





Why Interferometry?

resolution, resolution! maximum angular extent of some bodies:

Sun & Moon - 0.5° Venus - 60" Jupiter - 50" Mars - 25" Saturn - 20" Mercury - 12" Uranus - 4" Neptune - 2.4" Galilean Satellites - 1-2" Titan - 1" Triton - 0.1" Pluto - 0.1" MBA - .05 - .5" NEA, KBO - 0.005 - 0.05"

(interferometry also helps with confusion!)

A Bit of History

interferometrically, with the "sea cliff interferometer" in Australia (McCready, Pawsey, and Payne-Scott 1947).





What's the Big Deal?

Radio interferometric observations of solar system bodies are similar in many ways to other observations, including the data collection, calibration, reduction, etc...

So why am I here talking to you? In fact, there are some differences which are significant (and serve to illustrate some fundamentals of interferometry).

Differences

- Object motion
- Time variability
- Confusion
- \blacksquare Scheduling complexities
- \blacksquare Source strength
- Coherence
- Source distance
- Knowledge of source
- Optical depth

Object Motion

All solar system bodies move against the (relatively fixed) background sources on the celestial sphere. This motion has two components:

- •"Horizontal Parallax" caused by rotation of the observatory around the Earth.
- •"Orbital Motions" caused by motion of the Earth and the observed body around the Sun.





Time Variability

Time variability is a significant problem in solar system observations:

■ Sun - very fast fluctuations (< 1 sec)

Others - rotation (hours to days)

Distance may change appreciably (need "common" distance measurements)

These must be dealt with.

Time Variability - an example

snapshots made every 10 mins

Mars radar

Butler, Muhleman & Slade 1994



Implications

- Can't use same calibrators
- \blacksquare Can't add together data from different days
- Solar confusion
- \blacksquare Other confusion sources move in the beam
- Antenna and phase center pointing must be tracked (must have accurate ephemeris)
- Scheduling/planning need a good match of source apparent size and interferometer spacings

Source Strength

Some solar system bodies are very bright. They can be so bright that they raise the antenna temperature:

- Sun ~ 6000 K (or brighter)
- Moon ~ 200 K
- Venus, Jupiter ~ 1-100's of K

In the case of the Sun, special hardware may be required. In other cases, special processing may be needed (e.g., Van Vleck correction). In all cases, system temperature is increased.

Coherence

Some types of emission from the Sun are coherent. In addition, reflection from planetary bodies in radar experiments is coherent (over at least part of the image). This complicates greatly the interpretation of images made of these phenomena.

Source Distance - Wave Curvature

Objects which are very close to the Earth may be in the near-field of the interferometer. In this case, there is the additional complexity that the received e-m radiation cannot be assumed to be a plane wave. Because of this, an additional phase term in the relationship between the visibility and sky brightness - due to the curvature of the incoming wave - becomes significant. This phase term must be accounted for at some stage in the analysis.



Short Spacing Problem

As with other large, bright objects, there is usually a serious short spacing problem when observing the planets. This can produce a large negative "bowl" in images if care is not taken. This can usually be avoided with careful planning, and the use of appropriate models during imaging and deconvolution.

Source Knowledge

There **is** an advantage in most solar system observations - we have a very good idea of what the general source characteristics are, including general expected flux densities and extent of emission. This can be used to great advantage in the imaging, deconvolution, and self-calibration stages of data reduction.



3-D Reconstructions, more...

Developed by Bob Sault (ATNF) - see Sault et al. 1997; Leblanc et al. 1997; de Pater & Sault 1998



Lack of Source Knowledge

If the true source position is not where the phase center of the instrument was pointed, then a phase error is induced in the visibilities.

If you don't think that you knew the positions beforehand, then the phases can be "fixed". If you think you knew the positions beforehand, then the phases may be used to derive an offset.

Optical Depth

With the exception of comets, the upper parts of atmospheres, and Jupiter's synchrotron emission, all solar system bodies are optically thick. For solid surfaces, the "e-folding" depth is ~ 10 wavelengths. For atmospheres, a rough rule of thumb is that cm wavelengths probe down to depths of a few to a few 10's of bars, and mm wavelengths probe down to a few to a few hundred mbar. The desired science drives the choice of wavelength.

Conversion to TB

The meaningful unit of measurement for solar system observations is Kelvin. Since we usually roughly know distances and sizes, we can turn measured Janskys (or Janskys/beam) into brightness temperature:

unresolved:
$$T_B^d = V_o \frac{\lambda^2}{2k_B} \frac{D^2}{\pi R^2} + T_{CME}$$

resolved:
$$T_B^d(l,m) = F(l,m) \frac{\lambda^2}{2k_B} \frac{4\ln 2}{\pi B^2} + T_{CMB}$$

Conversion of coordinates

If we know the observed object's geometry well enough, then sky coordinates can be turned into planetographic surface coordinates - which is what we want for comparison, e.g., to optical images.





Real Data - what to expect
If the sky brightness is circularly symmetric, then the 2-D Fourier
relationship between sky brightness and visibility reduces to a 1-
D Hankel transform:

$$V(q) = 2\pi \int_{0}^{R} A(r) I(r) J_{0}(2\pi rq) rdr$$

For a "uniform disk", this reduces to:
 $V(\beta) = I_{0}\pi R^{2} \frac{J_{1}(2\pi\beta)}{\pi\beta}$
and for a "limb-darkened disk", this reduces to:
 $V(\beta) = I_{0}\pi R^{2} \Lambda_{c}(2\pi\beta)$













