psi_p + \Psi_q)\sin(\chi_p - \chi_q) + i\sin(\Psi_p + \Psi_q)\cos(\chi_p + \chi_q)] \\ &- V[\cos(\Psi_p - \Psi_q)\sin(\chi_p + \chi_q) + i\sin(\Psi_p - \Psi_q)\cos(\chi_p - \chi_q)] \} \end{split}$$

What are all these symbols?
v^μ is the complex output from the interferometer, for polarizations p and q from antennas 1 and 2, respectively.
Ψ and χ are the antenna polarization major axis and ellipticity for states p and q.

I,Q, U, and V are the Stokes Visibilities describing the polarization state of the astronomical signal.

G is the gain, which falls out in calibration.

CONVENTION – WE WILL ABSORB FACTOR 1/2 INTO GAIN!!!!!!!







Coherency vector and Stokes vector

- Maps (perfect) visibilities to the Stokes vector s
- Example: circular polarization (e.g. VLA)

$$\vec{v}_{circ} = \mathbf{S}_{circ} \,\vec{s} = \begin{pmatrix} v^{RR} \\ v^{RL} \\ v^{LR} \\ v^{LL} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & i & 0 \\ 0 & 1 & -i & 0 \\ 1 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} I \\ Q \\ U \\ V \end{pmatrix} = \begin{pmatrix} I+V \\ Q+iU \\ Q-iU \\ I-V \end{pmatrix}$$

• Example: linear polarization (e.g. ALMA, ATCA)

$$\vec{v}_{lin} = \mathbf{S}_{lin} \,\vec{s} = \begin{pmatrix} v^{XX} \\ v^{XY} \\ v^{YX} \\ v^{YX} \\ v^{YY} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & i \\ 0 & 0 & 1 & -i \\ 1 & -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} I \\ Q \\ U \\ V \end{pmatrix} = \begin{pmatrix} I+Q \\ U+iV \\ U-iV \\ I-Q \end{pmatrix}$$





Corruptions: Jones Matrices

- Antenna-based corruptions
 - pre-correlation polarization-dependent effects act as a matrix muliplication. This is the Jones matrix:

- $\begin{bmatrix} J_{21} & J_{22} \end{bmatrix}$
- form of J depends on basis (RL or XY) and effect
 - off-diagonal terms J_{12} and J_{21} cause corruption (mixing)
- total J is a string of Jones matrices for each effect





Parallactic Angle, P

- Orientation of sky in telescope's field of view
 - Constant for equatorial telescopes
 - Varies for alt-az telescopes

 $\mathbf{J}_{P}^{RL} = \begin{pmatrix} e^{i\varphi} & 0\\ 0 & e^{-i\varphi} \end{pmatrix}; \ \mathbf{J}_{P}^{XY} = \begin{pmatrix} \cos\varphi & -\sin\varphi\\ \sin\varphi & \cos\varphi \end{pmatrix}$

 Rotates the position angle of linearly polarized radiation (R-L phase)



- defined per antenna (often same over array)

$$\varphi(t) = \arctan\left(\frac{\cos(l)\sin(h(t))}{\sin(l)\cos(\delta) - \cos(l)\sin(\delta)\cos(h(t))}\right)$$

l =latitude, h(t) =hour angle, δ =declination

- P modulation can be used to aid in calibration





Visibilities to Stokes on-sky: RL basis

 the (outer) products of the parallactic angle (P) and the Stokes matrices gives



 this matrix maps a sky Stokes vector to the coherence vector representing the four perfect (circular) polarization products:

$$\begin{pmatrix} v^{RR} \\ v^{RL} \\ v^{RL} \\ v^{LR} \\ v^{LL} \end{pmatrix} = \begin{pmatrix} e^{-i(\varphi_{i}-\varphi_{j})} & 0 & 0 & e^{-i(\varphi_{i}+\varphi_{j})} \\ 0 & e^{-i(\varphi_{i}+\varphi_{j})} & ie^{-i(\varphi_{i}+\varphi_{j})} & 0 \\ 0 & e^{i(\varphi_{i}+\varphi_{j})} & -ie^{i(\varphi_{i}+\varphi_{j})} & 0 \\ e^{i(\varphi_{i}-\varphi_{j})} & 0 & 0 & -e^{i(\varphi_{i}-\varphi_{j})} \end{pmatrix} \begin{pmatrix} I \\ Q \\ U \\ V \end{pmatrix} \xrightarrow{\varphi_{i}=\varphi_{j}=\varphi} \begin{pmatrix} I+V & I \\ (Q+iU)e^{-i2\varphi_{j}} \\ (Q-iU)e^{i2\varphi_{j}} \\ I-V \end{pmatrix}$$

Circular Feeds: linear polarization in cross hands, circular in parallel-hands





Visibilities to Stokes on-sky: XY basis

we have

v^{XY}	$-\sin(\varphi_i - \varphi_j)$	$\sin(\varphi_i + \varphi_j)$		$i\cos(\varphi_i - \varphi_j)$	
v^{YX}	$-\sin(\varphi_i - \varphi_j)$	$\sin(\varphi_i + \varphi_j)$	$\cos(\varphi_i + \varphi_j)$	- $i\cos(\varphi_i - \varphi_j)$	U
v^{YY}	$\cos(\varphi_i - \varphi_j)$	- $\cos(\varphi_i + \varphi_j)$	- $\sin(\varphi_i + \varphi_j)$	$i\sin(\varphi_i - \varphi_j)$	$\left(V \right)$

- and for identical parallactic angles ϕ between antennas:



 $(I + Q\cos 2\varphi - U\sin 2\varphi)$ $Q\sin 2\varphi + U\cos 2\varphi + iV$ $Q\sin 2\varphi + U\cos 2\varphi - iV$ $I - Q\cos 2\varphi + U\sin 2\varphi$

Linear Feeds: linear polarization present in all hands

circular polarization only in cross-hands





Basic Interferometry equations

- An interferometer naturally measures the transform of the sky intensity in *uv*-space convolved with aperture
 - cross-correlation of aperture voltage patterns in uv-plane
 - its tranform on sky is the primary beam A with FWHM ~ λ /D
 - $V(\mathbf{u}) = \int d^2 \mathbf{x} A(\mathbf{x} \mathbf{x}_p) I(\mathbf{x}) e^{-2\pi i \mathbf{u} (\mathbf{x} \mathbf{x}_p)} + \mathbf{n}$ $= \int d^2 \mathbf{v} \widetilde{A}(\mathbf{u} \mathbf{v}) \widetilde{I}(\mathbf{v}) e^{2\pi i \mathbf{v} \cdot \mathbf{x}_p} + \mathbf{n}$
 - The "tilde" quantities are Fourier transforms, with convention: $\widetilde{T}(\mathbf{u}) = \int d^2 \mathbf{x} \, e^{-i2\pi \, \mathbf{u} \cdot \mathbf{x}} \, T(\mathbf{x}) \quad \mathbf{x} = (l, m) \leftrightarrow \mathbf{u} = (u, v)$ $T(\mathbf{x}) = \int d^2 \mathbf{u} \, e^{i2\pi \, \mathbf{u} \cdot \mathbf{x}} \, \widetilde{T}(\mathbf{u})$





Polarization Interferometry : Q & U

- , Parallel-hand & Cross-hand correlations (circular basis)
 - _ visibility *k* (antenna pair *ij*, time, pointing *x*, channel v, noise n):

 $V_{k}^{RR}(\mathbf{u}_{k}) = \int d^{2}\mathbf{v} \,\widetilde{A}_{k}^{RR}(\mathbf{u}_{k}-\mathbf{v})[\widetilde{I}_{v}(\mathbf{v})+\widetilde{V}_{v}(\mathbf{v})]e^{2\pi i\mathbf{v}\cdot\mathbf{x}_{k}} + \mathbf{n}_{k}^{RR}$ $V_{k}^{RL}(\mathbf{u}_{k}) = \int d^{2}\mathbf{v} \,\widetilde{A}_{k}^{RL}(\mathbf{u}_{k}-\mathbf{v})[\widetilde{Q}_{v}(\mathbf{v})+i\widetilde{U}_{v}(\mathbf{v})]e^{-i2\varphi_{k}}e^{2\pi i\mathbf{v}\cdot\mathbf{x}_{k}} + \mathbf{n}_{k}^{RL}$ $V_{k}^{LR}(\mathbf{u}_{k}) = \int d^{2}\mathbf{v} \,\widetilde{A}_{k}^{LR}(\mathbf{u}_{k}-\mathbf{v})[\widetilde{Q}_{v}(\mathbf{v})-i\widetilde{U}_{v}(\mathbf{v})]e^{i2\varphi_{k}}e^{2\pi i\mathbf{v}\cdot\mathbf{x}_{k}} + \mathbf{n}_{k}^{LR}$ $V_{k}^{LL}(\mathbf{u}_{k}) = \int d^{2}\mathbf{v} \,\widetilde{A}_{k}^{LR}(\mathbf{u}_{k}-\mathbf{v})[\widetilde{Q}_{v}(\mathbf{v})-i\widetilde{U}_{v}(\mathbf{v})]e^{i2\varphi_{k}}e^{2\pi i\mathbf{v}\cdot\mathbf{x}_{k}} + \mathbf{n}_{k}^{LR}$ $V_{k}^{LL}(\mathbf{u}_{k}) = \int d^{2}\mathbf{v} \,\widetilde{A}_{k}^{LR}(\mathbf{u}_{k}-\mathbf{v})[\widetilde{Q}_{v}(\mathbf{v})-i\widetilde{U}_{v}(\mathbf{v})]e^{i2\varphi_{k}}e^{2\pi i\mathbf{v}\cdot\mathbf{x}_{k}} + \mathbf{n}_{k}^{LR}$

• the phase of **P** is ϕ (the R-L phase difference)

$$\widetilde{P}(\mathbf{v}) = \widetilde{Q}(\mathbf{v}) + i\widetilde{U}(\mathbf{v}) = \left|\widetilde{P}(\mathbf{v})\right| e^{i2\phi(\mathbf{v})}$$





Example: RL basis imaging

- Parenthetical Note:
 - can make a pseudo-I image by gridding RR+LL on the Fourier half-plane and inverting to a real image
 - can make a pseudo-V image by gridding RR-LL on the Fourier half-plane and inverting to real image
 - can make a pseudo-(Q+iU) image by gridding RL to the full Fourier plane (with LR as the conjugate) and inverting to a complex image
 - does not require having full polarization RR,RL,LR,LL for every visibility (unlike calibration/correction of visibilities)
- More on imaging (& deconvolution) tomorrow!





Polarization Leakage, D

- Polarizer is not ideal, so orthogonal polarizations not perfectly isolated
 - Well-designed systems have d < 1-5% (but some systems >10% \otimes)
 - A geometric property of the antenna, feed & polarizer design
 - frequency dependent (e.g. quarter-wave at center v)
 - direction dependent (in beam) due to antenna
 - For R,L systems
 - parallel hands affected as d•Q + d•U, so only important at high dynamic range (because Q,U~d, typically)
 - cross-hands affected as d•l so almost always important

$$\mathbf{J}_{D}^{pq} = \begin{pmatrix} 1 & d^{p} \\ d^{q} & 1 \end{pmatrix} \qquad \text{Leakage of q into p}$$
(e.g. L into R)





Leakage revisited...

- Primary on-axis effect is "leakage" of one polarization into the measurement of the other (e.g. R ⇔ L)
 - but, direction dependence due to polarization beam!
- Customary to factor out on-axis leakage into D and put direction dependence in "beam"
 - example: expand RL basis with on-axis leakage

$$\hat{V}_{ij}^{RR} = V_{ij}^{RR} + d_i^R V_{ij}^{LR} + d_j^{*R} V_{ij}^{RL} + d_i^R d_j^{*R} V_{ij}^{LL}$$

$$\hat{V}_{ij}^{RL} = V_{ij}^{RL} + d_i^R V_{ij}^{LL} + d_j^{*L} V_{ij}^{RR} + d_i^R d_j^L V_{ij}^{LR}$$

- similarly for XY basis





Example: RL basis leakage

• In full detail:







Example: linearized leakage

• RL basis, keeping only terms linear in I,Q±iU,d:

 $V_{ij}^{RL} = (Q + iU)e^{-i(\varphi_i + \varphi_j)} + I(d_i^R e^{i(\varphi_i - \varphi_j)} + d_j^{*L} e^{-i(\varphi_i - \varphi_j)})$ $V_{ij}^{LR} = (Q - iU)e^{i(\varphi_i + \varphi_j)} - I(d_i^L e^{-i(\varphi_i - \varphi_j)} + d_j^{*R} e^{i(\varphi_i - \varphi_j)})$

• Likewise for XY basis, keeping linear in I,Q,U,V,d,sin(ϕ_i - ϕ_i)

 $V_{ij}^{XY} = Q\sin(\varphi_i + \varphi_j) + U\cos(\varphi_i + \varphi_j) + i V + [(d_i^X + d_j^{*Y})\cos(\varphi_i - \varphi_j) - \sin(\varphi_i - \varphi_j)]I$ $V_{ij}^{YX} = Q\sin(\varphi_i + \varphi_j) + U\cos(\varphi_i + \varphi_j) + i V + [(d_i^Y + d_j^{*X})\cos(\varphi_i - \varphi_j) + \sin(\varphi_i - \varphi_j)]I$

WARNING: Using linear order will limit dynamic range! (dropped terms have non-closing properties)





Ionospheric Faraday Rotation, F

• Birefringency due to magnetic field in ionospheric plasma

 $\cos\Delta\phi$ - $\sin\Delta\phi$ $\sin \Delta \phi \quad \cos \Delta \phi$ is direction-dependent $\Delta \varphi \approx 0.15^{\circ} \lambda^2 \int B_{\parallel} n_e ds$ $(\lambda \text{ in cm}, n_e ds \text{ in } 10^{14} \text{ cm}^{-2}, B_{\parallel} \text{ in G})$ $TEC = \int n_e ds \sim 10^{14} \,\mathrm{cm}^{-2}; \quad B_{\parallel} \sim 1\mathrm{G};$ $\lambda = 20 \text{cm} \rightarrow \Delta \phi \sim 60$



- also present in ISM, IGM and intrinsic to radio sources!
 - can come from different Faraday depths → tomography





Antenna voltage pattern, E

- Direction-dependent gain and polarization
 - includes primary beam
 - Fourier transform of cross-correlation of antenna voltage patterns
 - includes polarization asymmetry (squint)

$$\mathbf{J}_{E}^{pq} = \begin{pmatrix} e^{pp}(l',m') & e^{pq}(l',m') \\ e^{qp}(l',m') & e^{qq}(l',m') \end{pmatrix}$$

- includes off-axis cross-polarization (leakage)

- convenient to reserve D for on-axis leakage
- important in wide-field imaging and mosaicing
 - when sources fill the beam (e.g. low frequency)







Summary – polarization interferometry

- Choice of basis: CP or LP feeds
 - usually a technology consideration
- Follow the signal path
 - ionospheric Faraday rotation F at low frequency
 - direction dependent (and antenna dependent for long baselines)
 - parallactic angle P for coordinate transformation to Stokes
 - antennas can have differing PA (e.g. VLBI)
 - "leakage" D varies with ν and over beam (mix with E)
- Leakage
 - use full (all orders) D solver when possible
 - linear approximation OK for low dynamic range
 - beware when antennas have different parallactic angles





Polarization Calibration & Observation





So you want to make a polarization image...

- Making polarization images
 - follow general rules for imaging
 - image & deconvolve I, Q, U, V planes
 - Q, U, V will be positive and negative
 - V image can often be used as check (if no intrinsic V-pol)
- Polarization vector plots
 - EVPA calibrator to set angle (e.g. R-L phase difference)
 - Φ = ½ tan-1 U/Q for E vectors
 - B vectors ⊥ E
 - plot E vectors (length given by P)
- Leakage calibration is essential
- See Tutorials on Friday



e.g Jupiter 6cm continuum





Strategies for leakage calibration

- Need a bright calibrator! Effects are low level...
 - determine antenna gains independently (mostly from parallel hands)
 - use cross-hands (mostly) to determine leakage
 - however, cross-hand leakage insufficient to correct parallel-hands
 - do matrix solution to go beyond linear order
- Calibrator is unpolarized
 - leakage directly determined (ratio to I model), but only to an overall complex constant (additive over array)
 - need way to fix phase δ_p - δ_q (*ie.* R-L phase difference), e.g. using another calibrator with known EVPA
- Calibrator of known (non-zero) linear polarization
 - leakage can be directly determined (for I,Q,U,V model)
 - for a single scan only within an overall offset (e.g. sum of D-terms)
 - unknown *p*-*q* phase can be determined (from U/Q etc.)





Other strategies

- Calibrator of unknown polarization
 - solve for model IQUV and D simultaneously or iteratively
 - need good parallactic angle coverage to modulate sky and instrumental signals
 - in instrument basis, sky signal modulated by e^{i2χ}
- With a very bright strongly polarized calibrator
 - can solve for leakages and polarization per baseline
 - can solve for leakages using parallel hands!
- With no calibrator
 - hope it averages down over parallactic angle
 - transfer D from a similar observation
 - usually possible for several days, better than nothing!
 - need observations at same frequency





Parallactic Angle Coverage at VLA

- fastest PA swing for source passing through zenith
 - to get good PA coverage in a few hours, need calibrators between declination +20° and +60°







Finding polarization calibrators

- Standard sources
 - planets (unpolarized if unresolved)
 - 3C286, 3C48, 3C147 (known IQU, stable)
 - sources monitored (e.g. by VLA)
 - other bright sources (bootstrap)

http://www.vla.nrao.edu/astro/calib/polar/

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	2136+00	6 B	20031219	10.129 ± 0.021	10124.86 ± 13.68	102.56 ± 1.52	1.01 ± 0.02	-161.12 ± 2.38	20031219	8.791 ±		
	2136+00	6 MEAN	all	10.122 ± 0.113	10120.24 ± 112.97	119.32 ± 11.78	1.18 ± 0.12	-155.36 ± 5.36	all	8.747 ±		
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lews:	2202+42	z D	20030308	2.044 ± 0.002	2042.52 ± 1.27	117.19 ± 0.10	5.74 ± 0.00	-21.31 ± 1.22	20030308	0.000 ±		
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broken	2202+42	2 A	20030527	2.016 ± 0.003	2015.67 ± 0.18	97.05 ± 0.99	4.81 ± 0.05	-22.52 ± 0.01	20030527	2.062 ±		
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ule <u>Ga</u>	2202+42	z A	20030630	2.081 ± 0.003	2080.76 ± 0.05	94.24 ± 0.67	4.53 ± 0.03	-17.84 ± 0.60	20030630	2.362 ±		
 A list o not ava 	2202+42	2 A	20030707	2.101 ± 0.007	2100.35 ± 1.64	104.18 ± 0.61	4.96 ± 0.03	-18.78 ± 1.30	20030707	2.291 ±		
 Models 	2202+42	2 A	20030809	2.381 ± 0.002	2380.58 ± 2.59	97.25 ± 0.14	4.09 ± 0.01	-0.64 ± 2.18	20030809	2.750 ±		
and 3C details.	2202+42	2 A	20030821	2.401 ± 0.004	2400.15 ± 0.32	94.36 ± 0.14	3.93 ± 0.01	-6.39 ± 0.90	20030821	2.860 ±		
2	2202+42	2 A	20030905	2.341 ± 0.007	2340.07 ± 4.48	85.74 ± 0.02	3.66 ± 0.01	-0.42 ± 1.56	20030905	2.873 ±		
A reco	2202+42	z A	20030914	2.536 ± 0.006	2534.40 ± 2.73	89.88 ± 0.71	3.55 ± 0.02	-13.02 ± 0.94	20030914	2.792 ±		
	2202+42	z B	20031102	2.450 ± 0.002	2448.52 ± 3.37	83.19 ± 0.01	3.40 ± 0.00	-9.12 ± 0.39	20031102	2.645 ±		
	2202+42	2 В	20031117	2.288 ± 0.003	2286.56 ± 0.36	97.28 ± 0.44	4.25 ± 0.02	-18.17 ± 1.44	20031117	2.397 ±		
	2202+42	2 В	20031205	2.514 ± 0.004	2512.90 ± 2.89	109.69 ± 0.26	4.37 ± 0.02	-15.73 ± 0.11	20031205	2.814 ±		
	2202+42	z B	20031219	2.478 ± 0.004	2474.81 ± 0.29	127.94 ± 0.12	5.17 ± 0.01	-13.50 ± 0.20	20031219	2.707 ±		
	2202+42	2 MEAN	all	2.269 ± 0.184	2268.19 ± 183.41	101.30 ± 12.93	4.50 ± 0.68	-13.90 ± 6.65	all	2.498 ±		
					225	3+161 C BAND						
	2253+16	1 D	20030206	12.154 ± 0.012	12148.38 ± 31.90	488.79 ± 2.39	4.02 ± 0.01	2.54 ± 0.74	20030206	10.751 ±		
	2253+16	1 D	20030308	11.728 ± 0.013	11721.95 ± 14.16	455.86 ± 4.99	3.89 ± 0.05	3.21 ± 2.32	20030308	0.000 ±		
	2253+16	1 D	20030419	11.677 ± 0.023	11669.28 ± 34.96	449.99 ± 4.89	3.86 ± 0.05	-3.47 ± 1.59	20030419	10.921 ±		
	2253+16	1 A	20030527	11.240 ± 0.025	11220.39 ± 19.04	434.76 ± 2.30	3.87 ± 0.03	4.45 ± 0.24	20030527	10.120 ±		
	2253+16	1 4	20030609	11 124 + 0.031	1111479 + 12 18	461.61 + 1.77	415 + 0.02	7.68 ± 0.49	20030609	10 119 +		
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Example: VLA D-term calibration

• D-term calibration effect on RL visibilities (should be Q+iU):







Example: VLA D-term calibration

• D-term calibration effect in Q image plane :

Bad D-term solution



Good D-term solution









Example: EVLA D-term calibration

- C-band D-term calibration as a function of frequency (OSRO-1 mode):
 - frequency-dependent effects over wide bands, beware of cross-hand delays



D table: test2_TOSR0005_sb1216761_1.55269.279088587966.pcal1







Example: EVLA D-term calibration

• C-band D-term calibration as a function of antenna (OSRO-1 mode):











Example: EVLA EVPA calibration

- C-band R-L phase as a function of frequency (OSRO-1 mode):
 - solve for single-phase and cross-hand delay over array



Summary – Observing & Calibration

- Follow normal calibration procedure (see next lecture)
- Need bright calibrator for leakage D calibration
 - bright calibrator with known polarization
 - unpolarized (or very low polarization) sources see only leakage
- Parallactic angle coverage useful
 - necessary for unknown calibrator polarization
- Need to determine unknown *p-q* phase
 - CP feeds need EVPA calibrator (known strong Q,U) for R-L phase
 - if system stable, can transfer from other observations
- Upshot build polarization calibration into schedule
 - if you need PA coverage, will be observing near zenith
 - watch antenna wraps (particularly in dynamic scheduling)!





Special Considerations – EVLA & ALMA

- Wideband calibration issues
 - D-term and p-q phase corrections as function of frequency
 - need bright source to solve on per-channel basis
- Delay issues
 - parallel-hand delays taken out in bandpass
 - need to remove cross-hand delays in or before Pol calibration
- High-dynamic range issues
 - D-term contribution to parallel-hand correlations (non-closing)
 - wide-field polarization imaging/calibration algorithm development
 - direction-dependent voltage beam patterns needed
- Special issues
 - EVLA circular feeds: observing V difficult
 - ALMA linear feeds: gain calibration interaction



